

Programmable Controllers MELSEC-Q series [QnU] for a greener tomorrow



e-Factory

## Reaching higher, to the summit of the Q Series



## GLOBAL IMPACT OF MITSUBISHI ELECTRIC



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

#### Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

1

Mitsubishi Electric is involved in many areas including the following

#### **Energy and Electric Systems**

A wide range of power and electrical products from generators to large-scale displays.

#### **Electronic Devices**

A wide portfolio of cutting-edge semiconductor devices for systems and products.

#### **Home Appliance**

Dependable consumer products like air conditioners and home entertainment systems.

#### Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

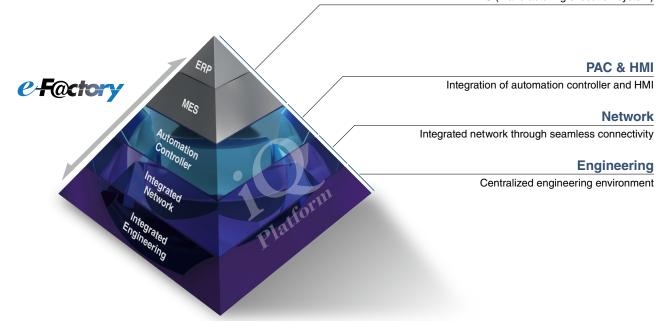
#### **Industrial Automation Systems**

Maximizing productivity and efficiency with cutting-edge automation technology.

## iQ Platform for maximum return on investment

Minimize TCO, Seamless integration, Maximize productivity, Transparent communications: these are common items that highlight the benefits of the iQ Platform and e-F@ctory. The iQ Platform minimizes TCO at all phases of the automation life cycle by improving development times, enhancing productivity, reducing maintenance costs, and making information more easily accessible across the plant. Together with e-F@ctory, offering various best-in-class solutions through its e-F@ctory alliance program, the capabilities of the manufacturing enterprise is enhanced even further realizing the next level for future intelligent manufacturing plants.

ERP (Enterprise resource planning) MES (Manufacturing execution system)



## Further reduce TCO while securing your manufacturing assets

#### **Automation Controller**

Improve productivity and product quality

- 1. High-speed system bus realizing improved system performance
- 2. On-screen multi-touch control enabling smooth GOT (HMI) operations

#### **Integrated Network**

Best-in-class integrated network optimizing production capabilities

- 1. CC-Link IE supporting 1 Gbps high-speed communication
- 2. Seamless connectivity within all levels of manufacturing with SLMP

#### **Centralized Engineering**

Integrated engineering environment with system level features

- 1. Automatic generation of system configuration
- 2. Share parameters across multiple engineering software via MELSOFT Navigator
- 3. Changes to system labels are reflected between PAC and HMI



Performance on a different level brought to you with the Programmable Controller

# Continuously evolving Universal Model

Current production requirements are calling for an increase in productivity and carrying out production processes even faster due to an increase in production information such as production results and traceability. The MELSEC-Q Series programmable controller "Universal model QnU" is a leader for these market needs. High-speed basic instruction processing on a micro scale dramatically increases your system and machine performance.

Inheriting the high robust and ease of use design of the Q Series, the MELSEC QnU programmable controller will open up new possibilities in automation solutions.





A PUL

A MIESU



#### Customer experiences created this programmable controller

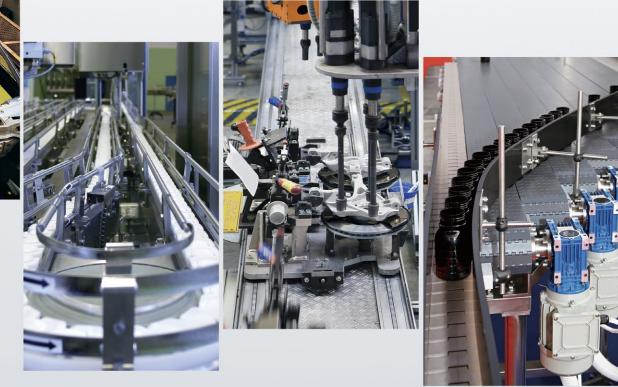
Support for shorter operation cycle times
 Support for higher quality control requirements
 Complex and large-scale equipment and systems
 Expanding control and production control data
 Shorter product cycles
 Support for higher equipment operation rates

#### INDEX

QnU CPU P.5	Module Lineup P.37
Improved Productivity ······P.7	Software P.49
More User-Friendly ····· P.11	Related Products P.59
• Easy Maintenance ······ P.17	Specifications P.64
CPU Lineup P.19	Support P.72
Network P.23	Product List P.75



## **Reaching higher**, to the summit of the Q Series



■ MELSEC-Q Series Universal model lineup

Program capacity (step) LISB : High-speed Universal model QCPU 1000K Q100UDEH : Built-in Ethernet port QCPU SD 500K : Built-in RS-232 port CPU Q50UDEH Q26UDEH 260K Q26UDVCPL Q26UDH USB Q20UDEH RS-232 200K Q20UDH Dedicated Q13UDEH Q13UDVCPU 130K Q13UDH Q10U 100K Q10UDH USB Q06UDEH Q06UDH 60K Q06UDVCPU RS-232 USB Dedica RS-232 40K Q04UDVCPU Q04UDH Q03UD Q03UDVCPU 30K 20K Q02U Power supply and base unit (5 slots) integrated type USB 15K Q01U 10K Q00UJ Q00U Basic operation processing speed (ns) 120 80 60 40 20 9.5 1.9

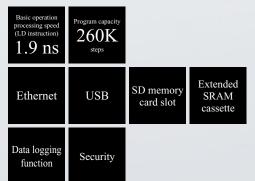
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# Melsec Q<sub>series</sub>



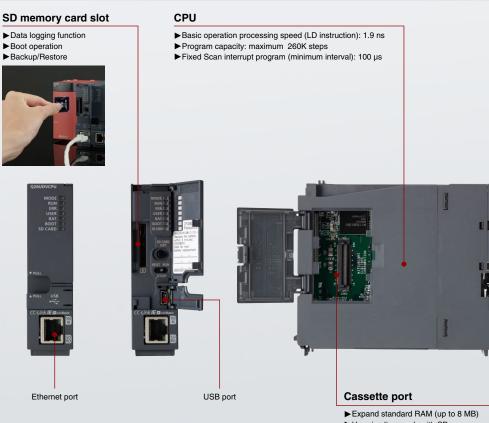
#### High-speed Universal model QCPU

Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV



 $^{\star}\!:$  This CPU type is only supported by GX Works2 (not supported by GX Developer).

#### High-speed Universal model QCPU



#### Enhanced security functions Maximum of 32 character password is

supported. A mix of alphanumeric and special characters (\*, @, and & etc.) can be used further strengthening the security of the password. In addition, protection of intellectual property can be enhanced by blocking any unauthorized devices and only allowing registered devices to access the CPU.



Expand standard RAM (up to 8 MB)
 Use simultaneously with SD memory card
 Continuously access file registers



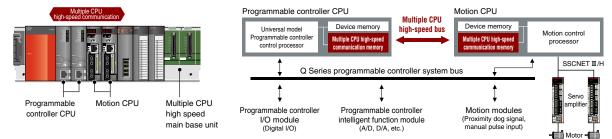
## **Improved Productivity**



#### ■ High-speed, high-accuracy machine control

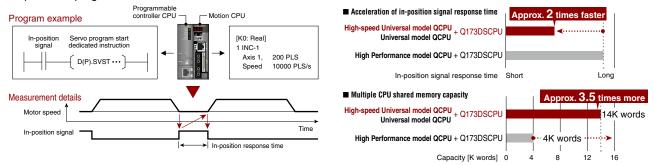
To achieve high-speed synchronized control between multiple CPUs, a dedicated bus is used, independent of sequence program operation. (0.88 ms operation cycle)<sup>\*1</sup>

This multiple CPU high-speed communication is synchronized with motion control to maximize efficiency. Additionally, the performance of the motion control CPU is twice as fast as the previous model, ensuring high-speed, high-accuracy machine control.



In-position response time

Fast in-position response time is realized between the motion CPU and programmable controller. The in-position signal is triggered by the servo amplifier of the first axis, with the time taken between the second axis at start-up and the speed command output of the programmable controller CPU.



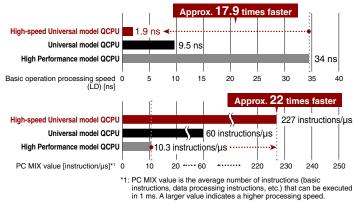
\*1: Q00UJ, Q00U, Q01U and Q02U are not supported.

# MELSEG eseries

#### ■ Improved production time with ultra-high-speed processing Improved performance!

As applications are getting larger and more complex it is essential to shorten the system operation cycle time. To achieve this, the ultra high-speed of 1.9 ns (LD instruction) processing enables to realize shorter operating cycles.

System performance can be improved by reducing the overall scan time, preventing any variances in performance. In addition to realization of highspeed control which is normally associated with microcomputer control.



High-speed, high-precision data processing Improved performance!

The floating point addition processing speed has been increased to  $0.014 \ \mu s$  to support high-speed, high-precision operation processing. Also, double-precision floating-point operation instruction is included to simplify programming and reduce calculation errors when implementing complex equations.

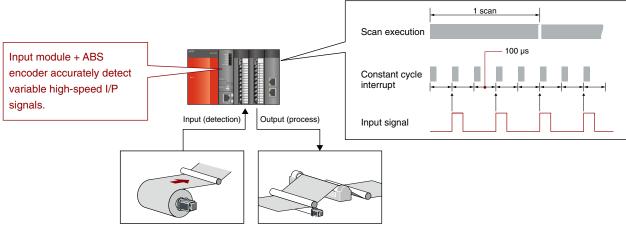
	Approx. 55.7 time	es faster	
High-speed Universal model QCPU	4 µs	••••••••••	
Universal model QCPU	057 µs		
High Performance model QCPU		0.78 µs	
Floating point addition (single precision) 0 0 instruction processing speed [µs]	.1 0.2 0.3 0.4 0.5	0.6 0.7 0.8 0.9	
	Additio	on (E+)	
CPU	Single precision [µs]*2	Double precision [µs]*2	
High-speed Universal model QCPU	0.014	1.8	
Universal model QCPU	0.057	4.3	
High Performance model QCPU	0.78	87*3	

\*2: Minimum value \*3: Indicates internal double-precision operation processing speed.

#### Shorter fixed scan interrupt time realizing higher system accuracy Improved performance!

Reduced minimal fixed scan interrupt program time to 100  $\mu s^{\star 4}.$  High-speed I/O signals resulting in high-accuracy control system.

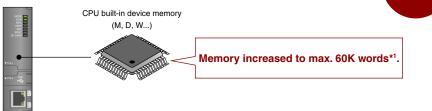
Example: High-speed position detection of film paper feed system



\*4: Only supported by High-speed Universal model QCPU.

#### Improved basic functions Improved performance!

The CPU's built-in device memory capacity has been increased to a max. of 60K words\*1. Support increasing control and quality data with high-speed processing.



\*1: Only for Q13UDVCPU and Q26UDVCPU.

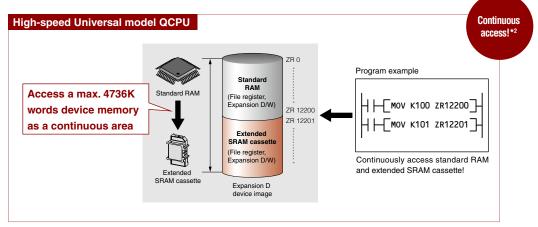
Increased capacity!

#### Large data volume at high-speed Improved performance!

Conventionally, continuous access to the standard RAM and SRAM card's file register area could not be achieved which had to be reflected in the user program.

When an 8 MB extended SRAM cassette is installed in the High-speed Universal model QCPU, the standard RAM can be as one continuous file register with up to 4736K words capacity, simplifying the user program.

Even if the device memory is insufficient, the file register area can be expanded easily by installing the extended SRAM cassette.



\*2: Only supported by High-speed Universal model QCPU.

◎File register capacity <sup>*3</sup>					
Model	Q03UDV	Q04UDV	Q06UDV	Q13UDV	Q26UDV
Extended SRAM cassette not installed (Standard RAM capacity)	96K words (192 KB)	128K words (256 KB)	384K words (768 KB)	512K words (1024 KB)	640K words (1280 KB)
with Q4MCA-1MBS (1 MB)*4	608K words	640K words	896K words	1024K words	1152K words
with Q4MCA-2MBS (2 MB)*4	1120K words	1152K words	1408K words	1536K words	1664K words
with Q4MCA-4MBS (4 MB)*4	2144K words	2176K words	2432K words	2560K words	2688K words
with Q4MCA-8MBS (8 MB)*4	4192K words	4224K words	4480K words	4608K words	4736K words

\*3: Maximum capacity when using extended SRAM cassette file as a file register. Total when CPU's standard RAM and extended SRAM cassette are installed. \*4: Only High-speed Universal model QCPU.

The index register has been extended to 32 bits to allow programming beyond the conventional 32K words and to enable use of the entire file register area.

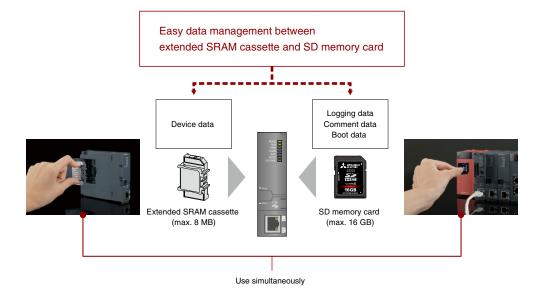
The processing speed for indexing, which is essential for efficient operation of structured (array) data, has been increased. The scan time can be shortened when indexing is used in repetitive programs, such as FOR to NEXT instructions.





#### SD memory card Improved functionality!

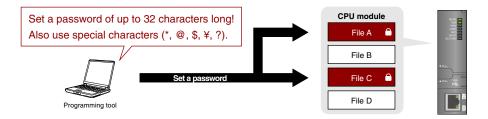
SD memory card is supported by High-speed Universal model QCPU allowing easy data exchange with a personal computer. The SD memory card and extended SRAM cassette can be used at the same time allowing extension of file registers (with extended SRAM cassette), data file logging, boot data, and storing of large comment data (SD memory card).



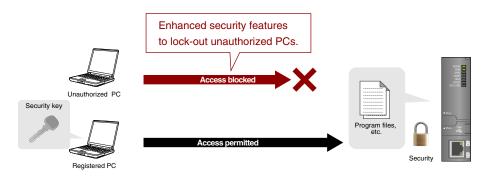
#### Protect important data with enhanced security Improved functionality!

A max. 32-character file password can be set\*1.

Special characters (\*, @, &, etc.) can be used in addition to alphanumeric characters making it harder to compromise the password.



Also protection of valuable intellectual property can be enhanced by only allowing preregistered devices to access the CPU, blocking out unauthorized users\*<sup>2</sup>.



\*1: Only supported by High-speed Universal model QCPU. Other models use 4 character password system. \*2: Only supported by High-speed Universal model QCPU.



## More User-Friendly

Data logging function Improved functionality!

Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV

#### Display collected data on PC or GOT (HMI)



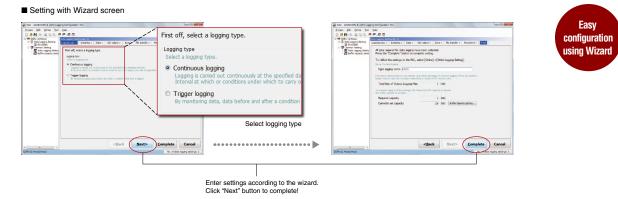
Logging data display and analysis tool GX LogViewer



GOT log viewer function

#### Easy logging without a program

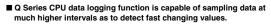
Save collected data in CSV format on a SD memory card just by completing easy settings with the dedicated setting tool wizard. Various reference materials including daily reports, form creation and general reports can be created easily within the saved CSV file. This data can be used for a wide variety of applications requiring traceability, production data, etc.

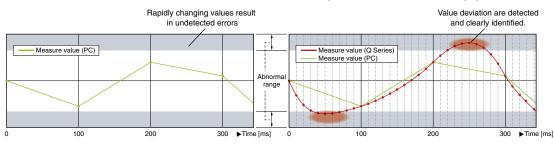


#### Logging of control data variances

Data is collected during each scan or within millisecond intervals allowing detection of control deviation even at very high speeds. Therefore, identification of errors can be conducted faster and in more detail.

■ Generic sample data from a PC or external device at 100 ms intervals

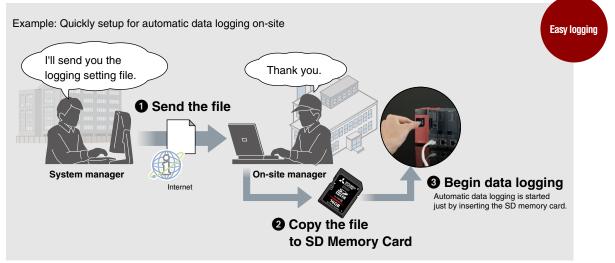






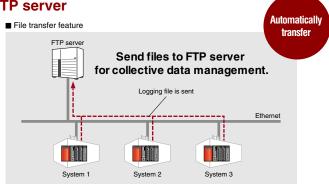
#### Automatic logging just by using a SD memory card

Automatic data logging realized just by inserting the SD memory card into the CPU, which is achieved as the memory card includes the logging configuration file. Instructing data logging remotely is also realized just by sending the configuration file by e-mail and copying onto the SD memory card.



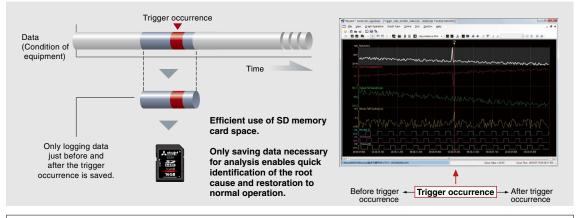
#### ■ Automatically send logging files to FTP server

Data logging files stored on the SD memory card can be sent to FTP server just by making a simple setting with the Logging configuration tool. As the logging server can handle multiple files, management and maintenance tasks can be reduced.



#### Quick troubleshooting response

Error causes and solutions can be quickly done as only the required data related to the problem is extracted, without having to spend time on filtering large volumes of diagnostic data.



#### "GX LogViewer\*1" and "Logging configuration tool\*2" available for free

To obtain a copy of GX LogViewer and Logging configuration tool, please contact your local Mitsubishi Electric representative.

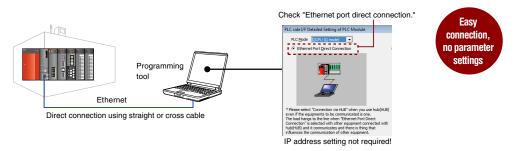
\*1: Refer to page 57 for details on GX LogViewer. \*2: The logging configuration tool is enclosed with GX Works2.

#### CPU modules with Built-in Ethernet Port

Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV Q03UDE, Q04UDEH, Q06UDEH, Q10UDEH, Q13UDEH, Q20UDEH, Q26UDEH, Q50UDEH, Q100UDEH

#### Easily connect to CPUs via Ethernet

IP address settings are not required to connect to CPU modules directly (one-to-one connection) using GX Works2 or GX Developer. Both straight and cross cables can be used, and are automatically identified by the CPU module. Therefore this connection method is as easy as using USB. Even operators who are not familiar with network settings can easily establish a connection.



#### CC-Link IE Field Network Basic does not require network module

#### Improved functionality!

Programmable controller CPUs with an embedded Ethernet port can be used as a master station<sup>\*1</sup>, eliminating the need for an additional network module. The network can be configured with a minimum number of modules reducing space and hardware cost.



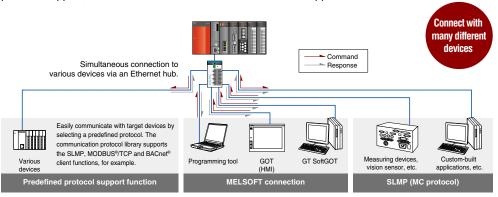
\*1: Only supported by High-speed Universal model QCPU.

\*2: SLMP:Seamless Message Protocol \*3: For further details regarding this product, please directly contact 'CKD Corporation', details can be found on their website at

http://www.ckd.co.jp/english/glblinfo/global/

#### ■ Easily connect to BACnet<sup>®</sup> and MODBUS<sup>®</sup>/TCP Improved functionality!

Ethernet realizes a high-speed connection, such as communication with external devices. By using predefined protocol support function<sup>\*4</sup>, various devices that require open network protocol support, such as BACnet<sup>®</sup> and MODBUS<sup>®</sup>/TCP are supported.

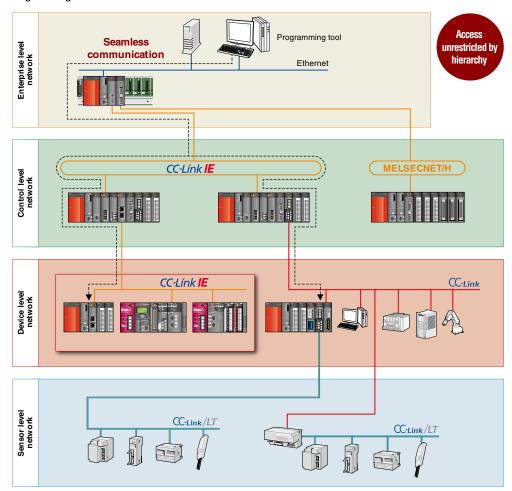


\*4: Only supported by High-speed Universal model QCPU



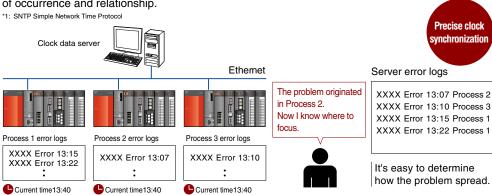
#### Seamless communication across all layers

The Universal model QCPUs support a multitude of networking technologies including the highspeed, high-capacity CC-Link IE Control Network and CC-Link IE Field Network. Along with MELSECNET/H, Ethernet, and CC-Link, these networks may be accessed seamlessly beyond network type or hierarchy. Each programmable controller on the network can be accessed for programming and maintenance duties by using a personal computer with the appropriate engineering tools connected via Ethernet.



#### Accurate clock data

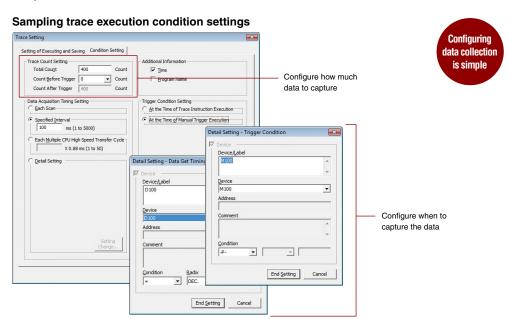
The CPU module's clock is automatically corrected with the SNTP\*1 clock synchronization function. When CPU clock data is reliably synchronized between systems, any time-stamped events or errors that involve more than one CPU can be easily understood in terms of their order of occurrence and relationship.



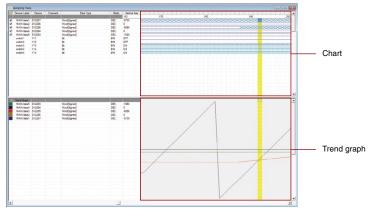
#### Save valuable time using the sampling trace function\*1

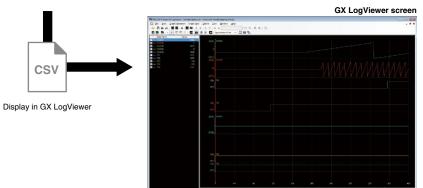
The sampling trace function is a useful diagnostic tool for analyzing error data, and sequence of events for program debug, etc. It can help reduce the overall time required for startup and commissioning of equipment.

In the multiple CPU configuration it can help to determine the timing and transfer of data between CPU modules. Collected data can be easily analyzed within the programming software tool with differences in word device and bit device values conveniently shown in chart and graph form. In addition, the results from sampling trace can be exported to GX LogViewer CSV file format for analysis within the software.



#### Sampling Trace window: example results



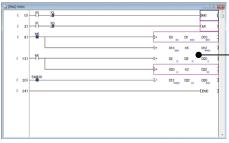


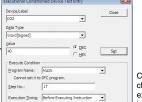
\*1: Not supported by Q00UJ.

# Melsec a series

#### Simplify the debugging process

Universal model CPUs have the ability to use the "Executional conditioned device test" function, which automatically sets device values to user specified values at any step during program simulation. Traditionally, to simulate real I/O or other device value change, a separate program would need to be written to perform debugging. By using the "Executional conditioned device test" function, it is possible to debug even small portions of simple ladder programs without the need to modify the program or add rungs of ladder. Therefore, debugging can be completed faster and easier.

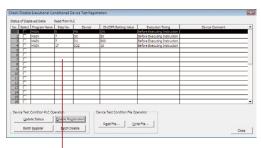






Configure the device setting by choosing the step No. and execution timing (before/after instruction execution).

Devices that have been added to the executional conditioned device test are highlighted by a pink box for easy identification.



A list of all devices being controlled by the function is automatically generated and can be saved and recalled for further debugging at a later time.

#### Improved flexibility of device point assignment

#### Extended range of bit devices

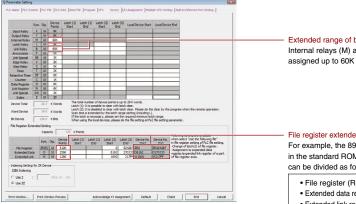
Bit devices, internal relay (M) and link relay (B), can now be assigned up to 60K points each. Previous models are limited to 32K points.

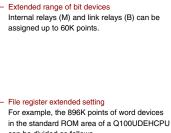
The total number of device points remains the same, however greater flexibility of device utilization and programming is achieved.



#### File register extended setting: data registers and link registers\*1

The number of Data Register (D) and Link Register (W) device points of can be extended using standard ROM or a memory card. Previous models only allow the extension of File Register (R/ZR) device points. Using this setting, it is easy to create more data or link registers to accommodate program changes, etc.





in the standard ROM area of a Q100UDEHCP can be divided as follows. • File register (R): 512K points

Extended data register (D): 256K points

Extended link register (W): 128K points

\*1: Not supported by Q00UJ.

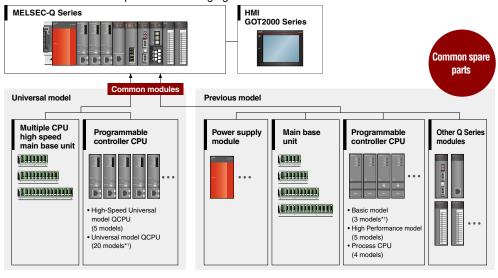
## **Easy Maintenance**



#### Fully compatible with standard Q Series

#### Use existing Q Series modules

Conventional Q Series modules are compatible with the Universal model QCPU Series. Therefore, when requiring an upgrade, system maintenance costs of existing systems can be kept to a minimum with little disruption when changing over.



\*1: The Q00UJCPU and Q00JCPU are all-in-one type, with integrated power supply, 5-slot base unit, and CPU.

#### Use existing Q Series programs

Conventional QCPU programs can be used just by changing the PLC type<sup>\*2</sup> within the programming tool, which enables easy upgrade to the Universal model Series with little reengineering required.

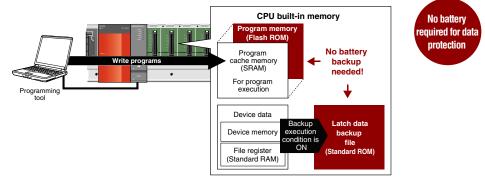


\*2: Depending on the program, the number of steps may vary when the PLC type is changed.



#### Automatically backup critical data

Programs and parameter files are automatically backed up to the program memory (Flash ROM) which does not require battery backup. This prevents loss of program and parameter data owing to failure in battery replacement. Also, back-up of important data such as device data can be registered to the standard ROM in order to prevent data loss due to a flat battery in case of planned outage during consecutive holidays. The backup data is restored automatically when the power is restored.

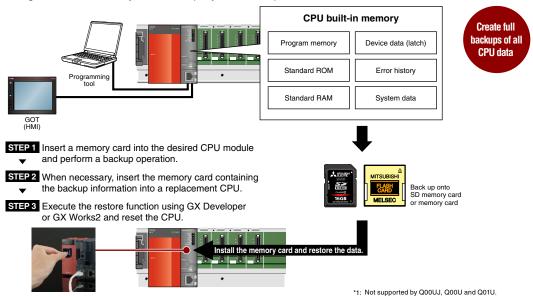


#### Shorten system down recovery time

#### CPU module change function\*1

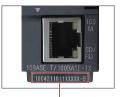
The CPU module change function allows the user to create a comprehensive backup of all CPU information to a memory card. In the unlikely event of a CPU failure or other catastrophic event, the backup data can be used to quickly program a new CPU module.

Using this function, the system can rapidly be made operational and downtime can be minimized.

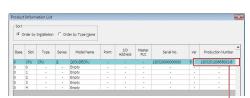


#### Serial numbers are now printed on the front of modules

Serial numbers can be checked quickly without having to remove them from the base unit (No interruption of operation is necessary). Also, serial numbers may be checked using the "product information list" feature included in GX Developer and GX Works2.



 Serial numbers are located on the bottom front of modules



The serial numbers of connected modules appear in the Product Information List and can be exported in CSV format.





## The iQ Platform incorporates many different CPU types to integrate multiple control disciplines

CPU Lineup

The MELSEC-Q Series offers programmable controller, process, redundant, C language, motion, robot and CNC CPUs to cover various different control requirements. With the multiple CPU configuration, a best-fit control system can be realized. In addition, high availability systems can be easily realized with the high-reliability redundant system range.

## **MELSEC** PROCESS

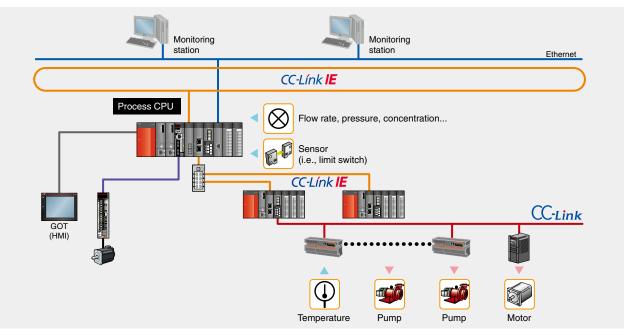
MELSEC process control is a flexible, highly reliable platform with advanced functionality designed to cost-effectively meet the needs of a wide range of industries.

#### Realize detailed instrument control to match the process state

#### • Process CPU...... Q02PHCPU, Q06PHCPU, Q12PHCPU, Q25PHCPU

Q Series process controllers offer features that rival those of costly DCS systems at a fraction of the cost. A single CPU can control a large number of PID loops while simultaneously performing standard sequence control. The process CPUs are complemented by a range of channel isolated high resolution analog I/O modules with online change (hot-swap) capability, and the function block programming and engineering software environment, PX Developer. In addition, PX Developer now supports GX Works2 programming software. With this connection between the two software, both sequence control and loop control programs can be used in the process CPU.





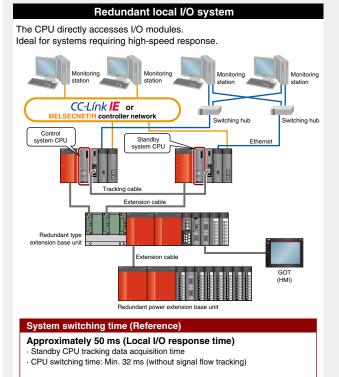
#### Redundancy to improve your system reliability

#### 

The redundant systems are designed to provide the users with systems that have the properties of Q Series and are not affected by sudden failures. The basic system including CPU module, power supply module, main base unit and network module is redundant to prevent system down. Programming can be performed without consciousness of redundancy.

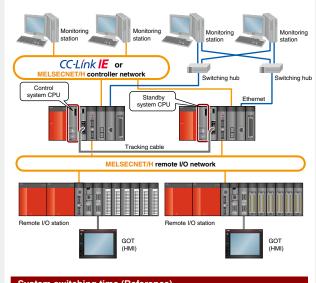
In addition, PX Developer now supports GX Works2 programming software. With this connection between the two software, both sequence control and loop control programs can be used in the process CPU.





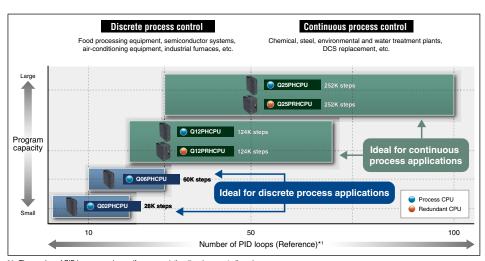
#### Redundant remote I/O system

Ideal for distributed systems with multiple remote I/O stations.



#### System switching time (Reference)

- Approximately 800 ms (Remote I/O response time)
- · Standby CPU tracking data acquisition time
- Output holding time of remote I/O station during control system switching: 700 to 800 ms • CPU switching time: Min. 21 ms (without signal flow tracking)





For further details, please refer to the "MELSEC PROCESS CONTROL/ REDUNDANT SYSTEM" catalog.

\*1: The number of PID loops may change if programs (other than loop control) are large. Refer to the PX Developer Version 1 Programming Manual or Process Technical Guide for details.

#### New possibilities for pre-installed systems connected from the C Controller

## • C Controller CPU-Wath Q24DHCCPU-V, Q24DHCCPU-VG\*1, Q24DHCCPU-LS, Q26DHCCPU-LS, Q12DCCPU-V

The C Controller is a generic open platform controller that can execute C language type programs, based on the MELSEC system architecture. It utilizes industrial performance such as long term parts supply, high availability, and advanced functionality. The high-end model Q24DHCCPU-V/-VG comes pre-installed with VxWorks®, and supports advanced information processing and control system I/O. The standard model Q12DCCPU-V is a space saving controller that realizes high-speed I/O control. The Q24DHCCPU-LS and Q26DHCCPU-LS are OS independent controllers. Linux® based control can be easily realized by installing 3rd Party partner OS, supporting advanced information processing with a user interface environment close to conventional personal computers. Wide scope of applications are realized with the availability of these 4 C Controllers, used together with MELSEC-Q Series I/O modules, 3rd Party products, open source, and customized applications/programs. Providing freedom with a robust, easier and high-performance system.



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For further details, please refer to the "iQ Platform C Controller" catalog.

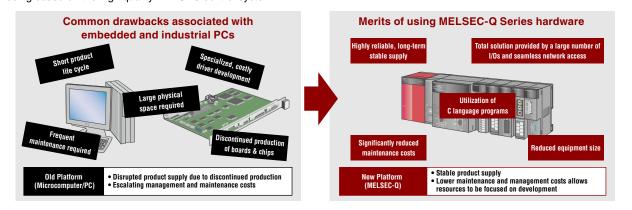
\*1: Set product (Q24DHCCPU-VG-B000/B002) with GENWARE® 3-VG by International Laboratory Corporation.

Ideal for a diverse range of systems, based on a generic platform architecture Leveraging the C Controller to realizing customized systems, by utilization of 3rd Party applications, installation of 3rd Party partner OS, utilization of programs, and open source applications. Partner Zone System Integrator Application Device



The C Controller overcomes the overheads associated with maintaining embedded PCs (micro boards, etc.) and industrial PCs realizing a cost effective solution.

The C Controller platform is a solution that realizes personal computer level functionality without the burden of high maintenance costs usually associated with personal computers. In addition, it includes a robust design that is ideal for industrial environments by being based on the high quality MELSEC control system.

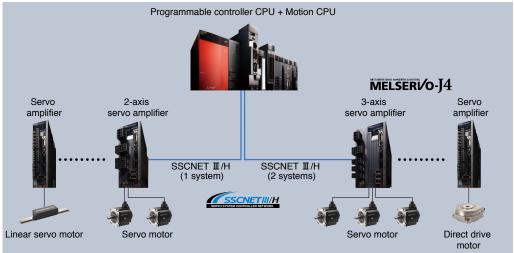




#### Flexibly connecting with servo amplifiers and servo motors, etc., via SSCNET II/H

#### Motion CPU Q173DSCPU, Q172DSCPU

Each MELSEC-Q Series Motion controller is capable of high-speed control of up to 32 axes (96 axes when using three CPUs together). Each Motion CPU is the same size as a standard Q Series programmable controller. The new generation Motion controller is packed with advanced functions while saving space with its smaller size.



# 6

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For further details, please refer to the "MITSUBISHI SERVO SYSTEM CONTROLLERS" catalog.

#### Automating production sites with robots

#### Robot controller ------ CR750-Q, CR751-Q

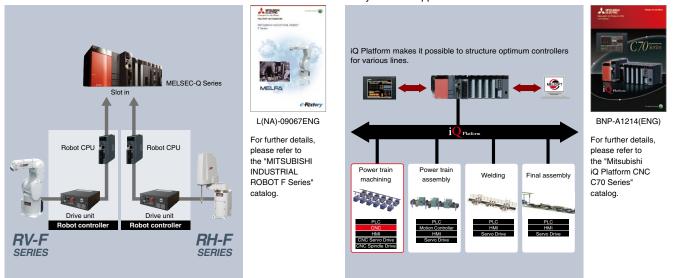
The iQ Platform compatible robot controller increases the speed of data communications between CPUs and dramatically reduces I/O processing times using a high-speed standard base between multiple CPUs.

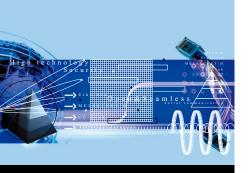


• CNCCPU------Q173NCCPU

This CNC controller is part of the Mitsubishi FA integration solution "iQ Platform".

The integration of the high-performance CNC and high-speed programmable controller helps reduce the total operation cycle time. Supporting a wide range of interface and I/O modules flexible to many different applications.



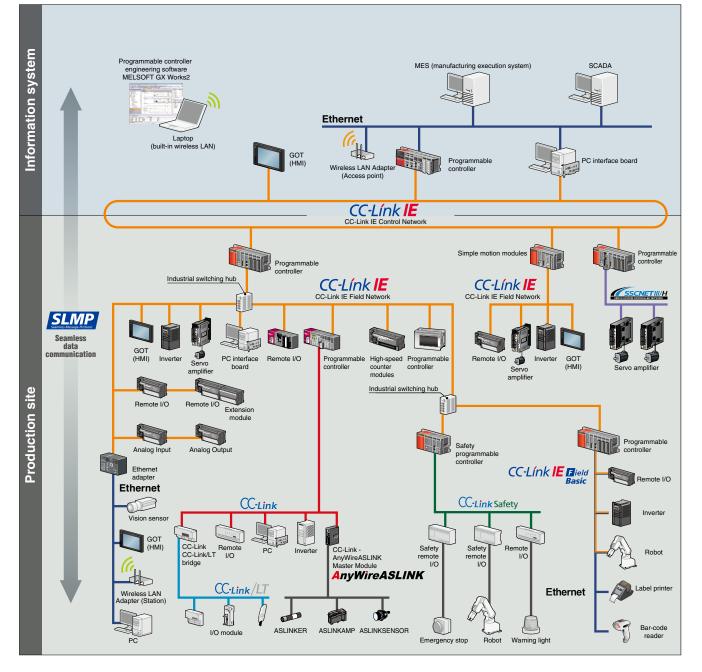


Network

## Seamless communication between upper-level information systems and lower-level field systems; scalable to fit any application size

Enhanced information communication by networking is the essential requirement in the automation industry. The MELSEC-Q Series provides an open and seamless network environment integrating the following different level of automation networks: CC-Link IE; high-speed and large capacity Ethernet-based integrated open network that connects shop floor and IT system as the core of e-F@ctory, CC-Link; SEMI certified global standard network originating from Japan and Asia, CC-Link/LT; wire-saving sensor level network inherited CC-Link design concept, and AnyWire; sensor level distributed control network.

#### Network Configurations



### Seamless communication

Seamless data communication through Ethernet, CC-Link IE, and CC-Link allow easy access to information, no matter where it resides on the network. Through this technology, it is possible to "drill down" from the Enterprise or IT layer through multiple networks accessing programming controllers using GX Works2 programming or other related software.

In addition, many devices supporting SLMP\*1 such as vision sensors and RFID controllers may be connected to the CC-Link IE.

\*1: SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.

## CC-Línk IE Gontrol

CC-Link IE Control is a high-reliability distributed control network designed to handle very large data communications (128K word) over a high-speed (1 Gbps) dual loop optical cable topology. \*: Compatible modules: QJ71GP21-SX, QJ71GP21S-SX

## CC-LÍNK **IE F**lield Basic

CC-Link IE Field Network Basic realizes easier network integration, as its cyclic communications stack is software-based, without requiring a dedicated ASIC helping to reduce implementation costs for device partners. CC-Link IE Field Network Basic, which is a part of CC-Link IE, realizes easier connection of Ethernet devices. \*: Compatible modules: QnUDVCPU, QnUDPVCPU

C-Link Safety

CC-Link Safety is a safety field network that prevents risks on the shop floor. This realizes a highly-reliable and a high-speed communication with less wiring.

\*: Compatible modules: QS0J61BT12

### AnyWireASLINK

AnyWireASLINK makes it possible to centrally monitor (visibility) the state of all sensors from the programmable controller, by that improving productivity and reducing operation steps.

\*: Modules supporting AnyWireASLINK: QJ51AW12AL, NZ2AW1C2AL

#### **BACnet**<sup>®</sup>

This network supports the communication protocol standard BACnet® client function. This network is mainly used to monitor and control airconditioning, lighting and fire detection, etc. in building automation system applications.

\*: Compatible modules: QnUDVCPU, QJ71E71-100 (client only)



## CC-Línk IE Field

CC-Link IE Field is an all-round versatile gigabit Ethernet based network integrating controller, I/O control, safety control, and motion control in a flexible wiring topology supporting star, ring, and line configurations. Compatible modules: QJ71GF11-T2, QS0J71GF11-T2 (safety control), QD77GF4, QD77GF8, QD77GF16 (motion control)

## *-*Link

CC-Link is a high-speed and high-reliable deterministic I/O control network which realizes reduced wiring whilst offering multi-vendor compatible products. This open field network is a global standard originating from Japan and Asia. Compatible module: QJ61BT11N

## CC-Link/LT

CC-Link/LT is a wire-saving sensor level network which is designed for use in panels between simple discrete devices. Its wiring system is based on reducing incorrect wiring and is based on CC-Link realizing high-speed and robust noise resistance features. \*: Compatible module: QJ61CL12

## SSCNETIII/H

SSCNETIII/H is a dedicated high-speed, high-performance, and highly reliable servo system control network which offers flexible long distance wiring capabilities based on optical fiber cable topology. \*: Compatible modules: QD77MS2, QD77MS4, QD77MS16

#### **MODBUS®**

Q-Series is now supporting the MODBUS® protocol network, realizing easy communication, with various MODBUS® slave devices compatible with Ethernet MODBUS®/TCP or RS-232/422/485 serial communication.

- : Module supporting MODBUS®/TCP : QJ71MT91 (master/slave functions), QnUDVCPU, QJ71E71-100 (master only) Modules supporting MODBUS<sup>®</sup>: QJ71MB91 (master/slave functions), QJ71C24N (-R2/
- R4) (master only)

Application	Enterprise level network	Control level network	Device level network			Sensor level network
Network	Information communication	Controller distributed control	I/O control	Safety control	Motion control	Control
Ethernet	•					
CC-Link IE Control		•				
CC-Link IE Field		•	•	•	•	
CC-Link IE Field Network Basic			•			
CC-Link			•			
CC-Link Safety				•		
CC-Link/LT						•
AnyWireASLINK						•
SSCNETI/H					•	
BACnet®	•					
MODBUS <sup>®</sup> /TCP		•				
MODBUS®			•			



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For further details, please refer to the

"Ethernet-based Open Network CC-Link IE Product Catalog" or "Open Field Network CC-Link Compatible Product Catalog".

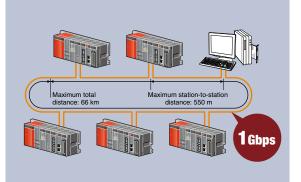
#### Highly reliable distributed control network designed for large bandwidth and high-speed

#### • CC-Link IE Control Network module

Standard model QJ71GP21-SX With external power supply function QJ71GP21S-SX

- » Commercially available Ethernet components can be used for significant cost savings over alternative networks.
- » Deterministic, reliable performance helps to reduce operation cycle time. This cyclic data exchange is fixed and will not suffer from degraded performance even when large volumes of data are transferred.
- » Share massive amounts of data between controllers. (Up to 256K bytes of network shared memory per station)
- » The CC-Link IE Control Network modules, QJ71GP21-SX and QJ71GP21S-SX, may be configured as normal stations, or the control station.





#### ■Performance Specifications\*1

Item		Specif	ication		
	LB	32K points (32768 points, 4 KB) (Basic model QCPU or safety CPU: 16K points (16384 points, 2 KB))			
Max. link points per network	LW	128K points (131072 points, 256 KB) (Basic model QCPU or safety CPU: 16K points (16384 points, 32 KB))			
	LX	8K points (819	2 points, 1 KB)		
	LY	8K points (819	2 points, 1 KB)		
		Regular mode	Extended mode <sup>*2</sup>		
	LB	16K points (16384 points, 2 KB)	32K points (32768 points, 4 KB)		
Max. link points per station	LW	16K points (16384 points, 32 KB)	128K points (131072 points, 256 KB)		
	LX	8K points (8192 points, 1 KB)	8K points (8192 points, 1 KB)		
	LY	8K points (8192 points, 1 KB)	8K points (8192 points, 1 KB)		
Communication speed		1 Gbps			
Number of stations per network		120 (1 control station plus 119 normal stations)			
Connection cable		Optical fiber cable (Multi-mode fiber)			
Overall cable distance		66000 m (When 120 stations are connected)			
Station-to-station distance (Max.)		550 m (Core/Clad = 50/125 (m))			
Max. number of networks		239			
Max. number of groups		32			
Network topology		Ring			

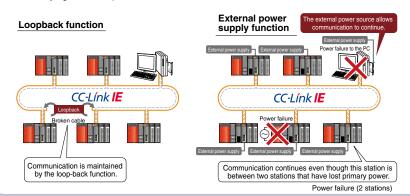
\*1: When the control station is a Universal model QCPU.

\*2: To use extended mode, (QJ71GP21(S)-SX) network modules and Universal model CPUs whose first five serial number digits are 12052 or later are required. All stations in the network must support the extended mode. Also, GX Works2 version 1.34 L or later is required.

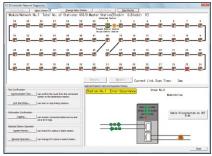
#### Designed to continue functioning even in the worst possible scenarios

• The use of fiber optic cables which are completely immune to EMI and RFI noise allows the network to function in environments where other networks cannot. The dual loop design allows the network to continue functioning even if cables become damaged or the power is lost to a station.

 Additionally, CC-Link IE stations can be powered using an external supply. That allows communication to continue normally in the event of a loss of the primary power supply, without relying on the loop-back function.



#### Visual display of network connection status



View the network connection status of entire system to identify problems at a glance. The cause of problems can be quickly identified and suggested remedies implemented to minimize down time.

#### Connect to remote I/O stations and other programmable controllers for high-speed distributed control with advanced functionality

[Line topology]

Gbps

- » Tremendous speed and bandwidth using commercially available cables and connectors. The network design (topology) is highly flexible to fit any layout.
- » Operates as either a master or local station. Perfect for managing remote I/O control and distributed control.
- » Devices from other stations can be accessed easily via transient communication using dedicated instructions.
- » Function blocks for transient communication are available to further simplify messaging. » The network can ensure 32-bit data integrity using the station-based block data assurance
- function. This forces pairs of word data to get updated together during link refresh. » The QJ71GF11-T2 CC-Link IE Field Network module can function as a slave or master
- station.



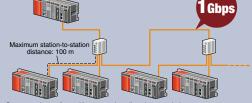
#### ■Performance Specifications

Item		Specification			
	RX	16K points (16384 points, 2 KB)			
Max. link points per	RY	16K points (16384 points, 2 KB)			
network	RWr	8K points (8192 points, 16 KB)			
	RWw	8K points (8192 points, 16 KB)			
	RX	2K points (2048 points, 256 B)			
Max. link points per	RY	2K points (2048 points, 256 B)			
station	RWr	1K points (1024 points, 2 KB)			
	RWw	1K points (1024 points, 2 KB)			
Communication speed		1 Gbps			
Number of stations per	network	121 (1 master plus 120 slave stations)			
Connection cable		Ethernet cable (Category 5e or higher, double shielded/STP)			
Maximum annuall	Line topology	12 km (with 1 master and 120 slaves connected)			
Maximum overall cable distance	Star topology	Depends on the system configuration. <sup>1</sup>			
	Ring topology	12.1 km (with 1 master and 120 slaves connected)			
Max. station-to-station distance		100 m			
Max. number of network	ks	239			
Network topology		Line, star, line and star mixed, or ring <sup>2</sup>			

\*1: Up to 20 hubs can be connected per network.

 Project number of the contracted per letters.
 Project number of the mixed with line or star networks. QJ71GF11-T2 network modules whose first five serial number digits are 12072 or later are required for ring networks. Additionally, GX Works2 version 1.34 L or later is required.

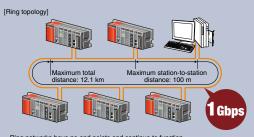




Maximum station-to-station distance: 100 m

Maximum total distance: 12 km

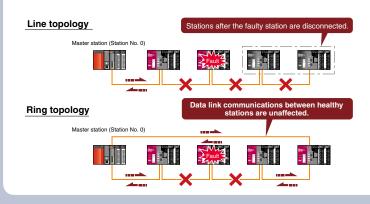
Star networks are formed by connecting all stations to a hub



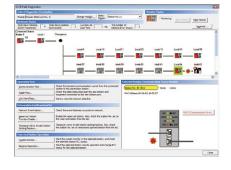
Ring networks have no end points and continue to function even if a connection becomes broken.

#### Easy diagnosis functions

• In certain situations such as power loss, a station could be prevented from communicating. In a line network this can cause perfectly healthy stations can become separated from the network. In a ring network, only the faulty station is separated, thus increasing the system reliability.



#### Visual display of network connection status



The network diagnostic tools in GX Works2<sup>-3</sup> allow problems to be identified rapidly. In addition to a visual overview of the network and several other tools, detailed monitoring of CPUs and modules from any station, to any station is possible.

\*3: Not supported by GX Developer

#### Linking the sensor with the programmable controller

#### AnyWireASLINK master module QJ51AW12AL

The AnyWireASLINK master module links the sensor inputs and outputs to the programmable controller. The module enables flexible layout of sensors with 512 I/O points. The sensor power can be supplied to the AnyWireASLINK transmission line (2-wire) for communication, allowing sensors to be added easily. With the MELSEC-Q/L/F Series, faulty sensors can be detected and the slave module settings can be managed at once by GX Works2 engineering environment, further reducing the engineering time.

#### AnyWireASLINK

#### System configuration example

#### Basic configuration

Either the 2-wire type or 4-wire slave device can be selected according to the load current for AnyWireASLINK. In addition to the 2-wire type, a 4-wire type can also be used by supplying the local power.

#### 2-wire type

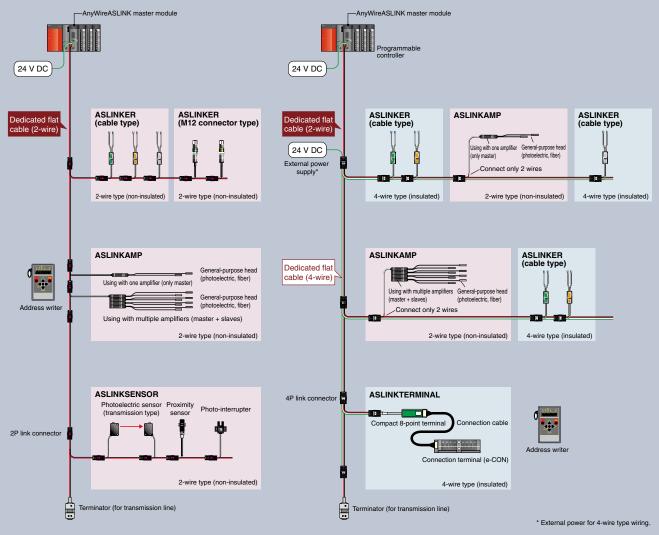
If the load current is low, 2-wire type (non-insulated) slave devices can be used without an external power supply.

#### 4-wire type

The 4-wire type (insulated) slave devices require an external 24 V DC power supply to satisfy large load current applications, for example.

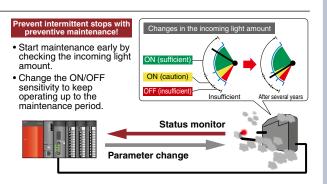
#### Configuration with 2-wire type (with no local power feed)

#### Configuration with 2-wire/4-wire type (with local power feed)



#### Preventing intermittent operation stops

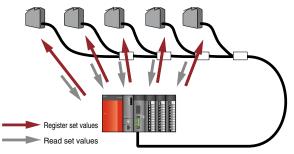
AnyWireASLINK can be used to monitor and save the sensor information within the programmable controller. Parameter settings of the AnyWireASLINK can also be changed via the programmable controller. Perform "preventive maintenance" with this function to prevent intermittent stops before they happen.



#### Reducing the setup time, and providing the traceability

AnyWireASLINK enables the set value to be registered at once to multiple sensors via a GOT (HMI) or personal computer. Also, the initial set values can be re-confirmed easily without having to read each sensor individually.

• Register set values to multiple sensors, and automatically read the initial set values.



Model	QJ51AW12AL
Number of connected I/O points	Max. 512 points (256 input points/256 output points)
Number of connected modules	Max. 128 modules (varies according to each slave module's current consumption)
Maximum transmission distance (overall length)*1	200 m*2
Transmission method	DC power superimposed total frame cyclic method
Connection style	Bus type (multi-drop method, T-branch method, tree branch method)
Transmission protocol	Dedicated protocol (AnyWireASLINK)
Error control	Checksum, double verification method
Transmission clock	27.0 kHz
RAS function	Transmission cable break position detection function, transmission cable short-circuit detection function, transmission power drop detection function
Transmission cable (DP, DN)	<ul> <li>UL compatible universal 2-wire cable (VCTF, VCT 1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>UL compatible universal cable (1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>Dedicated flat cable (1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 90°C)</li> </ul>
Power cable (24 V, 0 V)*1	<ul> <li>UL compatible universal 2-wire cable (VCTF, VCT 0.75 mm<sup>2</sup>,20 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>UL compatible universal cable (0.75 mm<sup>2</sup>2.0 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>Dedicated flat cable (1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 90°C)</li> </ul>
Transmission cable supply current*1	Using 1.25 mm² cable: Max. 2 A Using 0.75 mm² cable: Max. 1 A
External power supply	Voltage: 21.627.6 V DC (24 V DC -10+15%), ripple voltage 0.5 Vp-p or less Recommended voltage: 26.4 V DC (24 V DC +10%) Module current consumption: 0.1 A Transmission cable current supply: Max. 2 A*1

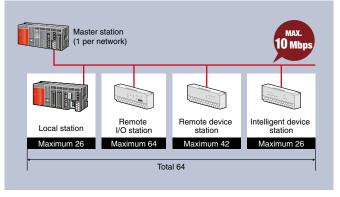
2. There to the manual for the relation of the overall length, transmission cable (DP, DN) whe diameter and transmission cable current supply. In some slave modules w (DP, DN) integrated with the module may be 0.75 mm<sup>3</sup> or less.
 2. With the slave module having an integrated transmission cable (DP, DN) and module, the length of the transmission cable (DP, DN) is included in the overall length.

#### Superior cost-performance field network with many compatible devices

#### CC-Link network module ------QJ61BT11N

- » By building on reliable field bus technology, CC-Link is capable of moving large volumes of bit data, like ON/OFF relay status, and word data at highspeed.
- » CC-Link keeps cyclic transmission consistent and guarantees punctuality by separating it from message (transient) communication. Even if message communication becomes saturated, it will not affect the link scan time.
- » The QJ61BT11N module supports CC-Link version 1 and 2, and may be used as a local or master module.

## Link



#### ■Performance Specifications

Item			Specification		
Communication speed			Can select from 156 kbps/625 kbps/2.5 Mbps/5 Mbps/10 Mbps		
Transmission path			Bus (RS-485)		
Maximum number of link points per system <sup>*1</sup>		em⁺1	Remote inputs/outputs (RX, RY): 8192 points Remote registers (RWw): 2048 points Remote registers (RWr): 2048 points		
	Single		Remote inputs/outputs (RX, RY): 32 points (30 points for local station) Remote registers (RWw): 4 points Remote registers (RWr): 4 points		
Maximum number of link points per	Expanded cyclic	Double	Remote inputs/outputs (RX, RY): 32 points (30 points for local station) Remote registers (RWw): 8 points Remote registers (RWr): 8 points		
system	setting	Quadruple	Remote inputs/outputs (RX, RY): 64 points (62 points for local station) Remote registers (RWw): 16 points Remote registers (RWr): 16 points		
		Octuple	Remote inputs/outputs (RX, RY): 128 points (126 points for local station) Remote registers (RWw): 32 points Remote registers (RWr): 32 points		
Maximum number of connected stations (master station)		(master station)	64'2		
Total distance/speed (When using Ver. 1.10)		.10)	1200 m/156 kbps, 900 m/625 kbps, 400 m/2.5 Mbps, 160 m/5 Mbps, 100 m/10 Mbps (Using repeaters, it is possible to extend the network distance up to 13.2 km)		

\*1: For CC-Link version 2. \*2: Using only remote I/O stations.

#### Device level wire-saving network

#### • CC-Link/LT network module QJ61CL12

- » The maximum of 64 stations can be updated in as little as 1.2 ms (at 2.5 Mbps). Choose from 3 transmission speeds according to the required transmission distance.
- » CC-Link/LT slave stations do not require any parameters, only the
- transmission speed needs to be specified by the master station.
- » The QJ61CL12 CC-Link/LT network module can only function as a master station.



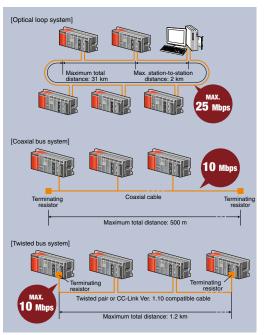
#### ■Performance Specifications

li	em	Specification		
Communication spee	d	156 kbps/625 kbps/2.5 Mbps		
Transmission path		T-branch topology		
Max. connected mod	ules	64		
	Length of trunk line	35 m/2.5 Mbps, 100 m/625 kbps, 500 m/156 kbps		
Overall distance	Max. length drop line	4 m/2.5 Mbps, 16 m/625 kbps, 60 m/156 kbps		
	Overall length drop lines	15 m/2.5 Mbps, 50 m/625 kbps, 200 m/156 kbps		

#### Cost-effective distributed control network compatible with A and AnS Series

MELSECNET/H network module	
Optical loop typeQJ71LP21-25, QJ71LP21S-25, QJ71LP21G,	
QJ72LP25-25, QJ72LP25G (Remote I/O station)	
Coaxial bus typeQJ71BR11, QJ72BR15 (Remote I/O station)	
Twisted bus type QJ71NT11B	

- » MELSECNET/H network systems support controller-to-controller, controller-to-personal computer, and controller-to-remote I/O station communications. Multiple wiring types are available and many functions designed to increase reliability are included, such as support for redundant systems.
- » Optical loop type: Communication speeds up to 25 Mbps. Fiber optic cable is immune to EMI/ RFI noise. Up to 2 km between stations using GI type cable.
- » Coaxial bus type: Using low cost coaxial cable allows networks to be constructed at less cost than optical loop networks.
- » Twisted bus type: The combination of an affordable network module and twisted-pair cables allows a network system to be built at very low cost.



#### ■Performance Specifications

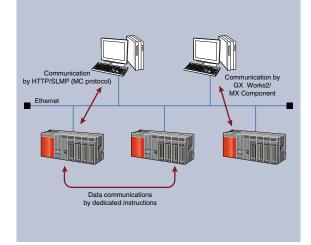
	Item		Specification					
Network conf	ligurations		Optical loop system Coaxial bus system			Twisted bus system		
Model		QJ71LP21(S)-25 QJ72LP25-25	QJ71LP21G QJ72LP25G	QJ71BR11 QJ72BR15		QJ71NT11B		
Cable			Fiber optic (SI)	Fiber optic (GI)	Coaxial (3C-2V)	Coaxial (5C-2V)	Twisted pair	CC-Link Ver. 1.10- compatible cable
	Maria	LB	16384 points (8192 points in the MELSECNET/10 mode)		16384	16384 points		
	Maximum number of link points per network	LW	16384	points (8192 points ir	the MELSECNET/10	mode)	16384	points
		LX/LY	8192 points					
PLC to PLC network	Maximum number of link po	ints per station		• MELSECNET/H mode {(LY + LB) /8 + (2 x LW)} ≤ 2000 bytes • MELSECNET/H extended mode {(LY + LB) /8 + (2 x LW)} ≤ 35840 bytes				
	Number of stations per netw	vork	Up to 64 (1 control station, 6		Up to	32 stations (1 control	station, 31 normal st	ations)
	Mariana and a state	LB		aster to Remote Sub-r	points naster or Remote I/O: 8 O to Remote Master: 8			
	Maximum number of link points per network	LW		16384 points (Remote Master to Remote Sub-master or Remote I/O: 8192 points, Remote Sub-master or Remote I/O to Remote Master: 8192 points)				
		LX/LY	8192 points					
Remote I/O network	Maximum number of link points per station		<ul> <li>Remote Master to Remote I/O ((LY + LB) /8 + (2 x LW)) ≤ 1600 bytes</li> <li>Remote I/O to Remote Master ((LX + LB) /8 + (2 x LW)) ≤ 1600 bytes</li> <li>Multiplexed Remote Master from/to Multiplexed Remote Sub-master ((LY + LB) /8 + (2 x LW)) ≤ 2000 bytes</li> </ul>			_		
	Maximum I/O points per rer	note I/O station	If X/Y numbers		096 points one side is taken into	consideration.		
		М		8192	points			
	Device points per remote	SM		2048	points			
	I/O station	D			points			
		SD			points			
	Number of stations per netw	vork	Up to 65 stations (1 remote master station, 64 remote I/O stations) Up to 33 stations (1 remote master station, 32 remote I/O stations)					
Communication speed		25 Mbps/10 Mbps 10 Mbps			ps/625 kbps/1.25 /5 Mbps/10 Mbps			
Overall distance		30	km	300 m	500 m	1200 m/156 kbps, 600 m/312 kbps, 400 m/625 kbps, 200 m/1.25 Mbps	1200 m/156 kbps, 900 m/312 kbps, 600 m/625 kbps, 400 m/1.25 Mbps, 200 m/2.5 Mbps, 150 m/5 Mbps, 100 m/10 Mbps	
Distance between stations			Up to 1 km	2 km	-	_	-	_

#### Interface module connectable with multiple Ethernet devices

#### Ethernet interface module

10BASE-T/100BASE-TX ......QJ71E71-100

- » Use dedicated instructions for communication between programmable controller CPUs.
- » A communication library and sample code is available to allow a web server to access any of the Ethernet modules and exchange information with the programmable controller CPU module. In this way, the web server may host a web page that allows remote operation of a programmable controller over the Internet via web browser.
- » To improve programming, maintenance, and debugging efficiency, multiple CPU connections may be established simultaneously using GX Developer and GX Works2
- » The E-mail Function allows Ethernet modules to send e-mail with attachments in binary, ASCII, and CSV formats via a mail server.
- » Perform existence checks and keep connections open using the KeepAlive or PING functions. This can be used to ensure connectivity and quickly discover errors.

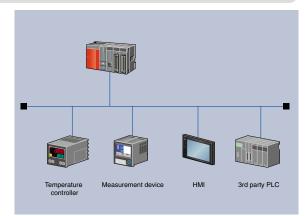


#### Connect with a large variety of devices using the MODBUS® interface module

MODBUS<sup>®</sup> interface module

RS-232 1ch, RS-422/485 1ch	QJ71MB91
10BASE-T/100BASE-TX	QJ71MT91

- » Using the master function, communicate with 3rd party MODBUS® compatible slave devices.
- » Slave mode is also supported, which allows communication with other MODBUS® masters such as 3rd party programmable controllers.
- » Using the QJ71MB91 synchronization function, a master station may be connected to CH1 (RS-232) and communicate with multiple slaves connected to the CH2 (RS-422/485) interface.
- » The QJ71MT91 module is able to operate using the master and slave functions simultaneously.

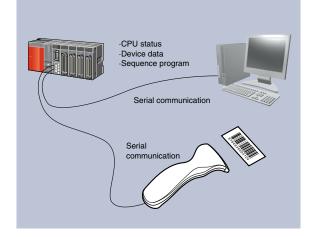


#### These highly flexible communications modules allow connection to practically any serial device

#### Serial communication module

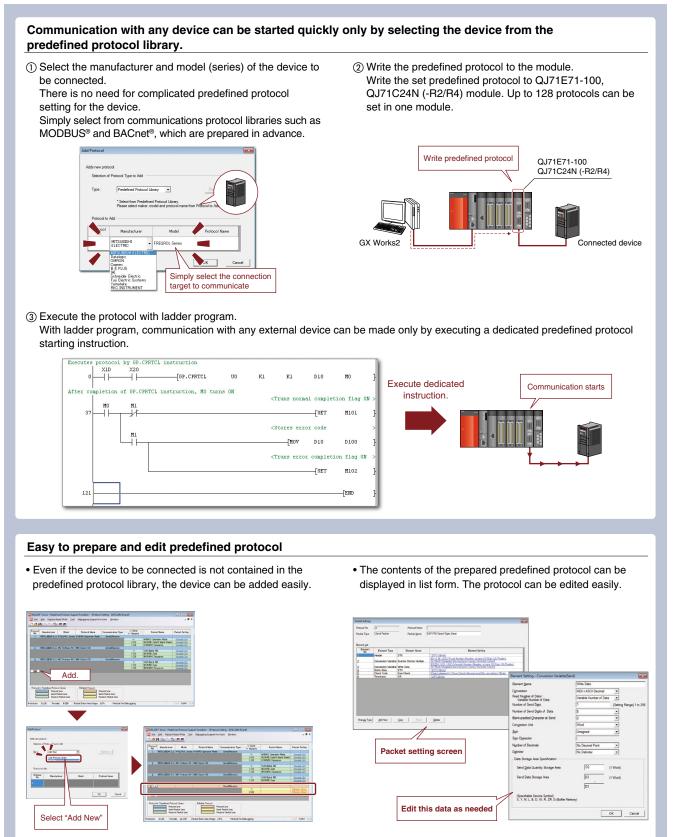
RS-232 1ch, RS-422/485 1ch	QJ71C24N
RS-232 2ch	QJ71C24N-R2
RS422/485 2ch	QJ71C24N-R4

- » Push the limits of serial technology: baud rates up to 230.4 kbps, distance up to 1200 m, and multiple block batch read/write up to 960 words from QCPU device memory
- » External devices (personal computer, HMI, etc.) may read and write data in the programmable controller CPU using MC protocol.
- » Connect with intelligent devices using their native protocol (barcode reader, measurement device, etc.) by selecting non-procedure protocol and using a sequence program for communication control.
- » MELSOFT engineering tools can establish a connection to the programmable controller CPU through the serial connection to perform programing and maintenance duties.
- » Dedicated functions are available to facilitate RS-232 communication over public telephone lines using a serial modern. One of them, the remote password function, prevents unauthorized access to programmable controllers via the modem line.





## Easier to use through combination of Ethernet/serial communication module and GX Works2 (predefined protocol support function)



\* Supported by QJ71C24N (-R2/R4) with the function version B and a serial number whose first 5 digits are 11062 or higher.
\* Supported by products with the first five digits of the QJ71E71-100 product number of 15042 or later.

#### Make the jump from shop floor data to valuable information in real time

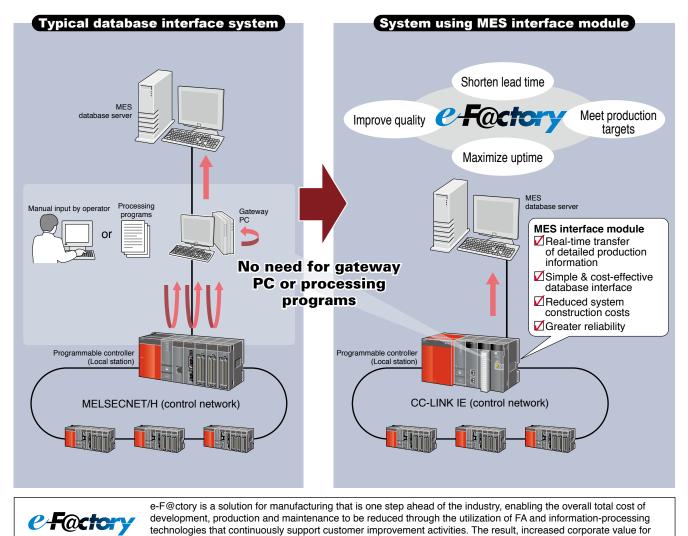
#### MES interface module

#### -QJ71MES96N **№**

- » Simplify the process of connecting to enterprise system databases such as an MES<sup>\*1</sup> by connecting directly. Configuration of the module is easy, and does not require any programming.
- » When user-defined trigger conditions occur, the specified data is read and transferred via SQL text. This event-driven communication method reduces network loading when compared to conventional solutions, which are based on polling architecture.

the customer!

- » Executes pre-registered SQL jobs. Also receives production instructions from MES and downloads production information from the database.
- \*1: MES (Manufacturing Execution System): A system that manages and controls production activities to optimize quality, production volume, delivery, costs, etc.



#### Fulfill the need for traceability and discover a powerful troubleshooting tool

#### High speed data logger module

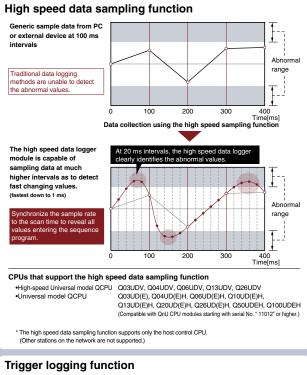
#### QD81DL96

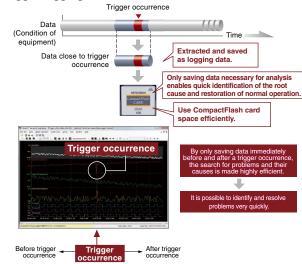
» High speed data sampling function

The high speed data sampling function has the power to synchronize with the sequence program scan, ensuring that every value available to the program is logged for analysis. Using this method it is possible to perform detailed operational analysis and identify existing or potential problems.

» Trigger logging function

Trigger logging allows the user to specify, in great detail, when data should be saved. This greatly simplifies the process of investigating why a problem has occurred and assists in the quick identification of solutions. Additionally, it allows CompactFlash memory card space to be used efficiently.





- » The logging data display and analysis tool, GX LogViewer, has a simple and effective interface that is user customizable and includes features to maximize the efficiency of analyzing collected data. The High speed Data Logger Module Configuration Tool enables the user to create sophisticated data collection rules using an intuitive step-by-step process. The wizard like interface is beginner-friendly and includes features like importing global labels and device comments.
- » Automatic generation of reports including graphs
- By creating an Excel® layout file and transferring it to the module, the report function can automatically fill in the numbers using sampled data to create reports on a reoccurring basis. All kinds of reports may be created that include charts, graphs, and other visual aids. It is even possible to e-mail the reports automatically!

#### High speed data logger module tools

#### Data display and analysis tool: GX LogViewer



View a list of events or a trend graph [pictured left] either in real-time (online) or historical (saved file) modes. Helpful features ensure key information is immediately visible.

Data logging in progress

High Speed Data Logger Module

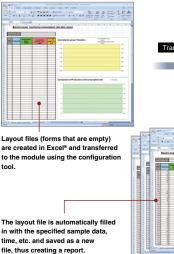
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#### High speed data logger module configuration tool



Even making sophisticated data collection rules is easy to do using the intuitive step-by-step configuration process.

 The High speed Data Logger Module Tools are available at no additional cost. Please contact your nearest Mitsubishi Electric representative for details.



#### Automatic generation of reports including graphs

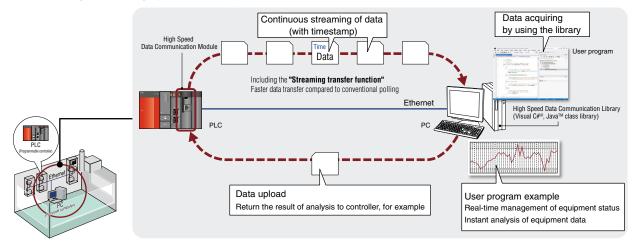
#### Supporting productivity and enhanced device value through real-time transfer of control data

#### High speed data communication module -------

- .....QJ71DC96
- » High data accuracy communication from the programmable controller to the personal computer can be easily realized with the high-speed data communication module (QJ71DC96). Data can be streamed at high speed to the personal computer by synchronizing with the controller scan cycle without having to continuously poll data as was previously achieved. This feature realizes improved productivity by resulting in real-time control data analysis on the personal computer.

#### Fast and reliable large data transfer in real-time

• Transfer of large data volumes across a very short sampling period can be realized with "Streaming transfer" feature. High data integrity can be easily achieved across TCIP/IP Ethernet to personal computer based servers.

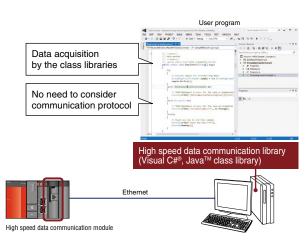


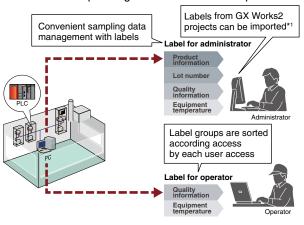
#### Data acquisition without considering protocol

Communication between the module and a personal computer is provided in the form of Visual C#<sup>®</sup> and Java<sup>™</sup> class libraries. These class libraries enable a simple personal computer program to acquire data from the programmable controller without considering the communication protocol.



 Labeling (naming) each personal computer data makes classifications of transferring data simple. Multiple labels are grouped and sorted as label groups by equipment or user. Label group access control corresponding to user levels is also possible.





\*1: The engineering software GX Works2 Version 1.44 W or later is required when the global labels of GX Works2 project are imported to the Configuration Tool of this module.

### Ethernet and CC-Link IE Field related products

- Industrial switching HUB CC-Link IE Field Ethernet
   NZ2EHG-T8N
- » NZ2EHG-T8N is compatible with transmission rates of 10 Mbps, 100 Mbps, and 1 Gbps.
- » This switching hub complies with IEEE802.3ab (1000BASE-T), IEEE802.3u (100BASE-TX), IEEE802.3 (10BASE-T) standards.
- » AUTO MDI/MDI-X and auto-negotiation are available.
- » The automatic power adjustment function can reduce power consumption by up to 60 percent.\*3
   » This hub does not use cooling fans, and yet a wide ambient-temperature operating range is permissible (0 to 50°C).
- » Quick detach mechanism allows easy DIN rail attachment and detachment.
- \*3: For comparison, power consumption was measured when all 8 ports were used and when none of them were used.

This series was developed and is produced with Contec Co. Ltd. Please note that the specifications and guarantee conditions of this product is different from those of MELSEC products. Please refer to the product manual for details.

# CC-Link IE Field Network Ethernet adapter module CC-Link IE Field NZ2GF-ETB

- » Using Seamless Message Protocol (SLMP\*4), a variety of Ethernet devices such as vision sensors and RFID controllers can be connected to the CC-Link IE Field Network.
- » Use a web browser to set station numbers, Ethernet options, and view error history.
- » This Ethernet adapter module is compatible with transmission rates of 100 Mbps and 1 Gbps.

\*4: SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.

1 Gbps

Ethernet



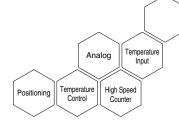




## Module Lineup

# Comprehensive range of I/O and intelligent function modules

The Q Series I/O and intelligent function module lineup is extensive and capable of meeting the needs of a wide range of applications. Some of the available modules include motion control, serial communication, temperature control, temperature input, standard digital and analog I/O modules, and channel isolated analog modules. Attain the ideal solution for the application, whether it be high speed positioning or high accuracy temperature control.



### Input modules, Interrupt module

	DC input					DC/AC input	AC i	nput
Point	5 V	DC	5/12 V DC	24 V DC		48 V DC/AC	100120 V AC	100240 V AC
	Positive	Negative	Positive/Negative	Positive	Negative	Positive/Negative	100120 V AC	100240 V AC
8 points	—	—	—	QX48Y57*1	—	—	—	QX28
16 points	QX70H	QX90H	QX70	QX40 QX40-TS QX40-S1 QX40H QI60	QX80 QX80H QX80-TS	QX50	QX10 QX10-TS	_
32 points	_	_	QX71	QX41 QX41-S1 QX41-S2 QH42P* <sup>1</sup> QX41Y41P <sup>*1</sup>	QX81 QX81-S2	_	_	_
64 points	_	_	QX72	QX42 QX42-S1	QX82 QX82-S1	_	_	—

\*1: Input specifications for I/O combined modules

### Output modules

	Contact output	TRIAC output		Transistor output			
Point	24 V DC, 240 V AC	100240 V AC	512 V DC	524	V DC	1224 V DC	
	24 V DC, 240 V AC	100240 V AC	Sink type	Sink type	Sink/Source type	Sink type	Source type
7 points	—	—	—	—	—	QX48Y57*2	—
8 points	QY18A	—	—	—	QY68A	—	—
16 points	QY10 QY10-TS	QY22	QY70	_	_	QY40P QY40P-TS QY50	QY80 QY80-TS
32 points	_	_	QY71	QY41H	_	QY41P QH42P* <sup>2</sup> QX41Y41P* <sup>2</sup>	QY81P
64 points	_		_	_	—	QY42P	QY82P

\*2: Output specifications for I/O combined modules

High speed DC input module (positive common type)
 .....QX40H, QX70H

High speed DC input module (negative common type)
 QX80H, QX90H

Speed up control by catching the input signal variation at 0 ms\*<sup>3</sup>. Two devices with differing power systems can be connected to the same module using different 8 point common terminals. \*3: The actual response time is 5 µs delay when turning ON, 10 µs delay when

turning OFF, because the hardware response time is added.

Common type	Input voltage		
Common type	24 V DC	5 V DC	
Positive	QX40H	QX70H	
Negative	QX80H	QX90H	

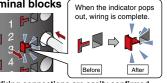
Spring clamp terminal block type input module
 QX10-TS, QX40-TS, QX80-TS

Spring clamp terminal block type output module
 QY10-TS, QY40P-TS, QY80-TS

Spring clamp terminal blocks visually indicate the connection status. Also, by eliminating screws, wiring and maintenance work is made easier.

Advantages of spring clamp terminal blocks

- Impervious to vibration, secured wiring connections.
  Eliminating screws greatly simplifies conventional
- maintenance.



Wiring connections are easily confirmed by high-contrast indicators.

### Analog modules

					Analog input				Analog	output
Number of	Channel	Voltage	Current	Signal		pad cell CT input	Temperat		Voltage	Current
channels isolat	isolated	input	input	conditioning	Load cell		Temperature input	RTD	output	output
1	•	_	_	—	Q61LD	_	—	—	—	—
	•	_	_	Q62AD-DGH	_	_	—	—	Q62D	A-FG
2	—	_	—	_	—	_	_	—	Q62D Q64A	
	•	Q64A	D-GH	_	—	_	Q64TD Q64TDV-GH	Q64RD-G	—	—
4	_	Q64A Q64A Q64A	DH	_	_	_	-	Q64RD	Q64D Q64D	
6	•	—	—	Q66AD-DG	—	—	—	—	Q66D	A-G
8	•	Q68A	D-G	-	—	_	Q68TD-G-H01 Q68TD-G-H02	Q68RD3-G	—	—
	_	Q68ADV	Q68ADI	_	_	Q68CT	—	_	Q68DAVN	Q68DAIN

### Temperature control modules

Number of	Wire break	Input		
channels	detection	Thermocouple	RTD	
4	•	Q64TCTTBWN	Q64TCRTBWN	
4	_	Q64TCTTN	Q64TCRTN	

### Simple motion modules

Number of axes	CC-Link IE Field	SSCNET II/H
2	—	QD77MS2
4	QD77GF4	QD77MS4
8	QD77GF8	—
16	QD77GF16	QD77MS16

### **Positioning modules**

Number of	Specialized functionality type			Simple control and fast-response type			Built-in counter function type
axes	Open collector output	Differential drive output	SSCNET II	Open collector output	Differential drive output	SSCNET II	Open collector output
1	QD75P1N	QD75D1N	QD75MH1	_	—	—	_
2	QD75P2N	QD75D2N	QD75MH2	_	—	—	_
3	_	_	_	_	—	—	QD72P3C3
4	QD75P4N	QD75D4N	QD75MH4	QD70P4	QD70D4	—	_
8	_	—	_	QD70P8	QD70D8	QD74MH8	_
16	—	—	_	—	—	QD74MH16	—

### High-speed counter modules, Pulse input module

		Maximum counting		Input specifications			
Numbe	r of channels	speed	Channel isolated	5 V DC	12 V DC	24 V DC	Differential drive output
					QD62 QD62E QD65PD2		_
2	2-phase input	500 kpps		—	_	_	QD62D
		4 Mpps		—	—	—	QD64D2
		8 Mpps		—	—	—	QD65PD2
6	2-phase input	200 kpps	—	QD63P6	—	—	—
8	1-phase input	30 kpps	•		QD60P8-G	-	-

### Energy measuring modules, Insulation monitoring module

Number of channels	Energy measuring	Insulation monitoring
1	QE81WH QE81WH4W	—
2	—	QE82LG
3	QE83WH4W	—
4	QE84WH	_

### Loop control module

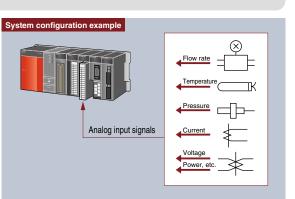
Number of channels	Input				
	Voltage	Current	Thermocouple	RTD	
2	Q62HLC				

# A wide range of application specific intelligent modules

A range of analog modules ideal for process control applications.

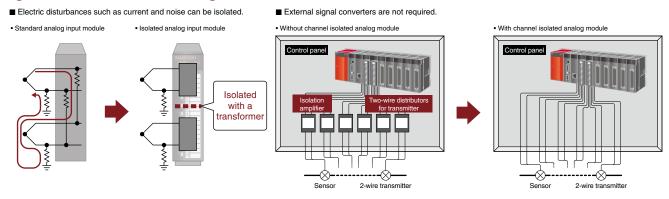
### Isolated analog modules suitable for process control

Channel isolated high resolution analog-digital converter module
Q64AD-GH
Channel isolated high resolution analog-digital converter module
(with signal conditioning function)
Channel isolated high resolution digital-analog converter module
Q62DA-FG
Channel isolated analog-digital converter module Q68AD-G
Channel isolated analog-digital converter module
(with signal conditioning function)
Channel isolated digital-analog converter module Q66DA-G



The channel isolated analog modules are specifically designed for process control applications by offering high accuracy conversion combined with high isolation voltage. Flow meters, pressure gauges, etc. can be directly connected to the analog input, and control valves to the analog output. Hardware and installation costs can be substantially reduced because external isolation amplifiers are not required. When used with a general purpose controller, a low cost process control solution can be created.

### High dielectric withstand voltage



#### High conversion speed analog modules

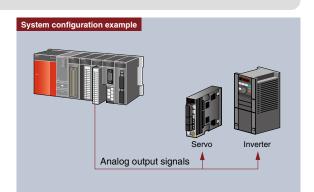
- High speed analog-digital converter module------ Q64ADH

- Digital-analog converter module ------

### Q62DAN, Q64DAN, Q68DAVN, Q68DAIN

• Analog-digital/Digital-analog converter module ---- Q64AD2DA

Many high-speed A/D and D/A conversion (analog) modules are available. These modules are feature packed to allow maximum flexibility when connecting to devices. Both speed and accuracy are great enough to control sensitive motion applications using servos or inverters.



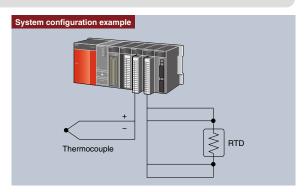


#### High accuracy temperature input modules

#### Temperature input module

Thermocouple input module ......Q64TD, Q64TDV-GH, Q68TD-G-H01, Q68TD-G-H02 RTD input module ...... Q64RD, Q64RD-G, Q68RD3-G

Temperature data can be captured by connecting a thermocouple or a resistance temperature detector. Multi-channel (8-channel) input types and channel-isolated types are available. An optimum model for the intended application can be selected.



Control

panel

СТ

System configuration example

Temperature

Heater

#### PID loop control integrated temperature control modules

• Temperature control module

Q64TCTTBWN Platinum RTD input module Q64TCRTN. Q64TCRTBWN

The devices which require high stability of temperature control such as extrusion forming machines, these modules prevent overheating and overcooling. The standard control (heating or cooling) or heating-cooling control (heating and cooling) mode can be selected depending on the machine to be controlled.

In addition, the mixed control mode (combination of standard control and heating-cooling control) can be selected.

#### Peak current suppression function

This function avoids simultaneously turning on outputs to control the peak current. It can save energy and reduce the running cost.

- Simultaneous temperature rise function
- This function allows several loops to reach the set value at the same time to conduct uniform temperature control.

It prevents idling and is effective in saving energy and reducing running cost.

#### Self-tuning function

The PID constant is automatically adjusted during control.

The automatic tuning cost (time, materials and power) can be reduced.

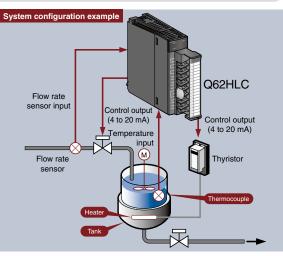
### Loop control module ideal for temperature and flow rate control environments which require fast response

Loop control module
 Q62HLC

With its speed-proportional control format and 25 ms sampling cycle, the loop control module is well suited for high-precision, high-resolution thermocouple inputs, micro voltage inputs, voltage inputs, current inputs, and current outputs. It is also ideal for sudden temperature change control, pressure control, and flow control applications which require fast response.

• Connectable to JIS, IEC, NBS, ASTM standards compliant thermocouples.

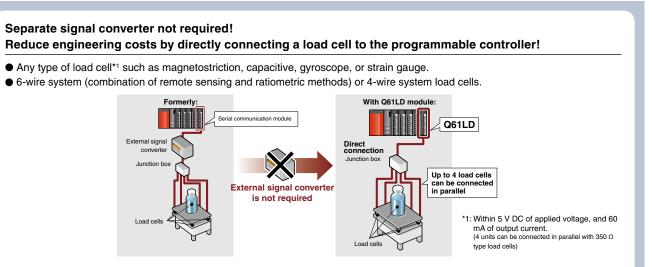
- · Permits analog value measurements of various input ranges by using micro voltage, voltage, and current input sensors.
- Offers program control while automatically changing the target values (SV) and PID constants [proportional band (P), integral time (I), derivative time (D)] in a time-specific manner, as well as a cascade control function that permits control with CH 1 as the master, and CH 2 as the slave.



### Interface with all types of load cell with the load cell I/P module

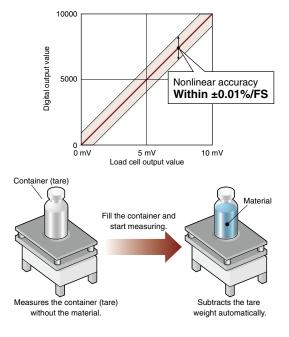
#### Load cell input module Q61LD

Load cells can now be directly connected to the programmable controller system without requiring an external signal converter. The module achieves highly accurate measurement with steady data conversion speed that guarantees the accuracy of load cells.



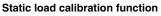
• Applications requiring high accuracy can be achieved by connecting the load cell directly to the programmable controller.

- Nonlinear accuracy: Within ±0.01%/FS
- Zero drift: Within ±0.25 µV/°C RTI
- Gain drift: Within ±15 ppm/°C
- (Load cell rated output is 2 mV/V, ambient temperature is  $25^{\circ}$ C, and the tare weight subtraction function is not used.)

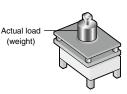


#### Zero offset function

This function subtracts the tare weight automatically relative to the load cell usage range when calibrating measuring instruments. Using this function can improve the accuracy of the measuring instrument.



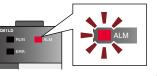
The gross weight value can be accurately calibrated by applying the actual load (weight) onto the load cell.



### Input signal error detection function

Load cell input signal errors can be detected.

- Input signal error
- Weight capacity over error
- Zero point out of range Exceed conversion error



### Direct CT sensor connection reduces wiring and saves space

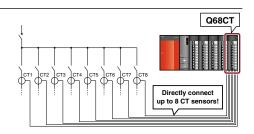
#### • CT input module Q68CT

The direct connection of the CT sensor<sup>\*1</sup> and the programmable controller has eliminated the need to connect a separate signal converter. Very accurate measurements can be achieved with stable data conversion speed for load control of systems and devices, monitoring of operations, and control and monitoring of power systems.

\*1: The CT (Current Transformer) sensor refers to an instrument transformer, a current sensor is essential for measuring alternating currents.

#### Direct CT sensor connection reduces wiring and saves space

- Directly connect to the CT sensor without an external signal converter. The AC current for up to eight channels can be measured with one unit, by that reducing the wiring steps and costs.
- Set the CT sensor type (input range) for each channel. CT sensors with 0 to 5 A AC or 0 to 600 A AC can be used by one unit.



#### Predictive maintenance of devices by detecting the peak current!

Analog input range

0...50 A (AC)

0...100 A (AC)

0...400 A (AC)

0...600 A (AC)

0...5 A (AC)

0...50 A (AC)

0...100 A (AC)

0...200 A (AC)

0...400 A (AC)

0...600 A (AC)

0...5 A (AC), 0...50 A (AC)

0...100 A (AC)

0...200 A (AC)

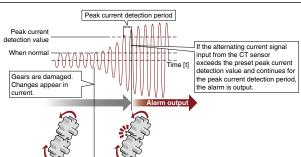
0...400 A (AC)

0...600 A (AC)

#### Peak current detection function

 The device can be serviced and troubleshooting performed by detecting the peak current.
 With a motor for example, the load applied on the motor is changed by the gear wear and damage, and the load current

suddenly changes. The device trouble can be diagnosed by detecting the transient peak current at this time.



#### Input signal error detection function

Connectable CT sensors

Mode

EMU-CT50

EMU-CT100

EMU-CT400

EMU-CT600

CTF-5A

CTF-50A

CTF-100A

CTF-200A

CTF-400A

CTF-600A

CTL-10-3FC

CTL-16-3FC

CTL-24-3FC

CTL-36-6SC

CTT-36-9SC

• Over-range (peak value over) of the CT input value can be detected. Since the flow of a large current exceeding the range of the measurement target can be detected, errors in the measurement target can be monitored.

Input range setting	Detection level
05 A (AC)	Approximately 6.25 A (AC)
050 A (AC)	Approximately 62.5 A (AC)
0100 A (AC)	Approximately 125 A (AC)
0200 A (AC)	Approximately 250 A (AC)
0400 A (AC)	Approximately 500 A (AC)
0600 A (AC)	Approximately 750 A (AC)

Manufacturer

Mitsubishi

Corporation

Measuring

Instruments

(introduced

U.R.D. Co.,

(introduced

products)

Ltd.

products)

Co., Ltd.

Electric

Multi

#### Returns to Over-range Alternating current wa occurrence the measurement range Peak value Current value from the CT Input range measurement range Time Peak value ----Sampling cycle ON Input signal error detection flag OFF ON ON Conversion completed flag **IOFF** Value before the Value returned to Digital output value over-range occurrence the measurement range ON Error clear request OFF OFF

#### 42

### Simple motion module for positioning control and synchronous control.

### Advanced control but simple use as the positioning module

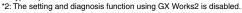
Speed/torque control and synchronous control are supported in addition to the traditional positioning control. Using the "simple motion module setting tool", operations such as positioning setting, monitoring and debugging can be performed easily. In addition, data synchronized with the motion controller can be collected and displayed in waveform.

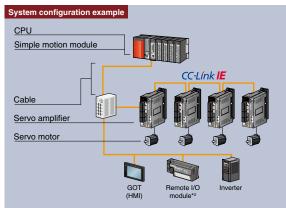
#### • Simple motion module

#### CC-Link IE Field Network connection type ------QD77GF

The in the above model indicates the number of axes (4, 8, 16).

The simple motion module supports the general purpose CC-Link IE Field Network, with its flexible wiring. This module can be used as the CC-Link IE Field's master station\*1 while retaining the simple motion module's functions. This realizes flexible networking supporting connection to various devices such as GOT(HMI), remote I/O, inverter, etc. \*1: QD77GF4, QD77GF8, QD77GF16 master station transmission style can use the line type or star type. Up to 104 slave devices can be connected to one network.



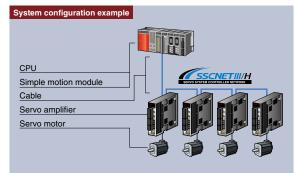


		QD77GF4	QD7	77GF8	QD77GF16	
Maximum number of control axes		4-axes	8-6	axes	16-axes	
Servo amplifier connection method			CC-Link IE Field Network			
Maximum	distance between stations		100 m			
Control system			ntrol, path control (both linear and arc can be set), speed control, speed/position switching control, ed switching control, speed-torque control, synchronous control, electronic cam control			
	1-axis linear control					
	1-axis speed control					
	2-axis linear interpolation control	_				
	2-axis circular interpolation control		Operation cycle	Starting time		
Starting	2-axis speed control		0.88 ms	1.77 ms		
time	3-axis linear interpolation control		1.77 ms	3.55 ms		
	· · · · · · · · · · · · · · · · · · ·		3.55 ms	7.11 ms		
	3-axis speed control					
	4-axis linear interpolation control					
	4-axis speed control					

#### SSCNET II/H connection type ------QD77MS

The 
in the above model indicates the number of axes (2, 4, 16).

The SSCNET  ${\rm I\!I}/{\rm H}$  connection reduces wiring, enables connections of up to 100 m between stations, and easily supports absolute position settings. The upper limit LS, lower limit LS, and near-point dog signals can be input from the servo amplifier, thus greatly reducing wiring. In addition to positioning control and speed control, processes such as synchronous control and electronic cam control can be performed. High compatibility with conventional models, projects and sequence programs for the positioning module (QD75MH) can be used easily in the simple motion module (QD77MS) projects.



		QD77MS2	QD77MS4	QD77MS16			
Maximum number of control axes		2-axes	2-axes 4-axes				
Servo amp	lifier connection method	SSCNET II/H					
Maximum o	distance between stations	100 m					
Control sys	tom	PTP (Point to Point) control, path	PTP (Point to Point) control, path control (both linear and arc can be set), speed control, speed/position switching control,				
Control Sys	sterri	position/speed switching control, speed-torque control	ol (press-fit control), synchronous control, electronic ca	m control, torque control, tightening & press-fit control			
	1-axis linear control						
	1-axis speed control		0.88 ms				
	2-axis linear interpolation control	0.88 ms					
o:	2-axis circular interpolation control						
Starting time	2-axis speed control			1.77 ms			
uno	3-axis linear interpolation control						
	3-axis speed control						
	4-axis linear interpolation control	]					
	4-axis speed control						

### A large selection of motion control solutions are available to fit any motion application.

### High-speed, accurate positioning control

Various types of motion control are supported including 2 to 4-axis linear interpolation, 2-axis circular interpolation, speed control, speed/ position changeover, path control and constant speed control. Making settings (including positioning data), monitoring, and debugging is made much easier using GX Works2's built-in intelligent function module tools or the stand-alone tool, GX Configurator-QP. For servo control, Q Series leverages the benefits of SSCNET, a Mitsubishi high performance motion control network. This allows Mitsubishi intelligent digital servos to be connected by a simple daisy chain cable that reduces cost and increases performance.

#### • Positioning module

The  $\square$  in the above model indicates the number of axes (1, 2, 4).

Using SSCNET III optical cables minimizes the required wiring, permits distances of up to 50 m between stations, and is highly resistant to EMI/RFI. This format is also compatible with absolute position systems where the home position is established by a home position return data setting operation. Using the CN3 connection, limit switches and proximity DOG inputs can be made directly to the servo amplifier, greatly reducing the required wiring.

		QD75MH□	
Servo amplifier connection method		SSCNET II	
Max. distance	between stations	50 m	
Control system		PTP (Point To Point) control, path control (both linear and arc can be set), speed control, speed-position switching control, position-speed switching control	
	1-axis linear control	3.5 ms	
	1-axis speed control	3.5 ms	
	2-axis linear interpolation control	4.0 ms	
	2-axis circular interpolation control	4.0 ms	
Starting time <sup>*1</sup>	2-axis speed control	3.5 ms	
	3-axis linear interpolation control	4.0 ms	
	3-axis speed control	3.5 ms	
	4-axis linear interpolation control	4.0 ms	
	4-axis speed control	4.0 ms	

\*1: Using the pre-reading start function, the actual starting time can be shortened.

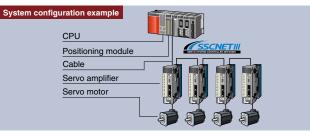
#### Positioning module

Open collector pulse train o	output type	.QD75P⊡N
Differential driver pulse train	n output type	.QD75D⊡N
	The  in the above model indicates	the number of axes (1, 2, 4).

For compatibility with the widest range of motion hardware, both open collector and differential driver type positioning modules are available. Transmission of high-speed pulses, up to 4 Mpps, to a servo amplifier can be made reliably up to 10 meters away. These pulse train output positioning modules can provide a high level of speed and accuracy for practically any application.

		QD75P⊡N	QD75D⊡N	
Pulse train output format		Open collector output	Differential drive output	
Max. output pulse		200 kpps	4 Mpps	
Max. connection	distance to drive unit	2 m	10 m	
Control system		PTP (Point To Point) control, path control (linear arc, and helical can be set), speed control, speed-position switching control, position-speed switching control		
	1-axis linear control	1.5	ms	
	1-axis speed control	1.5	ms	
	2-axis linear interpolation control	1.5	ms	
	2-axis circular interpolation control	2.0 ms		
	2-axis speed control	1.5 ms		
Starting time"2	3-axis linear interpolation control	1.7 ms		
	3-axis helical interpolation control	2.6 ms		
	3-axis speed control	1.7 ms		
	4-axis linear interpolation control	1.8 ms		
	4-axis speed control	1.8 ms		

\*2: Using the pre-reading start function, the actual starting time can be shortened.



rt

\_ r2

#### Application example > Sealing

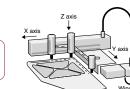
Function

Constant speed pass

control

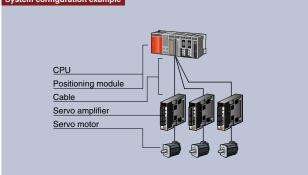


interpolation



■ High-speed, high-accuracy pass control

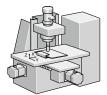
### System configuration example



#### Application example > X-Y table control

#### Function

- 2-axis linear interpolation
- 3-axis linear interpolation
- 2-axis circular interpolation
- Constant speed pass control
- 3-axis helical interpolation



44

### The ideal solution for simple multi-axis positioning

These modules are ideal for high-speed linear positioning control in a multi-axis system. Easily satisfying the requirements for simple positioning control applications, these modules include functions, such as positioning control, speed control and variable positioning control.

#### Positioning module

#### 

The  $\Box$  in the above model indicates the number of axes (8, 16).

Control up to 16-axes with a single module. The long list of functions includes positioning to an arbitrary position, incremental feed control, location control, a high-speed operating cycle, SSCNET II connectivity, electronic gears, backlash compensation, absolute position system, and linear interpolation of up to 4-axes.

		QD74MH□		
Servo amplifier connection method		SSCNET II		
Max. distance between stations		50 m		
Control system		PTP (Point To Point) control, path control (linear only)		
	1-axis linear control			
Starting	2-axis linear interpolation control	0.88 ms		
time	3-axis linear interpolation control	0.00 ms		
	4-axis linear interpolation control			

#### System configuration example

System configuration example

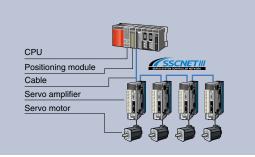
Positioning module

Servo amplifier

Stepper motor Servo motor Linear motor

CPU

Cable



### Positioning module

The  $\Box$  in the above model indicates the number of axes (4, 8).

These modules are a great match for stepper motor control. Acceleration and deceleration can be performed smoothly with very fine changes in speed. "Fast start processing" is a basic feature that allows for a single axis positioning start time of just 0.1 ms.

		QD70P	QD70D	
Pulse trair	n output format	Open collector output	Differential drive output	
Max. outp	ut pulse	200 kpps	4 Mpps	
Max. connection distance to drive unit		2 m 10 m		
Control system		PTP (Point To Point) control, path control (linear only), speed-position switching control		
o:	1-axis start	0.1 ms		
Starting time	4-axis simultaneous start*1	0.2 ms		
ume	8-axis simultaneous start*1	0.4 ms		

\*1: When START signal switches ON within 1 scan. There are no start delays between axes.

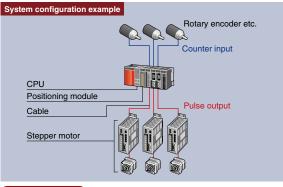
### Positioning control using encoder feedback ideal for conveyor systems and processing machines

#### • Positioning module with built-in counter function

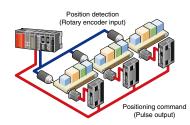
Open collector pulse train output type ...... QD72P3C3

This module combines counter inputs and pulse outputs for 3-axes in a single module to save space and reduce cost. Several useful functions such as 3-axis simultaneous start, target speed change, and coincidence detection are available.

			QD72P3C3
	Number of axes		3-axes
	Pulse train out	tput format	Open collector output
	Max. output p	ulse	100 kpps
Positioning control	Control system		PTP (Point To Point) control, speed control
control		1-axis start	1 ms
	Start time	3-axis simultaneous start	1 ms
	Number of channels		3 channels
		Phase	1-phase input, 2-phase input
Counter	Count input	Signal level	18 mA at 5 V DC, 26 mA at 24 V DC
function	signal	Pulse input	1 multiple of 2 phases, 2 multiple of 2 phases, 4 multiple of 2 phases, CW/CCW
	Counting speed (max.)		100 kpps



Application example 
Conveyor position control



### A selection of high-speed counter modules and pulse counter module for accuracy intensive, high resolution control applications is available.

#### Pulse input modules capable of high-speed counting

<ul> <li>High-speed</li> </ul>	l counter	module
--------------------------------	-----------	--------

Standard typeQD62, QD62	E, QD62D
Multi-channel high-speed counter module	QD63P6
4 Mpps compatible high-speed counter module	QD64D2
Multi-function counter/timer module	QD65PD2

Inputs may be connected to a variety of devices for positioning control, precision measurement, etc. The maximum counting speed may be adjusted via parameter (excluding QD64D2) for more reliable counting at lower frequencies.

- » External coincidence output (QD64D2 includes 2 per channel): Select coincidence output, continuous comparison (QD64D2 only), or the coincidence detection interrupt function for flexible high-speed external device control.
- » Many functions are available to satisfy application requirements including the coincidence output test function (QD64D2 only), latch counter function (excluding QD63P6), and preset function.
- » Calculate pulses at speeds up to 8 Mpps (4 multiples of 2 phases). Perform precise position tracking using a high-resolution encoder for demanding applications such as semiconductor and LCD manufacturing. (QD65PD2)

System configuration example	
CPU High-speed counter module Cable	Counter input Rotary encoder or other input

		QD62 (DC input sinking output type)	QD62E (DC input sourcing output type)	QD62D (differential input sinking output type)	QD63P6 (DC input)	QD64D2 (DC input, sink output type)	QD65PD2 (DC/Differential input, external output termina	als)	
Number of ch	annels		2 channels		6 channels	2 channels	2 channels		
	Phase			1-	phase input, 2-phase in	put, CW/CCW			
Count input signal	Signal level	5/12/24 V DC 25 mA		EIA Standard RS- 422-A Differential line driver level (AM26LS31 [manufactured by Texas Instruments] or equivalent)	5 V DC 6.411.5 mA	EIA Standard RS- 422-A, differential line driver level (AM26LS31 (manufactured by Texas Instruments Incorporated) or equivalent)	[Differential input] EIA Standards RS-422-A, differential line driver level (AM26LS31 [manufactured by Texas Instruments] or equivalent) [DC input] 5/12/24 V DC, 710 mA		
	Pulse input		1-phase			e input (x1, x2), CW/CCW, 2-phase (x1, x2, x4)			
Counting spe	ed (max.)	200	kpps	500 kpps	200 kpps	4 Mpps	[Differential input]8 Mpps [DC input]20	)0 kpps	
Function		Linear counter funct Ring counter function Coincidence output Preset function	on ·Count disa function ·Sampling	ter function ble function counter function alse counter function	Linear counter function     -Ring counter function     -Coincidence detection     function     -Preset function     -Perset function     -Periodic pulse counter     function	Linear counter function     -Ring counter function     -Coincidence detection     function     -Continuous comparison     function     -Preset function     -Latch counter function	Linear counter function Ring counter function Coincidence output function Cam switch function Preset/replace function Cam switch function Preset/replace function Counter function Counter function Pulse measurement fu Sampling counter function Periodic pulse counter function Count disable/preset/ Count disable/pre	nction	

Multi-function counter/timer module (QD65PD2) Perform extremely accurate position tracking! Multiple functions designed for ease of use! Counting speed up to 8 Mpps (4 multiples of 2 phases) Pulse measurement function With a resolution of 100 ns, it is possible to perform highly accurate pulse measurement. PWM output function Precisely control PWM output up to 200 kHz. With a resolution of 0.1 µs, superfine control of the duty cycle is possible. Cam switch function Configure up to 16 cam settings and use up to 8 dedicated outputs. The cam switch function enables highly accurate timing control Perform sophisticated control using coincidence detection! The coincidence output function allows complex applications to be supported. Depending on the situation, either the cam switch function or the coincidence output function can be used.

#### Channel isolated pulse input module QD60P8-G

This module is appropriate for the measurement of input pulse counts (related to speed, revolution, instantaneous flow rate, etc.) and the measurement of guantities (length, cumulative flow, and so forth). The QD60P8-G operates on a 10 ms control cycle, thus the minimum value refresh time is 10 ms. The count cycle setting can be changed to the desired time for cumulative count values and moving average pulse counts (sampling pulse counts).

		QD60P8-G					
Number of channels		8 channels					
	Phase	1-phase input					
Count input signal	Signal level	5 V DC/1224 V DC, ≥ 4 mA					
Signal	Pulse input	1-phase pulse input					
Counting speed (max.)		30 k/10 k/1 k/100/50/10/1/0.1 pps					

# Power measuring and insulation monitoring modules for easily measuring various energy information

#### Rack installation type energy measuring module

- Energy measuring module (three-phase 4-wire product)...... QE81WH4W
- Energy measuring module (multi-circuit, three-phase 4-wire product) ... QE83WH4W

Using only one module, highly detailed information about electric energy (consumption and regeneration), reactive energy, current, voltage, electric power, power factor, and frequency can be measured. Minimum and maximum values are constantly monitored and 2 types of upper/lower limit warnings can be implemented without any programming. The amount of electric power used by output devices only while ON can be measured.

The power rate during device operation and the power rate in takt units can be retrieved. The multi-circuit product allows power to be measured in a smaller space as up to four circuits can be measured with a three-phase 3-wire product in one slot, and up to three circuits with a three-phase 4-wire product. For example, one unit can be used to measure other loads from the control panel trunk.

In addition, the parameters can be set easily with GX Works2 (Version 1.91 V and higher).

				l i i				
Ν	Nodel	QE81WH	QE84WH*1	QE81WH4W	QE83WH4W*1			
Phase v	vire system	Single-phase 2-v 3-wire/three-		Three-phase 4-wire*2				
			V AC common , three-phase 3-wire)	63.5/110 V AC.	277/490 V AC			
=	Voltage circuit	110 V AC (1 - 2 line, 2 - 3 line) 220 V AC (1 - 3 line) (single-phase 3-wire)						
strume		Using two-stage configuration in combination with commercially-available voltage transformer (VT). Primary voltage value can be set up to 6,600 V.						
Instrument rating	Current circuit	50, 100, 250, 400, 600 A AC (Using dedicated split type current sensor. Each value indicates current sensor's primary current value.)						
Ð		5 A AC (Using dedicated 5 A current sensor. 5 A current sensor is used with two-stage configuration in combination with current transformer (CT). Primary current value can be set up to 6,000 A.)						
	Frequency	50/6	60 Hz (frequency	automatically judged)				
Number measure	of ement circuits	1 circuit	4 circuits	1 circuit	3 circuits			
Measurement items		rate, period pow voltage, power,	reactive power ver rate, current,	Power rate (consumption, regenerative), reactive power rate, period power rate, current, voltage, power, reactive power, apparent power rate, power factory, frequency				
*1: Curr	1: Current measurement mode is provided. Up to eight circuits can be measured							

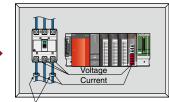
\*1: Current measurement mode is provided. Up to eight circuits can be measured when measuring only the current value.
\*2: The separate voltage transformer (QE8WH4VT) is required for the three-phase

4-wire compatible products.

#### Minimal impact on control panel layout

• By installing the energy measuring module onto the open slot of the base unit, measuring instrument can be added without changing the layout in the control panel.

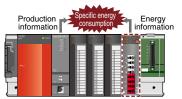




Current sensors

#### Allows for detailed power measurement at high speed (250 ms)

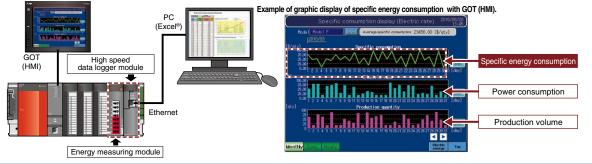
- Allows for easy specific energy consumption<sup>3</sup> management by matching the "production information" of the CPU module with the "energy information" of the energy measuring module.
- Since measured data is automatically collected in a buffer memory at 250 ms, detailed specific energy consumption management is also available.



\*3: The specific energy consumption is a numerical value displayed by "dividing energy consumption by production volume," which is one type of index that measures energy productivity. Improving this number leads to improved productivity and energy conservation.

#### Allows for easy construction of a "visualization" system

- Allows for easy graphic display of specific energy consumption with a GOT (HMI) installed on the control panel at the manufacturing site.
- Combination with the "high-speed data logger module (QD81DL96)" allows specific energy consumption analysis to be easily performed with a personal computer.



#### Insulation monitoring module measuring leakage current

#### Insulation monitoring module ......QE82LG

Leakage current can be measured for safety measures. Risks of electric shock are detected by monitoring leakage current (lo).

The isolated state of equipment can be constantly monitored.

The resistive leakage current (lor) is measured to constantly monitor the deterioration of equipment insulation.

Two-stage warning is provided for each measurement item. Two-stage warning for each of leakage current (Io) and resistive leakage current (Ior) can be issued via program-less communication. The two-stage warning function can be used to give a warning for calling for attention and a hazard warning.

One module can monitor two circuits. One module can monitor two circuits of power supplies of the same phase/wire type on the same system.

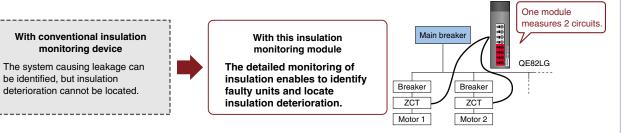
In addition, the parameters can be set easily with GX Works2 (Version 1.91V and higher).

#### Measurement items

Leakage current (Io) and resistive leakage current (Ior)



- The structure directly connected to programmable controller in the control panel saves space and facilitates measurement of leakage current in places close to loads.
- Failures caused by leakage (earth fault) and insulation of motor loads in production equipment can be monitored. Progression of insulation deterioration is not overlooked.
- The upper limit warning monitor can be set in two stages. Insulation deterioration and condition can be observed at an early stage, so that preventive measures can be taken before production equipment suddenly stops or goes down.



#### lor method realizes constant monitoring of insulation deterioration of equipment

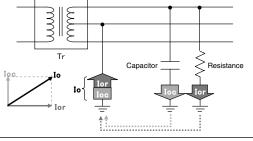
• With the conventional systems, such as inverter circuits with large capacitive leakage current (loc), it has difficulty for insulation monitoring.

The module is capable of measuring resistive leakage current (lor), and removes the capacitive leakage current then monitors the accurate leakage current caused by insulation deterioration.

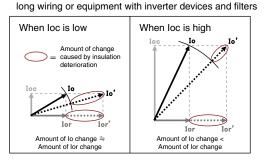
• Resistive leakage current (lor) is constantly measured even during operation of equipment. Signs of insulation deterioration can be detected without power interruption.

#### Leakage current (lo) is affected by capacitive leakage current (loc) of entire equipment. Therefore, resistive leakage current (lor) measurement is effective in diagnosis of insulation deterioration.

#### Method of measuring leakage current (lo measurement and lor measurement)



Ior: Leakage current caused by insulation deterioration (resistive component in the leakage current) Ioc: Leakage current (capacitive component of leakage current) flowing even if insulation is in good condition to: Leakage current obtained by synthesizing lor and Ioc (vector synthesis)



Capacitive leakage current (loc) fluctuates in equipment with

	Mo	del	Details	
Phase/wire type			Common to single-phase 2-wire and single-phase 3-wire/three-phase 3-wire types	
		Single-phase 2-wire Three-phase 3-wire	Common to 110 V AC and 220 V AC	
Instrument ratings	Voltage circuit*1*2	Single-phase 3-wire	110 V AC (between wires 1 and 2, between wires 2 and 3), 220 V AC (between wires 1 and 3)	
	Leakage	current circuit	1 A AC (ZCT is used. Primary current of ZCT)	
	Frequen	су	50/60 Hz (automatic discrimination of frequency)	
Number of c	ircuits whi	ch can be monitored	2 circuits*3	

- \*1: The module can be connected directly to 110-V and 220-V power supplies. To connect to a 440-V power supply, an external voltage transformer (VT) is necessary. Leakage current cannot be measured if voltage input is not provided.
- 2: Resistive leakage current (lor) can be measured on single-phase 3-wire and three-phase 3-wire delta circuits. On special circuits, such as three-phase 3-wire star circuits, high-resistance grounding circuits and capacitor grounding circuits. On lo can be measured.
- \*3: Leakage current (lo, lor) measurement on CH1 and CH2 can be performed only on circuits on the same system as the voltage input.



Software

## **MELSOFT** integrated FA software increases productivity by combining tools for development, maintenance, and operation of Q Series systems

Automation has brought tremendous productivity benefits to industrial and commercial applications. By creating the MELSOFT integrated FA software family of products, Mitsubishi Electric is aiming to bring similar productivity benefits to system designers, automation engineers, operators, and maintenance personnel. MELSOFT engineering tools are undergoing continuous evolution in order to meet the demands of new technologies and applications.

> For further details, please refer to the "iQ Platform

Controller Engineering Software MELSOFT GX Works2" catalog

### Programmable Controller Engineering Software

#### **GX Works2**



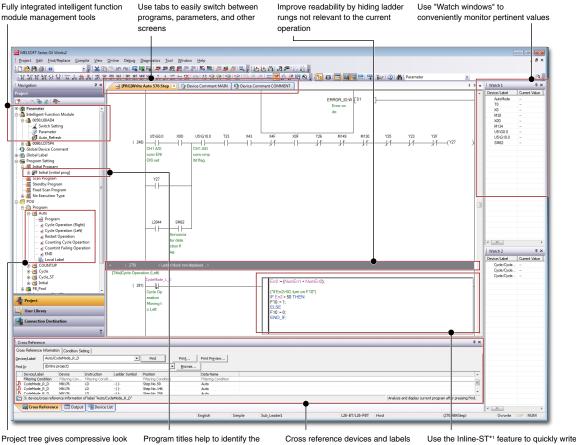
GX Works2 focuses on driving down total cost by including features that speed up commissioning, reduce downtime, improve programming productivity, and provide strong security.



L(NA)08122E

#### User interface that is "easy to use" by design

The programming tool GX Works2 has been developed from the ground up to be intuitive for all users and allow anyone to begin programming easily. The user interface and other functions provide a comfortable programming environment that enables improvements in design efficiency.



at flow of information in program and structure

content of each program

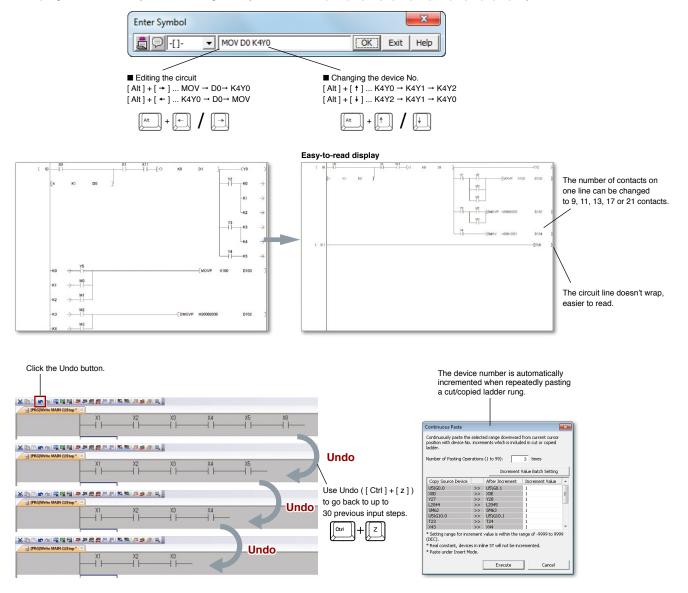
with ease

complex expressions in ladder programs

\*1 In-line ST can be only be created in projects that use labels

#### • Easily create circuits with few key inputs

The program can be easily modified using the keyboard shortcut [Alt] + [ $\leftarrow$ ] / [ $\rightarrow$ ] or [Alt] + [ $\uparrow$ ] / [ $\downarrow$ ] keys.



#### • Efficiently edit lines with keyboard

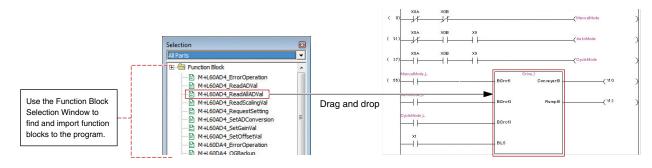
Ladder rungs can be easily modified just by using the various keyboard shortcut keys, eliminating the need to switch to editing mode.

(YI (YI	< > >	
Input line with $\boxed{\operatorname{Cerl}} + \boxed{\operatorname{+}}$ or $\boxed{\operatorname{Cerl}} + \boxed{\operatorname{+}}$ Input lines up to coil in batch with $\boxed{\operatorname{Cerl}} + \boxed{\operatorname{csslit}} + \boxed{\operatorname{+}}$ (Batch input lines in a vertical direction with $\boxed{\operatorname{Cerl}} + \boxed{\operatorname{csslit}} + \boxed{\operatorname{+}}$ )	■ H Pre: at a Pre: on t	ess ( an e ess (
(MC	>	

■ How to input a line Press [ Ctrl ] + [ → ] or [ Ctrl ] + [ ↓ ] at an empty spot. Press [ Ctrl ] + [ → ] or [ Ctrl ] + [ ↓ ] on top of a line to delete it.

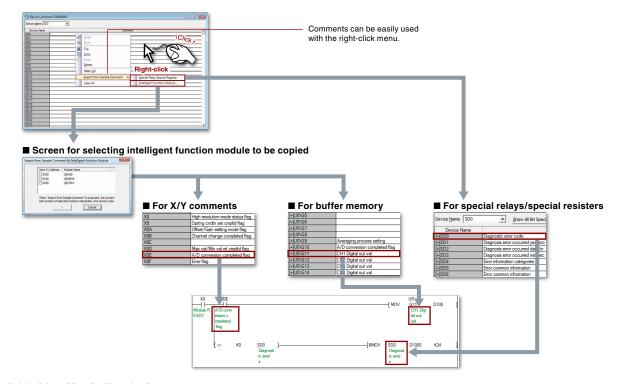
#### Use function blocks for common operations

Function blocks allow selections of commonly used code to be easily reused and shared among projects. Shared or created function blocks can be added to a program using simple drag and drop operation. Using function blocks effectively results in faster development times with fewer programming mistakes.



#### • Use sample comments to eliminate the need to input comments

Sample comments are provided for the CPU's special relays/registers and the intelligent function module's buffer memory/XY signals. These can be copied into the project's comments thus greatly reducing the time required for entering device comments.



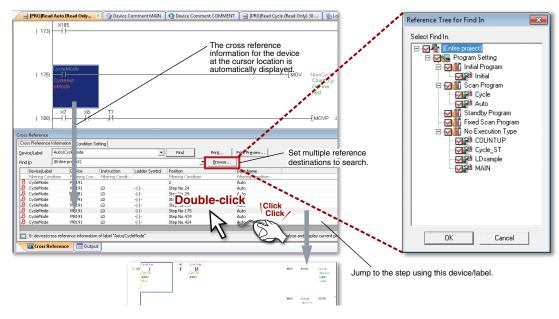
#### Quickly identify similar devices

Word device comments can be registered per bit with the contents displayed directly on the ladder rung.



#### • Cross referencing interlinked with circuit displays

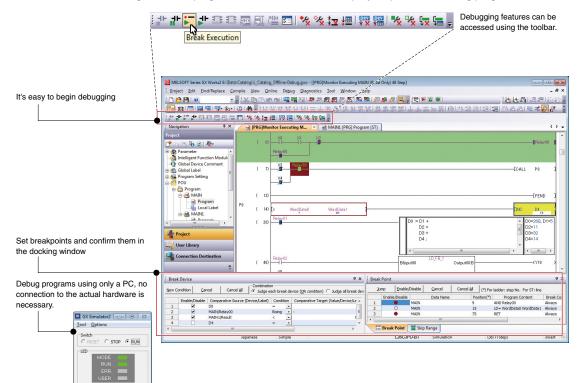
Relevant devices and labels can be searched within the contents of the program by using the cross reference tool. The results are immediately displayed in the cross reference dialog box conveniently besides the actual program view screen. It is then very easy to check where the relevant device is actually used within the program, just by double clicking on the target device.



#### Offline debug without physical hardware Function

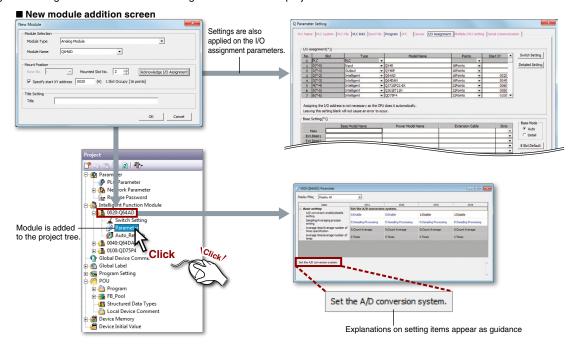


The simulation function is now integrated. The program can be executed in a step-by-step method, finding program errors more easily.



#### Integrating the intelligent function module setting tool (GX Configurator)

The intelligent function module's setting functions have been unified with GX Works2. Manage the intelligent function module's setting with a GX Works2 project.

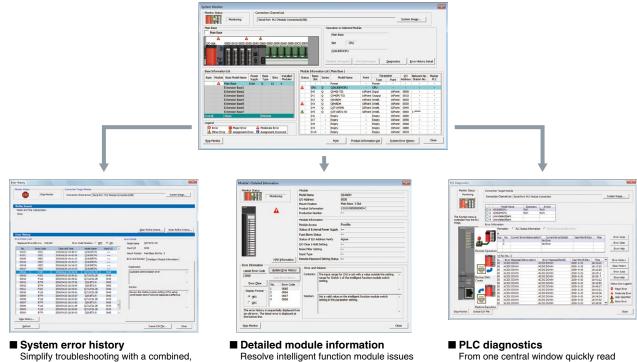


GX Configura

Function

#### • Visible System monitor function and PLC diagnostics

Operation status of the entire programmable controller system is clearly displayed. Each module's diagnosis and detailed information is displayed on the monitor for the entire system allowing the problem point to be confirmed quickly.



 Simplify troubleshooting with a combined,
 Hesolvi

 time-stamped, error history list for CPUs
 quickly

 and intelligent function modules.
 this fun

 The details section provides explanations
 to the n

 of error codes and suggested solutions.
 error codes

Resolve intelligent function module issues quickly by clicking on a module to open this function. All of the information relevant to the module is displayed here including error codes, their description, and possible solutions.

error and status information, export log

operations like reset, stop, CPU memory

files to CSV, perform remote CPU

format, and more.

53



#### Time-stamped error history list

Simplify troubleshooting with a combined, time-stamped, error history list for the CPU and all expansion modules. The details section provides explanations of error codes and suggested solutions.

Status GTD	Stop Monitor	Connection Cha	LC Module Connectio	001/580	System Image	Displayed Error	s/Errors: 123/12	23 Error Co	de Notation: 🔿 DE	C 🖲 HEX
						No. 7	Error Code	Date and Time	Model Name	Start I/O
iearch										
of the cri	teria below					00060	B782	2009/10/08 18:14:17	QJ61BT11N	0110
					1 mm	00059	7D13	2009/10/08 17:53:06	QJ71C24N-R2	00F0
						00058	7D16	2009/10/08 17:52:32	QJ71C24N-R2	00F0
lony					Gear Refine Criteria Enter Refine Criteria	00057	05DC	2009/10/08 16:14:09	Q26UDEHCPU	
ry List					Error Dobals	00056	7D12	2009/10/08 16:00:53	QJ71C24N-R2	00F0
	Errors: 123/123	Error Ca	de Notation: C DE	C F HEX	Hodel Name L3638T11	00055	7D16	2009/10/08 15:56:40	QJ71C24N-R2	00F0
7 3	Error Code	Date and Time	Model Name	Start L/O	Start I/O 0110					
9	0792 7D13	2009/10/08 18:14:17 2009/10/08 17:53:06	QJE10T11N QJ71C24N-R2	0110	Hount Position Hain block 1th slot	00054	7D16	2009/10/08 15:50:24	QJ71C24N-R2	00F0
8	7D15	2009/10/08 17:52:32	QJ71C24N-R2	00F0	Error and Solution Intelligent Module Information	00053	7D16	2009/10/08 14:59:03	QJ71C24N-R2	00F0
	050C 7D12	2009/30/08 36: 14:09 2009/30/08 36:00:53	Q26UDEHCPU QJ71C24N-R2	0070		00052	7D12	2009/10/08 14:43:27	QJ71C24N-R2	00F0
5	7D15	2009/10/08 15:56:40	QJ71C24N-R2	00F0	Explanation	00051	7D12	2009/10/08 14:35:53	QJ71C24N-R2	00F0
3	7D16 7D16	2009/30/08 15:50:24 2009/30/08 14:59:03	GJ71C24N-R2 GJ71C24N-R2	00F0	Station number specification error. The transmission destination and source stations were the same when	00050	7FF2	2009/10/08 14:35:02	QJ71C24N-R2	00F0
2	7D12	2009/10/08 14:43:27	QJ71C2NN-R2	0070	other station connection was specified.					
0	7012 7FF2	2009/10/08 14:35:53 2009/10/08 14:35:02	GJ71C24N-R2 GJ71C24N-R2	00F0		00049	1005	2009/10/08 14:03:44	Q26UDEHCPU	10000
9	1005	2009/10/08 14:03:44	Q26UDEHOPU		Solution	00048	7F42	2009/10/08 13:37:00	QJ71C24N-R2	00F0
8	7F42 0C21	2009/10/08 13:37:00 2009/10/08 13:13:56	QJ71C24N-R2 Q28UEFHCPU	00F0	Check the transmission destination station number, or change to host connection.	00047	0C21	2009/10/08 13:13:56	Q26UDEHCPU	
6	0834	2009/10/08 13:12:40	Q26UDEHOPU			00046	0834	2009/10/08 13:12:40	Q26UDEHCPU	
	05DC 7F42	2009/10/08 13:11:51 2009/10/08 12:04:52	Q26UDEHOPU QJ71C2HN-R2	0050		00045	05DC	2009/10/08 13:11:51		
3	0840	2009/10/08 11:43:17	Q28UDEHOPU	-					Q26UDEHCPU	
	0840	2009/10/08 11:41:01	Q26UDEHCPU			00044	7F42	2009/10/08 12:04:52	QJ71C24N-R2	00F0
fistory						00043	0840	2000/10/09 11.42.17	OBSUDELLODU	
effesh	12				Create CSV [He	00042	0840	Explanation		
						······ ·		Station number specifica destination and source s other station connection	stations were the sar	
								Solution		
								Check the transmission of change to host connection		umber, or 🔺
					Quickly ide	ntify the error, its cause, a	nd solution			

#### Save, edit labels and parameters with Microsoft<sup>®</sup> Excel<sup>®</sup>

Various program data can be exported in CSV file format.

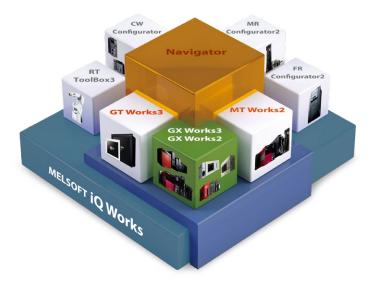
- Exporting to CSV format has various advantages, as shown below:
  - Data can be utilized on a personal computer even if GX Works2 is not installed
  - Data can be saved directly on the personal computer
  - Data can be sent and utilized off-site
  - Utilization of data for creating documents and graphs are possible using Excel®
  - Can use in other software that support CSV format

#### ■ Example of I/O assignment setting CSV file

#### I/O assignment setting

10 Accounter(1)         10           10         300           1001         3002           4003         5400           10         10	Intelligent Intelligent Intelligent Intelligent Intelligent		i 69 vinits i 69 vinits i 69 vinits i 69 vinits i 69 vinits i 69 vinits		Select PLC type     Select PLC type     New Module	× L × P × V × S × V × S p n	erification re	D assig /Y assig sults e functi / device or diagr nation, l nistory.	gnment setti gnment con ion e/label list nostics, PLC diagno	ing, Infirmation	Write n) Write Write Write Write	/Read I (CSV file /Read	format that can be read	with GX LogViewer
A	В	C	D E	F	G	Н	Ι	J	К	L	M	N	0	
4 0(0-0)	Intelligent	16	0 Q64AD	Clear	Stop		34616 -		598				Base Model Name	
5 1(0-1)	Intelligent	16	16 Q64AD	Clear	Stop		52 -						Q312B	
6 2(0-2)	Intelligent	16	32 Q64AD	Clear	Stop								Power Model Name	
7 3(0-3)	Intelligent	16	48 Q64DAN	Clear	Stop								Q61 P	
8 4(0-4)	Intelligent	16	64 QD75P4	Clear	Stop								Extension Cable	
9					·									
10													Slots	
11													5	
12														
I/O assig	nment		Α	dvanced	l setting		Switch setti	na					Basic setting	1

### iQ Works



# MELSOFT iQ Works

### Next Generation Integrated Engineering Environment

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, GX Works2, MT Works2, GT Works3, RT ToolBox3, FR Configurator2, CW Configurator and MR Configurator2. The

advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.

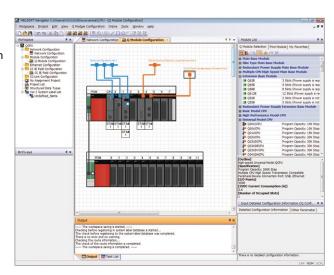
> For further details, please refer to the "Mitsubishi iQ Platform Compatible FA Integrated Engineering Software MELSOFT iQ Works" catalog.



#### L(NA)08232ENG

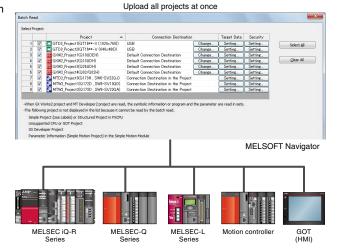
#### Graphical project management

The entire control system is represented using the "Network Configuration", "Module Configuration" and field network configuration windows. System components are easily added using a drag & drop interface, and the validity of the system can be confirmed using the check function to ensure parameters are configured correctly, the power supply is sufficient, etc. Different programmable controller and GOT (HMI) projects can be grouped together (for example by factory, line, and cell) for central management.



#### Read project data for multiple devices in a batch

Multiple projects can be read as a block just by having one connection to the programmable controller. If there are multiple devices such as other CPU or GOT (HMI) on the same network as the target master programmable controller, it is possible to upload all projects to each target device without having to individually connect to each device.

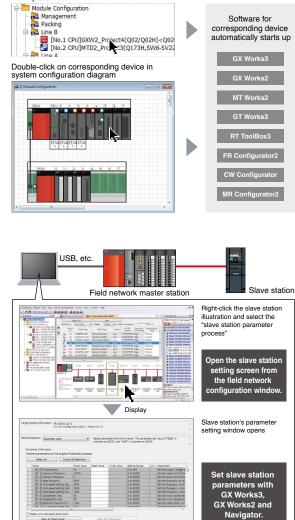


55

#### • Automatically start up the relevant maintenance software with a single click

Just double-click on the corresponding project in the system configuration diagram or workspace tree to automatically startup the software relevant for that device. Maintenance can be efficiently performed without having to know and startup each relevant software manually.

#### Double-click on corresponding project in workspace tree



#### Set up field network slave stations

There's no need to prepare a dedicated tool to check or change the parameter settings of a slave station on-site. The latest version of iQ Works includes slave station setting utility. Inverter parameters, for example, can be confirmed or changed for speed adjustment directly from the field network configuration window. In addition, error information can be read easily.

#### CC-Línk

CC-Link

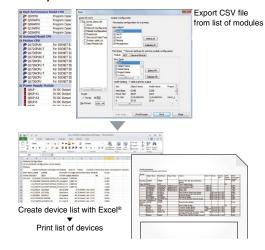
Ethernet

**AnyWireASLINK** 

#### • Prepare a device from the system configuration diagram with no manual inputs

A list of modules used can be exported as a CSV file from the system configuration diagram.

This is particularly useful when utilizing data for creating a bill of materials (BOM) in Excel®, etc.



Get error information

### **GX LogViewer**



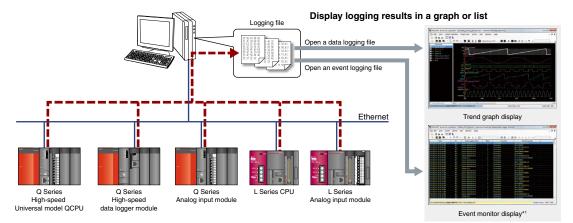
# **GX LogViewer**

### Visualizing the production process

Within modern manufacturing needs, data collection has become more important for fully optimizing the production process. GX LogViewer is a software tool that realizes visualization of large amounts of production data in a simple to use format. Utilizing this functionality to identify root error causes and improving the production rate.

#### • Easily display and analyze large amounts of collected logging data

This tool is used when large amounts of data need to be visualized and collected from the MELSEC-Q Series or MELSEC-L Series. The connection settings and checking of log files are the same as GX Works2 enabling individual connections to each module.

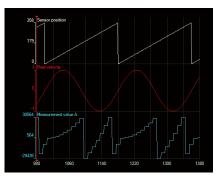


\*1: The event monitor display is supported only with the Q Series high-speed logger module.

#### • Easily adjust graphs without referring to the setup manual

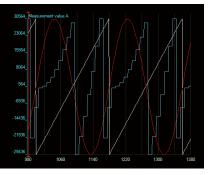
#### Arranging graphs

Able to arrange each graph so as not to overlap each other. It is easier to display the graphs as each graph is evenly spaced out.

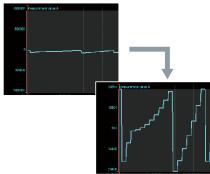


#### Overlapping graphs

With this it is possible to overlap each graph over one another. Multiple graphs can be compared enabling easier data analysis and comparison.



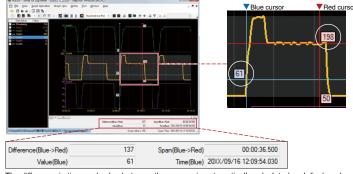
Automatically adjusting graphs Various attributes of the graph are automatically adjusted (max/min values) as to display the upper and lower limit values better.







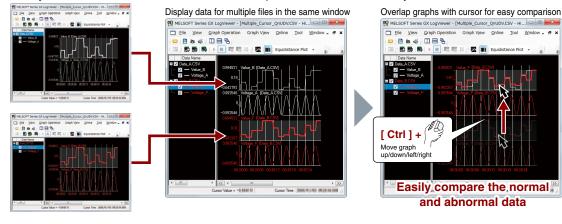
Data changes within a designated time frame can be quickly checked with user-friendly dual cursors (multicursors). When the cursors are moved to the point at which changes are to be confirmed, the difference in time and value between those points will appear.



The difference in time and value between the cursors is automatically calculated and displayed.

#### • Display data for multiple files within one graph area for easy comparison

Data for multiple files are displayed with the same time units in the same graph area. The display position within a file can be moved easily. This allows the differences of data within multiple files to be confirmed easily.



#### • Quickly jump cursor to designated position

Cursor jump

Confirm data values by quickly moving the cursor to a designated value, time or index position in the trend graph.



lect condition alue Time	s for jump cursor.
File Name	HSDL1_Q.csv
Data Name	Data5
Jassification	Conditional
Value Range	0 to 4294967295

/alue Time Ind	imp cursor. ex
File Name HSE	DL1_Q.cav
Time Range	
2011/03/31 11:4	6:43 to 2011/03/31 11:48:22
Date and time to w	hich the cursor jumps
✓ Date	
2011/03/31	
U Hour	Minute Second
11 💌	47 🔹 33 💌
Select a cursor that j	unps

Value search

Values are searched, and the cursor jumps to the position where the conditions match.

Time designation The cursor jumps to the designated time.

Select conditions for jump c Value Time Index	ursor.	
File Name HSDL1_0	ý.cev	
Index Range		
1 to 100		
Index to which the cure 51	or jumps	
Select a cursor that jumps Bed Cursor	Blue Cursor	

Index designation The cursor jumps to the designated index.



**MELSEC** Safety

# The concept of safety is shifting from "zero accidents" to "zero risk"

For further details, please

refer to the "Safety

The safety concept has shifted from human intervention based "zero accidents" to risk assessment based "zero risk". To meet the accompanying needs of this shift, Mitsubishi Electric has introduced MELSEC Safety programmable controller to realize safety control compatible with established MELSEC programmable controller. MELSEC Safety provides a comprehensive safety control solution.



L(NA)08192E



MELSEC Safety realizes visualization of safety information, realizing optimal safety control, and boosting productivity. The safety components such as Safety programmable controller, Safety controller, and Safety relay module provide a total safety solution.

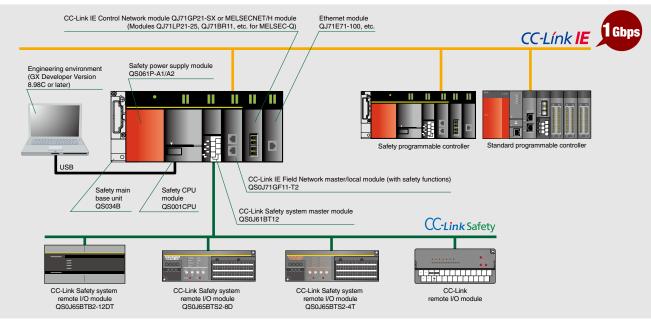
#### Safety Programmable Controller MELSEC-QS Series

#### Safety CPU\*1-------QS001CPU

The safety programmable controller is a programmable controller dedicated to safety control, conforming to international standards such as ISO13849-1 PL e and IEC 61508 SIL 3. When connected with a safety device, such as an emergency stop switch or light curtain, this programmable controller executes safety control by turning the safety output OFF with a user-created sequence program to stop movement toward a source of hazard, such as a robot.

Machine control of the robot and conveyor, etc., is executed with a standard programmable controller in the conventional manner. The difference between the safety programmable controller and general-purpose programmable controller lies in that if the safety programmable controller itself fails, it performs a self-diagnosis to detect the failure and turn the safety output OFF forcibly. This CPU branches topology using the CC-Link Safety and CC-Link IE Field Network with safety communication function. This is ideal for large control systems requiring many safety I/O points.

\*1: The CPU cannot be installed on the Q Series base unit

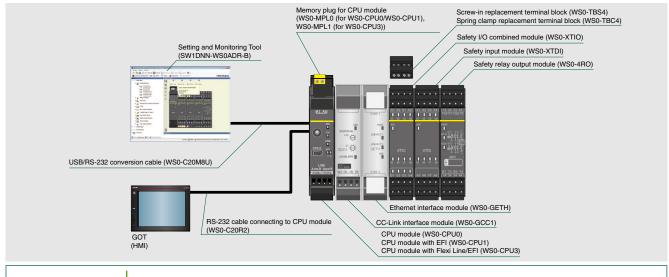


### **MELSEC-WS Series Safety Controller**

### 

The safety controller is a controller dedicated to safety control, conforming to international standards such as ISO13849-1 PL e and IEC 61508 SIL 3. The MELSEC-WS is ideal for small to medium-size safety machines and systems. I/O points of up to 144 (no redundancy) and up to 2 network interfaces and the dedicated Setting and Monitoring Tool, which contains safety sensor/switch connections and function blocks, all support the configuration of a safety system.

\*1: The CPU cannot be installed on the Q Series base unit.





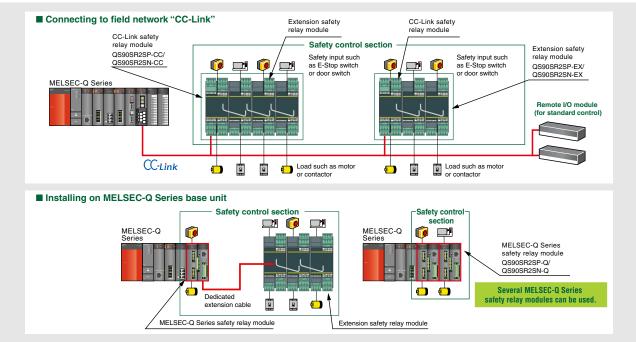
The MELSEC-WS Series is jointly developed and manufactured by Mitsubishi Electric and SICK SICK AG, a company based in Germany, is a manufacturer of safety related products and solutions. SICK designs and manufactures a broad range of safety products including industrial-use sensors and automatic identification systems.

### **MELSEC-QS Series Safety Relay Modules**

Extension safety relay module .....

• Q Series safety relay module......QS90SR2SP-Q, QS90SR2SN-Q QS90SR2SP-EX, QS90SR2SN-EX

The safety relay module integrates the emergency stop circuit and the restart circuit with a double safety relay. A basic safety function can be realized with just wiring, eliminating the need for programming and parameter settings. Furthermore, the number of I/O points can be increased by adding extension modules.





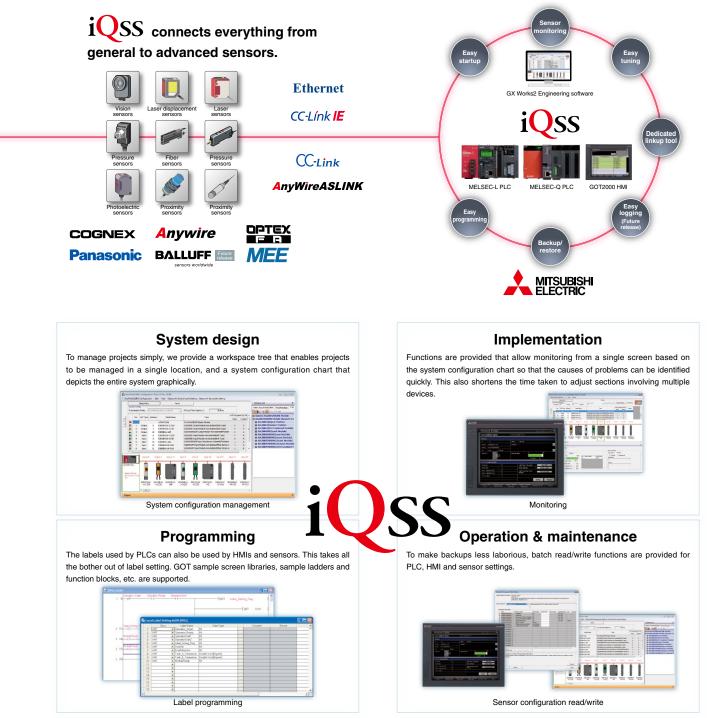
### iQ Sensor Solution

# A tool for connecting! Visualizing! For a more seamless sensor control!

Sensors used on the manufacturing floor are becoming more intelligent and complex, requiring even more maintenance of equipment and the overall management of various configuration setup software. With iQSS, the intelligent sensor solution provided by Mitsubishi Electric, configuration and maintenance of sensors are further simplified with the connectivity to other components such as automation controllers, HMIs, and engineering software even further enhanced reducing the overall TCO\*.

For further details, please refer to the "iQ Sensor Solution" catalog.





Further simplifying the management of sensors in the control system



### **Vision Solution**

# COGNEX<sup>®</sup> machine vision system and Mitsubishi Electric FA devices innovating your production with this integral power a contra

Functioning as devices that "watch" instead of human eyes, COGNEX machine vision systems have continued to reform automation of production lines. Mitsubishi Electric FA devices, such as programmable controllers, lead the future of automation.

The possibilities of vision system solutions, created in the integration of this spirit of innovation, have continued to increase.



L(NA)08230E

For further details, please refer to the Vision System and Factory Automation Solution" catalog.

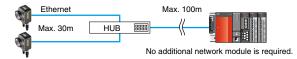
#### COGNEX In-Sight EZ Series iQSS ready! Device partner

• Entry model	EZ-700
Standard model	EZ-720
High-speed processing model	EZ-740
High resolution model	EZ-742

### Simple connection

#### **Directly connect with Ethernet**

The "In-Sight EZ" can be directly connected to the Ethernet port provided on the "MELSEC-Q Series universal model" and "MELSEC-L" programmable controller, and to the Ethernet interface module on the MELSEC-F. By using a switching hub, a multi-unit vision system having units installed as far as 100 m away can be created.



### Simple communication with SLMP

Now that "In-Sight EZ" supports SLMP, data can be easily written from the vision system to the programmable controller. Communication is easily configured with "EasyBuilder". Just select the connected device and SLMP, set the programmable controller device used for communication and select the communication data from the list. With the SLMP scanner mode, a trigger can be applied on the vision system via SLMP.

#### Simple control with function blocks (FB)

Intuitively setup the vision control system from the GX Works2 programming tool utilizing dedicated vision function blocks without having to develop specific programming code.

COGNEX DataMan<sup>®</sup> Barcode Reader Device partner

• Fixed DataMan ......DataMan 50/60/300 • Hand-held DataMan ...... DataMan 8050/8100/8500

#### DataMan - active in various industries









- ▶ Unmatched read rate performance with Hotbars™
- Proprietary Hotbars™ technology
- Solid state design with no moving parts
- Easy setup with three position adjustable lens and integrated lighting aimer
- IP65-rated housing (DataMan 50)
- Supports SLMP (DataMan 60)

#### Fixed DataMan 300 Series

- ► Unprecedented read rate with Hotbars<sup>™</sup>
- Reads the most difficult-to-read 2-D Direct Part Mark (DPM) codes
- Liquid lens with automatic variable focus
- Intelligent tuning
- Integrated lighting module
- Supports SLMP



#### Hand-held DataMan 8050/8100/8500 Series

- ▶ UltraLight<sup>®</sup>: Two types of lighting enable optimum reading\*1
- Newly developed body enhances sturdiness
- Standard automatic focus adjustment function\*2
- Supports SLMP
- Cordless capability
- (up to 30 m communication range)
- ► Unprecedented read rate with Hotbars<sup>™</sup>
- \*1· DataMan 8500
- \*2: DataMan 8100 and 8500



DataMan 8500









DataMan 300





Contactors and Motor Starters

# Diverse variations to respond to all situations

The Mitsubishi Electric Contactors and Motor Starters MS-T and MS-N series and DC interface contactor SD-Q series products are equipped with an environment and global compliance, compact size, ease-of-use and safety. Certification to various international standards, this highly reliable magnetic contactor is suitable for a variety of applications from panels to systems. L(N)02031

For further details.

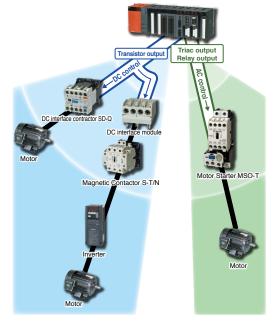
please refer to the

"Mitsubishi Electric

Magnetic Starters

MS-T/N Series"

catalog.



### Direct drive with Programmable Controller

MS-T, MS-N, and SD-Q series have small operating coil VA. This means these contactors, especially the SD-Q, are operable with 24 V DC 0.1 A transistor outputs without amplifier relays.

$ullet$ Connectable $\bigcirc$ Connectable with some restrictions $-$ Not connectable							
		Programmable controller output module type					
		Transistor output	Transistor output Contact output				
DC interface contactor SD-Q Series	DC operation	•	٠	_			
Magnetic contactor	AC operation	(Using DC interface module)	٠	0			
MS-T Series	DC operation	0	0	_			
Magnetic contactor	AC operation	(Using DC interface module)	•	0			
MS-N Series	DC operation	0	_	_			

\*: This table shows the relation of the programmable controller output module type and operation interface. There may be restrictions according to the type of frame size, etc., that can be used. Refer to the MS-T/N Series Catalog, or contact a Mitsubishi dealer or Sales Office for details on the types of magnetic contactors and models that can be used.

### SD-Q series

Direct drive is possible with the programmable controller's transistor output. Since a relay and interface module are not required, the number of parts can be reduced, and space can be saved.

### Standard surge absorber

Prevent adverse effects onto the peripheral equipment.

### Standard terminal cover

A terminal cover with finger protection function is installed as a standard. This cover answers to user's needs for safety.

### MS-T series (10A to 100A)

Mitsubishi Electric's main series is equipped with a small size, ease-of-use, safety and international compliance. This series greatly contributes to smaller panels, easier selection and compliance with international standards.

### 10A frame model is just 36 mm wide!!

The industry's smallest width\*1 has been realized for the general-purpose magnetic contactor.

The other rated products have also been downsized to help you reduce your panel size.

\*1: 10A frame general-purpose magnetic contactor (Mitsubishi Electric survey as of Feb. 2016)



### Wide range of operation coil ratings!!

The wider operation coil rating ranges allow us to consolidate the number of coil types from 14 types (N Series) to 8 types.

This helps reduce stock and makes it easier to select the required type.

### Standard terminal cover!!

The standard terminal cover\*<sup>2</sup> improves the safety in the panel, and simplifies ordering as a separate model no longer needs to be specified.

\*2: Applicable frame is 10A to 50A

Specifications



General specifications indicate the environmental specifications in which this product can be installed and operated. Unless otherwise specified, the general specifications apply to all products of the Q Series. Install and operate the Q Series products in the environment indicated in the general specifications.

Item	Specification										
Operating ambient temperature			05	55℃							
Storage ambient temperature	–2575℃ <sup>×1</sup>										
Operating ambient humidity		595% RH* <sup>2</sup> , non-condensing									
Storage ambient humidity	595% RH* <sup>2</sup> , non-condensing										
			Frequency	Constant acceleration	Half amplitude	Sweep count					
	Compliant with JIS B 3502 and IEC 61131-2	Under intermittent vibration	58.4 Hz	-	3.5 mm (0.14 inches)	10 times each in					
Vibration resistance			8.4150 Hz	9.8 m/s²	-	X, Y, Z directions					
		Under continuous vibration	58.4 Hz	-	1.75 mm (0.069 inches)						
			8.4150 Hz	4.9 m/s²	-						
Shock resistance	Co	mpliant with JIS B 35	02 and IEC 61131-2	(147 m/s², 3 times e	ach in directions X, Y	Y, Z)					
Operating atmosphere			No corros	ive gases							
Operating altitude*3			≤ 2000 m	(6562 feet)							
Installation location			Inside a co	ontrol panel							
Overvoltage category*4			≤	Ι							
Pollution level*5			≤	2							

Class I

Equipment class

Class 1
 C

# **CPU Module Performance Specifications**

#### **Universal model QCPU**

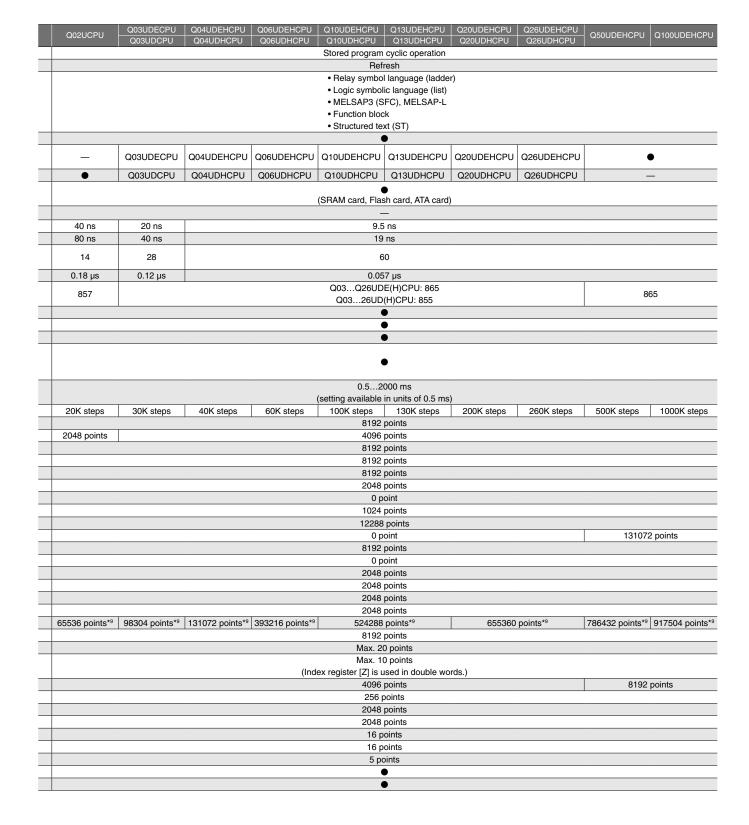
			_							
	Item	Q03UDVCPU	Q04UDVCPU	Q06UDVCPU	Q13UDVCPU	Q26UDVCPU	Q00UJCPU	Q00UCPU	Q01UCPU	
Control method					Stored program	cyclic operation				
I/O control mode	е				Ref					
Program langua (sequence contr	-									
	USB*1									
Peripheral connection port	Ethernet (100BASE-TX/10BASE-T)			•			_			
	RS-232			_				•		
Memory card int	terface		(SD Memory	● y Card, SDHC Me	mory Card)*2			_		
Extended SRAM	A cassette port			•				_		
	LD instruction			1.9 ns			120 ns	80 ns	60 ns	
	MOV instruction			3.9 ns			240 ns	160 ns	120 ns	
Processing	PC MIX value*4						1.00	=	0.70	
speed*3	(instruction/µs)			227			4.92	7.36	9.79	
	Floating point addition			0.014 µs			0.42 µs	0.30 µs	0.24 µs	
Total number of				859			821		55	
Floating point in	struction							1		
	processing instruction					_				
PID instruction	processing instruction									
Special function	instruction									
•	unction, square root,									
exponential ope					•					
				0.5 0000				0 5 0000		
Constant scan		0.5…2000 ms (setting available in units of 0.1 ms)								
	ning regular scon time)		(aatting )		af 0.1 ma		(aatting a	0.52000 ms	of 0 E ma)	
(Function for kee	ping regular scan time)	20K stopp		available in units o	1	260K stops		vailable in units	1	
(Function for kee Program capaci	ty*6	30K steps	(setting a 40K steps		130K steps	260K steps			of 0.5 ms) 15K steps	
(Function for kee Program capaci Number of I/O d	ty*6 levice points [X/Y]	30K steps		available in units of 60K steps	130K steps	260K steps points	10K :	vailable in units o steps	15K steps	
(Function for kee Program capacit Number of I/O d Number of I/O p	ty <sup>*6</sup> levice points [X/Y] points [X/Y]		40K steps	available in units of 60K steps	130K steps 8192	points		steps 1024	1	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M	ty*6 levice points [X/Y] points [X/Y] 1]*7	30K steps 9216 points	40K steps	available in units of 60K steps	130K steps 8192 28672	points points	10K :	vailable in units o steps	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7	ty*6 levice points [X/Y] points [X/Y] 1]*7		40K steps	available in units of 60K steps	130K steps 8192 28672 8192	points points points	10K :	steps 1024	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Link relay [B]*7	ty*6 levice points [X/Y] points [X/Y] 1]*7		40K steps	available in units of 60K steps	130K steps 8192 28672 8192 8192	points points points points	10K :	steps 1024	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Link relay [B]*7 Timer [T]*7	ty* <sup>5</sup> levice points [X/Y] points [X/Y] 1]* <sup>7</sup>		40K steps	available in units of 60K steps	130K steps 8192 28672 8192 8192 2048	points points points points points	10K :	steps 1024	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M] Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer	ty* <sup>5</sup> levice points [X/Y] points [X/Y] 1]* <sup>7</sup>		40K steps	available in units of 60K steps	130K steps 8192 28672 8192 8192 2048 0 p	points points points points points oint	10K :	steps 1024	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M] Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7	ty* <sup>5</sup> levice points [X/Y] points [X/Y] 1]+7 [ST]*7		40K steps	available in units of 60K steps	130K steps 8192 28672 8192 8192 2048 0 p 1024	points po	10K :	vailable in units of steps 1024 8192 points	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M] Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D]	ty*5 levice points [X/Y] points [X/Y] []+7 [ST]*7		40K steps	available in units of 60K steps 4096 points 0 points 3 points	130K steps 8192 28672 8192 8192 2048 0 p	points po	10K :	vailable in units of steps 1024 8192 points 12288 points	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r	ty*5 levice points [X/Y] points [X/Y] []*7 [ST]*7 [ST]*7 ]*7 register [D]*7	9216 points	40K steps 15360	available in units of 60K steps 4096 points 0 points	130K steps 8192 28672 8192 8192 2048 0 p 1024 41984	points po	10K :	vailable in units of steps 1024 8192 points 12288 points	15K steps	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D Extended data r Link register [W]	ty* <sup>6</sup> levice points [X/Y] points [X/Y] ] <sup>*7</sup> [ST]* <sup>7</sup> [ST]* <sup>7</sup> ]* register [D]* <sup>7</sup>	9216 points	40K steps 15360	available in units of 60K steps 4096 points 0 points 3 points	130K steps 8192 28672 8192 8192 2048 0 p 1024 41984	points po	10K :	vailable in units of steps 1024 8192 points 12288 points	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [B]*7 Link relay [B]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re	ty* <sup>6</sup> levice points [X/Y] points [X/Y] 1]* <sup>7</sup> [ST]* <sup>7</sup> [ST]* <sup>7</sup> ] * <sup>7</sup> register [D]* <sup>7</sup> ] sgister [W]* <sup>7</sup>	9216 points	40K steps 15360	available in units of 60K steps 4096 points 0 points 3 points	130K steps 8192 28672 8192 8192 2048 0 p 1024 41984	points po	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D Extended data r Link register [W]	ty* <sup>6</sup> levice points [X/Y] points [X/Y] 1]* <sup>7</sup> [ST]* <sup>7</sup> [ST]* <sup>7</sup> ] * <sup>7</sup> register [D]* <sup>7</sup> ] sgister [W]* <sup>7</sup>	9216 points	40K steps 15360	available in units of 60K steps 4096 points 0 points 3 points 0 point	130K steps 8192 28672 8192 2048 0 p 1024 41984 8192	points po	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [B]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re	ty*6 levice points [X/Y] points [X/Y] [ST]*7 [ST]*7 [ST]*7 [sr] r7 [sr] r7 ] pister [D]*7 ] pister [W]*7 sr	9216 points	40K steps 15360	available in units of 60K steps 4096 points 0 points 3 points 0 point	130K steps 8192 28672 8192 2048 0 p 1024 41984 8192 8192 2048	points	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7	ty*6 levice points [X/Y] points [X/Y] [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 aggister [D]*7 ] aggister [W]*7 *7 *7 *7 *7 *7 *7 *7 *7 *7	9216 points	40K steps 15360	available in units of 60K steps 4096 points 0 points 3 points 0 point	130K steps 8192 28672 8192 2048 0 p 1024 41984 8192 8192 2048 2048	points	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7	ty*6 levice points [X/Y] points [X/Y] [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 [\$T]*7 aggister [D]*7 ] aggister [W]*7 *7 *7 *7 *7 *7 *7 *7 *7 *7	9216 points 13312 points	40K steps	available in units of 60K steps 4096 points 0 points 8 points 0 point 0 point	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048	points po	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special relation Link special relation	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           j*7           register [D]*7           ]           ggister [W]*7           *7           ister [SW]*7	9216 points 13312 points	40K steps	available in units of 60K steps 4096 points 0 points 3 points 0 point	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048	points po	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p 0 p	15K steps points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7 Link special rela Link special register [R,	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           j*7           register [D]*7           ]           ggister [W]*7           *7           ister [SW]*7	9216 points 13312 points	40K steps	available in units of 60K steps 4096 points 0 points 8 points 0 point 0 point	130K steps 8192 28672 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048 524288 points* <sup>6</sup>	points po	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p 0 p	15K steps points point point	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7 Link special relat Link special relat Link special relat Step relay [S]*7	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           j*7           register [D]*7           ]           ggister [W]*7           *7           ister [SW]*7	9216 points 13312 points	40K steps	available in units of 60K steps 4096 points 0 points 8 points 0 point 0 point	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048 2048 2048 204	points po	10K :	Ivailable in units of steps 1024 8192 points 12288 points 0 p 0 p	15K steps points point point	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7 Link special relag File register [R, Step relay [S]*7 Index register/sta	ty* <sup>6</sup> levice points [X/Y] points [X/Y] ] <sup>*7</sup> [ST]* <sup>7</sup> [ST]* <sup>7</sup> ] <sup>*7</sup> register [D]* <sup>7</sup> ] ggister [W]* <sup>7</sup> * <sup>7</sup> ay [SB]* <sup>7</sup> ister [SW]* <sup>7</sup> ZR] undard device register [Z]	9216 points 13312 points	40K steps	available in units of 60K steps 4096 points 0 points 8 points 0 point 0 point	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048 2048 2048 204	points po	10K :	Ivailable in units of steps 1024 8192 points 1024 12288 points 0 p 0 p 65536	15K steps points point point	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7 Link special relag File register [R, Step relay [S]*7 Index register/sta	ty*6 levice points [X/Y] points [X/Y] [ST]*7 [ST]*7 [ST]*7 [ST]*7 iegister [D]*7 ] gister [W]*7 ister [SW]*7 ister [SW]*7 ZR] undard device register [Z] 2]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 0 point 1 393216 points*8	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048 2048 2048 204	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1	15K steps points point point point point points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Timer [T]*7 Retentive timer   Counter [C]*7 Data register [D Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7 Link special rela Link special regist File register [R, Step relay [S]*7 Index register [Z (32-bit ZR index	ty*6 levice points [X/Y] points [X/Y] [ST]*7 [ST]*7 [ST]*7 [ST]*7 iegister [D]*7 ] gister [W]*7 ister [SW]*7 ister [SW]*7 ZR] undard device register [Z] 2]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points* <sup>6</sup> Max. 10 points	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048 2048 2048 204	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [B]*7 Link relay [B]*7 Retentive timer   Counter [C]*7 Data register [D] Extended data r Link register [M] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special rela Link special rela Link special rela Step relay [S]*7 Index register [Z (32-bit ZR index Pointer [P]	ty*6 levice points [X/Y] points [X/Y] [ST]*7 [ST]*7 [ST]*7 [ster [D]*7 ] points [X/Y] [ST]*7	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points*6 Max. 10 points ter [Z] is used in d	130K steps 8192 8192 8192 2048 0 p 1024 41984 8192 2048 2048 2048 2048 2048 2048 2048 204	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1 (Index register [Z] is	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay [L]*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special relay Link special relay File register [R], Step relay [S]*7 Index register [Z] (32-bit ZR index Pointer [P] Interrupt pointer	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           [stor [D]*7           ]*7           agister [D]*7           ]           agister [W]*7           *7           agister [W]*7           zR]           undard device register [Z]           z]           ting)	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points** Max. 10 points ter [Z] is used in di 4096 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048 2058	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay []*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [M] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special relay File register [R, Step relay [S]*7 Index register/Sta Index register [Z (32-bit ZR index Pointer [P] Interrupt pointer Special relay [S]	ty*6 levice points [X/Y] points [X/Y] [ST]*7 [ST]*	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points** Max. 10 points ter [Z] is used in di 4096 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay []*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special register Kile register [R, Step relay [S]*7 Index register [Z] Index register [Z] Ca2-bit ZR index Pointer [P] Interrupt pointer Special relay [S]	ty**6 levice points [X/Y] points [X/Y] [ST]*7 [ST]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points** Max. 10 points ter [Z] is used in di 4096 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay []*7 Link relay [B]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special relay [Nik special relay [S]*7 Index register [R, Step relay [S]*7 Index register [P] Interrupt pointer Special relay [S] Special relay [S]	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           [ster [D]*7           ]           gister [D]*7           jagister [W]*7           ster [SW]*7           ZR]           undard device register [Z]           zing)           [I]           [SD]           FX]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points** Max. 10 points ter [Z] is used in di 4096 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 16 p	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay []*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [M] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special relay [File register [R], Step relay [S]*7 Index register [Z] Notex register [Z] Pointer [P] Interrupt pointer Special relay [S] Special relay [S] Special relay [S]	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           [ster [D]*7           ]           gister [D]*7           ister [SW]*7           zR]           undard device register [Z]           z]           ining)           [SD]           FX]           [FY]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points** Max. 10 points ter [Z] is used in di 4096 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048 2048 2048 2048 2048 2048 2048 524288 points* <sup>8</sup> 8192 Max. 20 ouble words.) 2048 2048 2048 2048 2048	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points	0 points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M] Latch relay [L]*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended link re Annunciator [F]* Edge relay [V]*7 Link special relay [File register [R, Step relay [S]*7 Index register [Z] (32-bit ZR index Pointer [P] Interrupt pointer Special relay [S] Special relay [S] Special register Function input [I Function output Function register	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           [ST]*7           [ST]*7           [ster [D]*7           ]           gister [D]*7           ister [SW]*7           zR]           undard device register [Z]           z]           ining)           [SD]           FX]           [FY]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 0 point 1 393216 points*8 Max. 10 points ter [Z] is used in d 4096 points 256 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 2048 16 p	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points 128 points	15K steps points point point point point point point point points	
(Function for kee Program capaci Number of I/O d Number of I/O p Internal relay [M Latch relay []*7 Timer [T]*7 Retentive timer Counter [C]*7 Data register [D] Extended data r Link register [W] Extended dink re Annunciator [F]* Edge relay [V]*7 Link special relay [File register [R, Step relay [S]*7 Index register [Z] Index register [Z] Pointer [P] Interrupt pointer Special relay [S] Special relay [S] Special relay [S]	ty*6           tevice points [X/Y]           points [X/Y]           points [X/Y]           ]*7           register [D]*7           ]gister [D]*7           agister [D]*7           agister [W]*7           zgister [SW]*7           ister [SW]*7           zR]           undard device register [Z]           z]           (II]           M]           [SD]           FX]           [FY]           ar [FD]	9216 points 13312 points	40K steps 15360 22526 131072 points*8	available in units of 60K steps 4096 points 0 points 3 points 0 point 0 point 1 393216 points** Max. 10 points ter [Z] is used in di 4096 points	130K steps 8192 28672 8192 2048 0 p 1024 41984 2048 2048 2048 2048 2048 2048 2048 524288 points* <sup>8</sup> 8192 Max. 20 ouble words.) 2048 2048 2048 2048 2048	points po	10K :	vailable in units of steps 1024 8192 points 12288 points 0 p 0 p 0 p 65536 Max. 1 (Index register [Z] is 512 points 128 points	0 points	

\*1: The USB port terminal is mini-B.
\*2: The operation of devices that are not manufactured or recommended as compatible products by Mitsubishi Electric cannot be guaranteed.
\*3: The processing speed is the same even when the device is indexed.
\*4: The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1µs. A larger value indicates a higher processing speed.
\*5: Intelligent function module dedicated instructions are not included.
\*6: When the OnUD(H)(PCU or OnUDE(H)(PCU is replaced with the OnUDVCPU, the number of steps in the program may change (increase or decrease). For more information, refer to the relevant manual.
\*7: Indicates the number of points in the default state. This can be changed with the parameter.
\*8: Intelligent of points in the default state. This can be changed with the parameter.
\*8: Indicates the number of points in the default state. This can be increased with the extended SRAM cassette.
When using together with the extended SRAM cassette, the value obtained by totaling the number of points in the following table is the number of file registers that can be used.

 
 With Q4MCA-1MBS (1 MB)
 With Q4MCA-2MBS (2 MB)
 With Q4MCA-4MBS (4 MB)
 With Q4MCA-8MBS (8 MB)
 524288 points 1048576 points 2097152 points 4194304 points 

\*9: Indicates the number of points when using the built-in memory (standard RAM). This can be expanded with the SRAM card or Flash card. (Writing from the program is not possible with the Flash card.) Up to 4184064 points can be used with the SRAM card.





# **CPU Module Performance Specifications**

### **Basic model QCPU**

Control method Stored program cyclic operation Refresh Refres		Item	Q00JCPU	Q00CPU	Q01CPU			
I/O control mode       Petrash         Program language (sequence control language)       • Relay symbol language (ladder)         • Logic symbolic language (list)       • MELSAP3 (SFC), MELSAP-L         • Function block       • Structured text (ST)         Peripheral       USB       —         • Cognosting parts       MOV instruction       200 ns       160 ns       100 ns         MOV instruction       700 ns       560 ns       350 ns       950 ns         Processing       MOV instruction       700 ns       560 ns       350 ns         Post and the system       1.6       2.0       2.7         Floating point addition       65.5 µs       60.5 µs       49.5 µs         Folating point instruction       ●       ●         Character string processing instruction       ●       ●         Crastate sca       12000 ms (setting available in units of 1 ms)       Program capacity         Program capacity       8K steps       14K steps         Number of I/O points (X/Y)       256 points       1024 points         Number of I/O device points (X/Y)       2048 points       1024 points         Link relay [L]*       2048 points       1024 points         Link relay [L]*       2048 points       1024 points </td <td>Control metho</td> <td></td> <td></td> <td></td> <td></td>	Control metho							
• Relay symbol language (ladder)         Program language (sequence control language)       • Logic symbolic language (list)         • MELSAPS (SFC), MELSAPL • Function block       • Function block         • Structured text (ST)       • -         Peripheral connection port RS-232       •         Memory card interface          • Distruction       200 ns       160 ns       100 ns         Processing speed*'       LD instruction       700 ns       560 ns       350 ns         PC MIX value (instruction/sys)**       1.6       2.0       2.7         Floating point addition       •       •       •         PC MIX value (instruction       65.5 µs       60.5 µs       49.5 µs         Floating point addition       •       •       •         PID instruction       •       •       •         Special function instruction       •       •       •         Figure on this function instruction       •       •       •         Figeoinal device points [X/Y] <td< td=""><td></td><td></td><td>01</td><td></td><td></td></td<>			01					
Program language (sequence control language) Peripheral bonnection port RS-232 Memory card interface Processing speed*' LD instruction PC MIX value (instruction/us)* Floating point addition PC MIX value (instruction/us)* Floating point instruction PC MIX value (instruction/us)* Floating point addition PC MIX value (instruction/us)* Floating point addition PC MIX value (instructions* PC MIX value (instructions* PC MIX value (instructions* PC MIX value (instructions* PC MIX value (instructions* PC MIX value (instruction instruction Character string processing instruction PC mixtue Program capacity Number of I/O device points [XY] Number of I/O device points [XY] Number of I/O device points [XY] PC MIX PC MIX PC MIX PC MIX PC MIX PC MIX PC MIX PC MIX PC MIX PC MIX PC MIX		ue						
Program Language       • MELSAP3 (SFC), MELSAP-L         (sequence control language)       • Function block         • Function block       • Structured text (ST)         Peripheral       USB								
Image: sequence control language)              • Function block             • Structured text (ST)            Peripheral connection port [R5-232              •            Memory card interface	Program langu	lage			,			
Peripheral Denotection port IRS-232	(sequence con	ntrol language)			-L			
Peripheral connection port         USB								
connection port Memory card interface         -           Memory card interface         -           Processing speed*'         LD instruction         200 ns         160 ns         100 ns           MOV instruction         700 ns         560 ns         350 ns           Processing speed*'         MOV instruction         700 ns         560 ns         350 ns           PC MIX value (instruction/µs)*2         1.6         2.0         2.7           Floating point instruction         -         -         -           PC MIX value (instructions**         534         564         -           Floating point instruction         -         -         -           Trigonometric function, square root, exponential operation, etc.)         -         -         -           Constant scan (Function for keeping regular scan time)         12000 ms (setting available in units of 1 ms)         -           Program capacity         8K steps         14K steps         -           Number of I/O device points [X/Y]         256 points         1024 points         -           Internal relay [L]*5         2048 points         -         -         -           Latch relay [L]*5         2048 points         -         -         -           Counter [C]*5	Deriphoral	LICP	• 3					
Memory card interface         —           Processing speed*1         LD instruction         200 ns         160 ns         100 ns           Processing speed*1         MOV instruction         700 ns         560 ns         350 ns           PC MIX value (instruction/sp'*         1.6         2.0         2.7           Floating point addition         65.5 µs         60.5 µs         49.5 µs           Total number of instruction         —         —         —           Character string processing instruction         —         —         —           PID instruction         —         —         —         —           Special function instruction (Frigonometric function, square root, exponential operation, etc.)         —         —         —           Constant scan (Function for keeping regular scan time)         12000 ms (setting available in units of 1 ms)         #           Program capacity         8K steps         14K steps         14K steps           Number of I/O device points [X/Y]         256 points         1024 points           Link relay [L]*5         2048 points         1           Latch relay [L]*5         2048 points         1           Latch relay [L]*5         2048 points         1           Data register [D]*5         11136 points	•			-	-			
LD instruction         200 ns         160 ns         100 ns           MOV instruction         700 ns         560 ns         350 ns           Speed*1         PC MIX value (instruction/µs)*2         1.6         2.0         2.7           Floating point addition         65.5 µs         60.5 µs         49.5 µs           Floating point instruction         -         -         -           Character string processing instruction         -         -         -           Character string processing instruction         -         -         -           Special function instruction         -         -         -           Constant scan         -         -         -         -           Frogram capacity         8K steps         14K steps         Number of I/O points [X/Y]         2048 points         -         -           Number of I/O points [X/Y]         256 points         1024 points         -         -         -           Number of I/O points [X/Y]         256 points         1024 points         -         -         -           Number of I/O points [X/Y]         256 points         1024 points         -         -         -         -         -         -         -         -         -         -				•				
MOV instruction         700 ns         560 ns         350 ns           PC MIX value (instruction/µ5)*2         1.6         2.0         2.7           Floating point addition         65.5 µs         60.5 µs         49.5 µs           Total number of instruction*5*         534         564           Floating point instruction         •         •           Character string processing instruction         •**         •           Special function instruction         •         •           Crigonometric function, square root, exponential operation, etc.)         •         •           Constant scan         •         •         •           Program capacity         8K steps         14K steps           Number of I/O device points [X/Y]         2048 points         •           Number of I/O points [X/Y]         2048 points         •           Number of I/O points [X/Y]         2048 points         •           Internal relay [M]**         8192 points         •           Timer [T]**         2048 points         •           Counter [C]**         512 points         •           Data register [D]**         0 point         •           Counter [C]**         512 points         •           Data register [D	wemory card i	1	200 mg	160 m	100 m			
Processing speed*1         PC MIX value (Instruction/µs)*2         1.6         2.0         2.7           Floating point addition         65.5 µs         60.5 µs         49.5 µs           Total number of instructions*3         534         564           Floating point instruction         ●         •           Character string processing instruction         ●         •           Special function instruction         ●         •           Special function instruction         ●         •           Constant scan         ●         •           Function for keeping regular scan time)         ●         12000 ms (setting available in units of 1 ms)           Program capacity         8K steps         14K steps           Number of I/O points [X/Y]         2048 points         1024 points           Internal relay [M]**         8192 points         14K steps           Link relay [B]*5         2048 points         14K steps           Link relay [B]*5         2048 points         1           Counter [C]*5         512 points         1           Data register [D]*5         11136 points         2           Link register [D]*5         1024 points         2           Link special relay [SB]         1024 points         2 <td></td> <td></td> <td></td> <td></td> <td></td>								
speed**         [instruction/µs)*2         1.6         2.0         2.7           Floating point addition         65.5 µs         60.5 µs         49.5 µs           Total number of instructions**         534         564           Floating point instruction         •**           PD instruction instruction         •**           Special function instruction         •**           Constant scan         •           Floating point (KY)         •           Constant scan         •           Floating point (KY)         2048 points           Program capacity         8K steps         14K steps           Number of I/O device points [X/Y]         256 points         1024 points           Number of I/O device points [X/Y]         256 points         1024 points           Link relay [M]**         8192 points         1024 points           Link relay [B]*5         2048 points         1024 points           Link relay [L]*5         512 points         1024 points           Constart scan ([C]*5         512 points         11136 points           Link relay [L]*5         1024 points         11136 points           Link relay [L]*5         1024 points         11136 points           Link relay [L]*5         1024 points	Processing		700 ns	560 NS	350 ns			
Floating point addition         66.5 µs         60.5 µs         49.5 µs           Total number of instructions***         534         564           Floating point instruction         ●         ***           Character string processing instruction         ●**         ●           PID instruction         ●         ●           Special function instruction         ●         ●           Crigonometric function, square root, exponential operation, etc.)         ●         ●           Constant scan         ●         ●         ●           Program capacity         8K steps         14K steps           Number of I/O device points [X/Y]         2048 points         ●           Number of I/O points [X/Y]         256 points         1024 points         ●           Number of I/O points [X/Y]         256 points         1024 points         ●           Latch relay [L]*5         2048 points         ●         ●         ●           Link relay [B]*5         2048 points         ●	speed*1		1.6	2.0	2.7			
Total number of instructions*3       534       564         Floating point instruction <ul> <li>Character string processing instruction</li> <li>P1</li> <li>Special function instruction</li> <li>Special function instruction, square root, exponential operation, etc.)</li> </ul> <ul> <li>Constant scan</li> <li>Constant scan scan scan scan scan scan scan scan</li></ul>			05.5	00.5	10.5			
Floating point instruction <ul> <li>Character string processing instruction</li> <li>PID instruction</li> <li>Special function instruction</li> <li>(Trigonometric function, square root, exponential operation, etc.)</li> </ul> Constant scan              12000 ms (setting available in units of 1 ms)            Program capacity              8K steps               14K steps            Number of I/O device points [X/Y]              2048 points               1024 points            Number of I/O points [X/Y]              256 points               1024 points            Internal relay [M]*5               2048 points               11024 points            Link relay [B]*5               2048 points               11024 points            Counter [C]*5               2048 points               11024 points            Counter [C]*5               512 points               11136 points            Counter [C]*5               1024 points               1024 points            Link relay [N]*5               1024 points               1024 points            Link special relay [SB]								
Character string processing instruction PID instruction PID instruction Special function instruction (Trigonometric function, square root, exponential operation, etc.) Constant scan (Function for keeping regular scan time) Program capacity Number of I/O points [X/Y] 2048 points Number of I/O points [X/Y] 2056 points Number of I/O points [X/Y] 2048 points Link relay [B]*5 2048 points Link relay [B]*5 2048 points Link relay [B]*5 2048 points Link register [D]*5 2048 points Link special relay [SB] 2048 points 2048 point			534		64			
PiD instruction       •         Special function instruction       •         (Findometric function, square root, exponential operation, etc.)       •         Constant scan       12000 ms (setting available in units of 1 ms)         (Function for keeping regular scan time)       8K steps       14K steps         Program capacity       8K steps       14K steps         Number of I/O device points [X/Y]       2048 points       1024 points         Number of I/O points [X/Y]       256 points       1024 points         Internal relay [M]*5       8192 points       1024 points         Latch relay [L]*5       2048 points       1024 points         Link relay [B]*5       512 points       1024 points         Counter [C]*5       512 points       11136 points         Link register [D]*5       1024 points       2048 points         Link register [D]*5       1024 points       11136 points         Link register [D]*5       1024 points       1024 points         Edge relay [V]*5       1024 points       1024 points         Link special relay [SB]       1024 points       1024 points         Link special relay [S]       2048 points       2048 points         Link special relay [S]       2048 points       2048 points				-				
Special function instruction <ul> <li>Trigonometric function, square root, exponential operation, etc.)</li> <li>Constant scan</li> <li>Flunction for keeping regular scan time)</li> <li>Program capacity</li> <li>BK steps</li> <li>14K steps</li> </ul> Program capacity         8K steps         14K steps           Number of I/O device points [X/Y]         2048 points           Number of I/O points [X/Y]         256 points         1024 points           Latch relay [I]*5         8192 points         1024 points           Latch relay [I]*5         2048 points         2048 poin		<u> </u>		•				
Trigonometric function, square root, exponential operation, etc.)         I           Constant scan (Function for keeping regular scan time)         12000 ms (setting available in units of 1 ms)           Program capacity         8K steps         14K steps           Number of I/O device points [X/Y]         2048 points         1024 points           Number of I/O points [X/Y]         256 points         1024 points           Latch relay [L]*5         8192 points         1024 points           Latch relay [L]*5         2048 points         1024 points           Link relay [B]*6         2048 points         1024 points           Data register [ST]*5         0 point         6512 points           Data register [W]*5         2048 points         11136 points           Link register [W]*5         2048 points         1024 points           Link register [W]*5         2048 points         1024 points           Link register [W]*5         2048 points         1024 points           Link special relay [SB]         1024 points         1024 points           Link special relay [SB]         1024 points         1024 points           Link special relay [S]         2048 points         1024 points           Link special relay [SB]         1024 points         1024 points           Link special regi				•				
exponential operation, etc.)         Constant scan         (Function for keeping regular scan time)         Program capacity         8K steps         1/L2000 ms (setting available in units of 1 ms)         Program capacity         Number of I/O device points [X/Y]         2048 points         Number of I/O points [X/Y]         256 points         14K steps         Number of I/O points [X/Y]         256 points         1111	•							
Constant scan       12000 ms (setting available in units of 1 ms)         Program capacity       8K steps       14K steps         Number of I/O device points [X/Y]       2048 points       1024 points         Number of I/O points [X/Y]       256 points       1024 points         Internal relay [M]*5       8192 points       1024 points         Latch relay [L]*5       2048 points       1024 points         Latch relay [B]*5       2048 points       1024 points         Retentive timer [ST]*5       0 point       0 point         Counter [C]*5       0 point       11136 points         Link register [D]*5       11136 points       1024 points         Link register [W]*5       2048 points       1024 points         Counter [C]*5       11136 points       1024 points         Link register [W]*5       1024 points       1024 points         Link register [W]*5       1024 points       1024 points         Link special relay [SB]       1024 points       1024 points         Link special relay [SB]       1024 points       1024 points         Link special relay [S]       2048 points       1024 points         Link special relay [S]       2048 points       1024 points         Link special relay [SM]       1024 points				•				
(Function for keeping regular scan time)       12000 ms (setting available in units of 1 ms)         Program capacity       8K steps       14K steps         Number of I/O device points [X/Y]       2048 points       1024 points         Number of I/O points [X/Y]       256 points       1024 points         Internal relay [M]**       8192 points       1024 points         Latch relay [L]*5       2048 points       1024 points         Link relay [B]*5       2048 points       1024 points         Link relay [B]*5       2048 points       1024 points         Timer [T]*5       2048 points       1024 points         Retentive timer [ST]*5       0 point       0 point         Counter [C]*5       512 points       11136 points         Link register [D]*5       11136 points       11136 points         Link register [D]*5       1024 points       1024 points         Edge relay [V]*5       1024 points       1024 points         Link special relay [SB]       1024 points       1024 points         Link special register [R, ZR]       —       65536 points         Step relay [S]       2048 points       1024 points         Index register [Z]       10 points       1024 points         Pointer [P]       3000 points       1024								
[Function for keeping regular scan time]       8K steps       14K steps         Program capacity       8K steps       14K steps         Number of I/O points [X/Y]       256 points       2048 points         Internal relay [M]*5       8192 points       1024 points         Internal relay [M]*5       8192 points       1024 points         Latch relay [L]*5       2048 points       1024 points         Link relay [B]*5       2048 points       1024 points         Counter [T]*5       2048 points       1024 points         Retentive timer [ST]*5       0 point       0 point         Counter [C]*5       512 points       1024 points         Data register [D]*5       11136 points       1024 points         Link register [M]*5       2048 points       1024 points         Link register [M]*5       2048 points       1024 points         Link special relay [SB]       1024 points       1024 points         Link special relay [SH]       1024 points       1024 points         Step relay [V]*5       2048 points       1024 points         Link special relay [SB]       1024 points       1024 points         Step relay [S]       2048 points       1024 points         Index register [SD]       10 points       1024 points </td <td></td> <td></td> <td colspan="6">12000 ms (setting available in units of 1 ms)</td>			12000 ms (setting available in units of 1 ms)					
Number of I/O device points [X/Y]         2048 points           Number of I/O points [X/Y]         256 points         1024 points           Internal relay [I]*5         8192 points         1024 points           Latch relay [L]*5         2048 points         1024 points           Link relay [B]*5         2048 points         1024 points           Link relay [B]*5         2048 points         1024 points           Retentive timer [ST]*5         2048 points         1024 points           Counter [C]*5         512 points         1024 points           Data register [D]*5         11136 points         1024 points           Link register [M]*5         2048 points         11136 points           Link register [V]*5         1024 points         1024 points           Link special relay [SB]         1024 points         1024 points           Link special register [SW]         1024 points         1024 points           File register [R, ZR]         —         65536 points         1024 points           Index register [Z]         10 points         1024 points         1024 points           Index register [S]         2048 points         1024 points         1024 points           Index register [S]         2048 points         1024 points         1024 points         1024 po			, <b>e</b>					
Number of I/O points [X/Y]         256 points         1024 points           Internal relay [M]*5         8192 points         2048 points           Latch relay [L]*5         2048 points         2048 points           Link relay [B]*5         2048 points         2048 points           Timer [T]*5         2048 points         2048 points           Retentive timer [ST]*5         0 point         0 point           Counter [C]*5         512 points         0 point           Data register [D]*5         11136 points         2048 points           Link register [D]*5         11136 points         2048 points           Annunciator [F]*5         2048 points         2048 points           Annunciator [F]*5         1024 points         2048 points           Link special relay [SB]         1024 points         2048 points           Link special relay [SB]         1024 points         2048 points           Link special register [R, ZR]         —         65536 points           Step relay [S]         2048 points         2048 points           Index register [Z]         10 points         2048 points           Pointer [P]         300 points         2048 points           Interrupt pointer [I]         128 points         2048 points           Sp	• ·		8K s	14K steps				
Internal relay [M]*5 B192 points B192 points Latch relay [L]*5 Counter [C]*5 Bretentive timer [ST]*5 Data register [D]*5 Data register [D] Data register [SW] Data register [SW] Data register [Z] Data register [Z] Data register [Z] Data register [D] Data register [SD] Data register [SD] Data register [SD] Local device Data register [FD] Local device Data register [FD] Da					· · · ·			
Latch relay [L]*5         2048 points           Link relay [B]*5         2048 points           Timer [T]*5         512 points           Retentive timer [ST]*5         0 point           Counter [C]*5         512 points           Data register [D]*5         11136 points           Link register [D]*5         11136 points           Link register [D]*5         2048 points           Annunciator [F]*5         1024 points           Edge relay [V]*5         1024 points           Link special relay [SB]         1024 points           Step relay [S]         2048 points           Index register [R, ZR]         —           65536 points         1024 points           Interrupt pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Special relay [SM]         1024 points           Special relay [SM]         1024 points           Function input [FX]         16 points           Function register [FD]         5 points           Local device </td <td></td> <td></td> <td>256 points</td> <td></td> <td>points</td>			256 points		points			
Link relay [B]*5         2048 points           Timer [T]*5         512 points           Retentive timer [ST]*5         0 point           Counter [C]*5         512 points           Data register [D]*5         11136 points           Link register [D]*5         2048 points           Annunciator [F]*5         2048 points           Edge relay [V]*5         1024 points           Link special relay [SB]         1024 points           Link special register [SW]         1024 points           Link special register [Z]         0 points           Step relay [S]         2048 points           Index register [Z]         1024 points           Interrupt pointer [P]         300 points           Special relay [SM]         1024 points           Special relay [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points								
Timer [T]*5         512 points           Retentive timer [ST]*5         0 point           Counter [C]*5         512 points           Data register [D]*5         11136 points           Link register [M]*5         2048 points           Annunciator [F]*6         1024 points           Edge relay [V]*5         1024 points           Link special relay [SB]         1024 points           Link special register [SW]         1024 points           Step relay [S]         2048 points           Index register [R, ZR]         —           65536 points         Step relay [S]           Index register [Z]         10 points           Pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Function input [FX]         16 points           Function rupt [FY]         16 points           Function register [FD]         5 points								
Retentive timer [ST]*5       0 point         Counter [C]*5       512 points         Data register [D]*5       11136 points         Link register [M]*5       2048 points         Annunciator [F]*5       1024 points         Edge relay [V]*5       1024 points         Link special relay [SB]       1024 points         Link special register [SW]       1024 points         Step relay [S]       2048 points         Index register [R, ZR]       —         65536 points       Step relay [S]         Index register [Z]       10 points         Pointer [P]       300 points         Interrupt pointer [I]       128 points         Special relay [SM]       1024 points         Function input [FX]       16 points         Function output [FY]       16 points         Function register [FD]       5 points			•					
Counter [C]*5       512 points         Data register [D]*5       11136 points         Link register [W]*5       2048 points         Annunciator [F]*5       1024 points         Edge relay [V]*5       1024 points         Link special relay [SB]       1024 points         Link special register [SW]       1024 points         Link special register [SW]       1024 points         Step relay [S]       2048 points         Index register [Z]       00 points         Interrupt pointer [I]       128 points         Interrupt pointer [I]       128 points         Special relay [SM]       1024 points         Special relay [SM]       1024 points         Function input [FX]       16 points         Function register [FD]       5 points         Local device       —			•					
Data register [D]*5       11136 points         Link register [W]*5       2048 points         Annunciator [F]*5       1024 points         Edge relay [V]*5       1024 points         Link special relay [SB]       1024 points         Link special register [SW]       1024 points         Link special register [SW]       1024 points         Step relay [S]       2048 points         Index register [Z]       0 points         Pointer [P]       300 points         Interrupt pointer [I]       128 points         Special relay [SM]       1024 points         Special register [SD]       1024 points         Function input [FX]       16 points         Function register [FD]       5 points		r [ST]*⁵	•					
Link register [W]*5         2048 points           Annunciator [F]*5         1024 points           Edge relay [V]*5         1024 points           Link special relay [SB]         1024 points           Link special register [SW]         1024 points           Step relay [S]         1024 points           Step relay [S]         2048 points           Index register [R, ZR]         —           65536 points         65536 points           Step relay [S]         2048 points           Index register [Z]         10 points           Pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Special register [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points								
Annunciator [F]*5       1024 points         Edge relay [V]*5       1024 points         Link special relay [SB]       1024 points         Link special register [SW]       1024 points         File register [R, ZR]       —       65536 points         Step relay [S]       2048 points         Index register [Z]       10 points         Pointer [P]       300 points         Interrupt pointer [I]       128 points         Special relay [SM]       1024 points         Special relay [SD]       1024 points         Function input [FX]       16 points         Function output [FY]       16 points         Function register [FD]       5 points	• •	-						
Edge relay [V]*5       1024 points         Link special register [SW]       1024 points         Link special register [SW]       1024 points         File register [R, ZR]       65536 points         Step relay [S]       2048 points         Index register [Z]       10 points         Pointer [P]       300 points         Interrupt pointer [I]       128 points         Special register [SD]       1024 points         Function input [FX]       16 points         Function register [FD]       5 points         Local device       —			•					
Link special relay [SB] 1024 points Link special register [SW] 1024 points File register [R, ZR] 65536 points Step relay [S] 2048 points Index register [Z] 10 points Pointer [P] 300 points Interrupt pointer [I] 128 points Special relay [SM] 1024 points Special register [SD] 1024 points Function input [FX] 16 points Function output [FV] 16 points Function register [FD] 5 points Local device								
Link special register [SW]         1024 points           File register [R, ZR]         —         65536 points           Step relay [S]         2048 points           Index register [Z]         10 points           Pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Special relay [SD]         1024 points           Function input [FX]         16 points           Function output [FV]         16 points           Function register [FD]         5 points	• • • •		•					
File register [R, ZR]         —         65536 points           Step relay [S]         2048 points           Index register [Z]         10 points           Pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Special register [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points	· ·		1024 points					
Step relay [S]         2048 points           Index register [Z]         10 points           Pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Special register [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points	· · · · · · · · · · · · · · · · · · ·							
index register [Z]         10 points           Pointer [P]         300 points           Interrupt pointer [I]         128 points           Special relay [SM]         1024 points           Special register [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points		I, ZR]						
Pointer [P]       300 points         Interrupt pointer [I]       128 points         Special relay [SM]       1024 points         Special register [SD]       1024 points         Function input [FX]       16 points         Function output [FY]       16 points         Function register [FD]       5 points         Local device       —	Step relay [S]		2048 points					
Interrupt pointer [I] 128 points Special relay [SM] 1024 points Special register [SD] 1024 points Function input [FX] 16 points Function output [FY] 16 points Function register [FD] 5 points Local device —		[Z]	10 points					
Special relay [SM]         1024 points           Special register [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points           Local device         —	Pointer [P]		300 points					
Special register [SD]         1024 points           Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points           Local device         —			128 points					
Function input [FX]         16 points           Function output [FY]         16 points           Function register [FD]         5 points           Local device         —		-	1024 points					
Function output [FY]         16 points           Function register [FD]         5 points           Local device         —	Special registe	er [SD]		1024 points				
Function register [FD] 5 points Local device —	Function input	[FX]		16 points				
Local device —	Function output	ıt [FY]		16 points				
	Function regist	ter [FD]		5 points				
Device initial values	Local device			_				
	Device initial v	alues		•				

\*1: The processing speed is the same even when the device is indexed.
\*2: The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1 µs. A larger value indicates a higher processing speed.
\*3: Intelligent function module dedicated instructions are not included.
\*4: Character string can be used only when using the character string transfer instruction (\$MOV).
\*5: Indicates the number of points in the default state. This can be changed with the parameter.

Specifications



### **High Performance QCPU**

	Item	Q02CPU	Q02HCPU	Q06HCPU	Q12HCPU	Q25HCPU			
Control method	d	· · · · · ·		Stored program cyclic opera	tion				
I/O control mod	de			Refresh					
				Relay symbol language (la	adder)				
				Logic symbolic language (	list)				
Program langu	•			• MELSAP3 (SFC), MELSA	P-L				
(sequence con	itroi language)			Function block					
				<ul> <li>Structured text (ST)</li> </ul>					
Peripheral	USB	_		•					
connection por	rt RS-232			•					
Memory card in	nterface			(SRAM card, Flash card, ATA	card)				
	LD instruction	79 ns		34 ns					
	MOV instruction	237 ns		102 ns					
Processing	PC MIX value								
speed*1	(instruction/us)*2	4.4		10.3					
	Floating point addition	1.8 µs		0.78 µs					
Total number o				725					
Floating point i	instruction			•					
	g processing instruction			•					
PID instruction	1			•					
Special functio	on instruction								
(Trigonometric	function, square root,			•					
exponential op	eration, etc.)								
Constant scan		0.5 2000 ms (catting available in units of 0.5 ms)							
(Function for ke	eeping regular scan time)	0.52000 ms (setting available in units of 0.5 ms)							
Program capac	city	28K s	28K steps         60K steps         124K steps         25						
Number of I/O	device points [X/Y]	8192 points							
Number of I/O		4096 points							
Internal relay [I	M]*4	8192 points							
Latch relay [L]*	*4	8192 points							
Link relay [B]*4	l	8192 points							
Timer [T]*4		2048 points							
Retentive time	r [ST]*4	0 point							
Counter [C]*4		1024 points							
Data register [[				12288 points					
Link register [V	-		8192 points						
Annunciator [F			2048 points						
Edge relay [V]*				2048 points					
Link special rel				2048 points					
Link special reg				2048 points	1				
File register [R	l, ZR]	32768 points*5	65	536 points*5	131072	2 points*5			
Step relay [S]			8192 points						
Index register [Z]			16 points						
Pointer [P]		4096 points							
Interrupt pointer [I]			256 points						
Special relay [S				2048 points					
Special registe				2048 points					
Function input				16 points					
Function outpu	<u> </u>			16 points					
Function regist	ter [FD]			5 points					
Local device				•					
Device initial va	alues			•					

\*1: The processing speed is the same even when the device is indexed.
\*2: The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1 μs. A larger value indicates a higher processing speed.
\*3: Intelligent function module dedicated instructions are not included.
\*4: Indicates the number of points in the default state. This can be changed with the parameter.
\*5: Indicates the number of points in the built-in memory (standard RAM) is used. Capacity can be expanded by using an SRAM card or a Flash card. (Writing from a program is not possible with a Flash card.) With an SRAM card, up to 1041408 points can be used.

# **CPU Module Performance Specifications**

#### **Process CPU**

FIUCESS										
Control mother	Item	Q02PHCPU	Q06PHCPU	Q12PHCPU	Q25PHCPU					
Control method			Stored program	• •						
I/O control mod	de	Refresh								
				language (ladder)						
	Sequence control			c language (list)						
Program	language			FC), MELSAP-L						
language	languago		<ul> <li>Function block</li> </ul>	k						
language			Structured tex	tt (ST)						
	Process control language		Process control FBD*1							
Peripheral	USB									
connection por	t RS-232									
Manager										
Memory card in	nterrace		(SRAM card, Flas	sh card, ATA card)						
	LD instruction		34	ns						
Description	MOV instruction		102	2 ns						
Processing	PC MIX value									
speed*2	(instruction/µs)*3		10	0.3						
	Floating point addition		0.78	8 μs						
Total number of			75							
Floating point i										
	g processing instruction									
PID instruction	01 0									
Process contro										
Special functio										
	function, square root,	•								
exponential op		-								
Constant scan										
	eping regular scan time)	0.52000 ms (setting available in units of 0.5 ms)								
Program capad		28K steps	60K steps	124K steps	252K steps					
	device points [X/Y]		8192	· · · · · · · · · · · · · · · · · · ·						
Number of I/O										
Internal relay [		4096 points 8192 points								
Latch relay [L]	-	8192 points								
Link relay [B]*5										
Timer [T]*5		8192 points 2048 points								
Retentive time	r [ST]*5									
Counter [C]*5	.[01]	0 point 1024 points								
Data register [I	ל*IC	1224 points								
Link register [V			8192							
Annunciator [F	-		2048							
Edge relay [V]										
Link special re			2048 points							
Link special re			2048 points 2048 points							
File register [R		65536	points*6		2 points <sup>*6</sup>					
Step relay [S]	, <b>2</b> i ij	00000		points	pointo					
Index register	[Z]			oints						
Pointer [P]	,	4096 points								
Interrupt pointe	er []]	256 points								
Special relay [				points						
Special registe			2048							
Function input				oints						
Function input										
				oints						
Function regist				pints						
Local device	aluaa									
Device initial v	aiues									

1: PX Developer is required for programming by FBD.
1: PX Developer is required for programming by FBD.
1: PX Developer is required for programming by FBD.
2: The processing speed is the same even when the device is indexed.
3: The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1 µs. A larger value indicates a higher processing speed.
4: Intelligent function module dedicated instructions are not included.
5: Indicates the number of points in the default state. This can be changed with the parameter.
6: Indicates the number of points when the built-in memory (standard RAM) is used. Capacity can be expanded by using an SRAM card or a Flash card. (Writing from a program is not possible with a Flash card.) With an SRAM card, up to 1041408 points can be used.



Specifications

### **Redundant CPU**

	Item	Q12PRHCPU	Q25PRHCPU						
Control method		Stored program							
I/O control mod		Refr							
			language (ladder)						
		Logic symbolic language (list)     MELSAP3 (SFC), MELSAP-L							
	Sequence control								
Program	language	Function block							
language		Structured text	t (ST)						
	Process control	Process control FBD*1							
	language	Process control	ור אונייי						
Peripheral	USB	•							
connection por	t RS-232	•							
Memory card ir	nterface	•							
		(SRAM card, Flash	h card, ATA card)						
	LD instruction	34							
Processing	MOV instruction	102	ns						
speed*2	PC MIX value	10.	.3						
	(instruction/µs)*3								
	Floating point addition	0.78							
Total number of		77							
Floating point in		•							
	g processing instruction	•							
PID instruction		•							
Process contro									
Special function		-							
	function, square root,	•							
exponential ope	eration, etc.)								
Constant scan		0.52000 ms (setting available in units of 0.5 ms)							
	eping regular scan time)	1041/ 11/10	0501/ 11 11						
Program capac	device points [X/Y]	124K steps 8192 p	252K steps						
Number of I/O		4096 p							
Internal relay [N		8192 p							
Latch relay [L]*	-	8192 p							
Link relay [B]*5									
Timer [T]*5		8192 points 2048 points							
Retentive timer	r [ST]*5	0 point							
Counter [C]*5	[01]	1024 points							
Data register [D	זיז זיז	12288 points							
Link register [W		8192 points							
Annunciator [F]		2048 points							
Edge relay [V]*		2048 points							
Link special rel		2048 points							
Link special reg		2048 points							
File register [R,		131072 points*6							
Step relay [S]	· •	8192 points							
Index register [	[Z]	16 points							
Pointer [P]		4096 points							
Interrupt pointer [I]		256 points							
Special relay [S		2048 p							
Special register	-	2048 p							
Function input		16 pc							
Function output		16 pc							
Function registe		5 po							
Local device		9 þú							
Device initial va	alues								
201100 111101 10									

# Module Combinations for Multiple CPU System

Restrictions apply depending on CPU type, the number that can be installed, and supported serial No. For more information, please refer to the relevant users manual for each CPU.

#### Multiple CPU high speed main base unit (Q3 DB)

 Possible Possible (multiple CPU high-speed communication not available) Impossible

		High-speed Universal model QCPU	niversal model		High Performance model QCPU	Process CPU	Motion CPU/ Robot CPU <sup>-1</sup> /CNC CPU		C Controller CPU	
CPU 1	CPU 2 to 4	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV	Q00U Q01U Q02U	Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q13UD(E)H Q20UD(E)H Q26UD(E)H Q26UD(E)H Q50UDEH Q100UDEH	Q02(H) Q06H Q12H Q25H	002PH 006PH 012PH 025PH	Q172D Q173D Q172DS Q173DS CR750-Q CR751-Q Q173NC	Q172H Q173H Q172 Q173	Q24DHCCPU-V Q24DHCCPU-VG Q24DHCCPU-LS Q26DHCCPU-LS Q12DCCPU-V	Q06CCPU-V
High-speed Universal model QCPU	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV	•	_	•	0	0	•	_	•	_
	Q00U Q01U Q02U	-	-	_	-	-	-	-	0	0
Universal model QCPU	Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q10UD(E)H Q20UD(E)H Q26UD(E)H Q50UDEH Q100UDEH	•	_	•	0	0	•	_	•	0
High Performance model QCPU	Q02(H) Q06H Q12H Q25H	0	_	0	0	0	_	_	0	0

\*1: The robot CPU includes CR750-Q, CR751-Q.

#### Main base unit other than Q3 DB

O Possible (multiple CPU high-speed communication not available) - Impossible

		High-speed Universal model QCPU QCPU			High Performance model QCPU	Process CPU	Motion CPU/ Robot CPU <sup>*2</sup> /CNC CPU		C Controller CPU	
CPU 1	CPU 2 to 4	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV		Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q13UD(E)H Q20UD(E)H Q26UD(E)H Q50UDEH Q100UDEH	Q02(H) Q06H Q12H Q25H	Q02PH Q06PH Q12PH Q25PH	Q172D Q173D Q172DS Q173DS CR750-Q CR751-Q Q173NC	Q172H Q173H Q172 Q173	Q24DHCCPU-V Q24DHCCPU-VG Q24DHCCPU-LS Q26DHCCPU-LS Q12DCCPU-V	Q06CCPU-V
High-speed Universal model QCPU	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV	0	_	0	0	○*3	_	_	○*5	_
	Q00U Q01U Q02U	-	_	_	-	-	-	○*3*4	○*5	○*5
Universal model QCPU	Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q10UD(E)H Q20UD(E)H Q26UD(E)H Q20UD(E)H Q50UDEH Q100UDEH	0	_	0	0	O*3	_	_	O*5	○*5
High Performance model QCPU	Q02(H) Q06H Q12H Q25H	0	_	0	0	○*³	_	○*3*6	○*5	○*5

Y2: The robot CPU includes CR750-Q, CR751-Q.
 \*3: The slim type main base unit (Q3⊟SB) cannot be used.
 \*4: Can only use 1x Motion CPU.
 \*5: In case of using Q06CCPU-V or Q12DCCPU-V, the redundant power main base unit (Q3⊟RB) cannot be used.
 \*6: Cannot be used together with Q03UD(E), Q04UD(E)H, Q06UD(E)H, Q10UD(E)H, Q13UD(E)H, Q20UD(E)H, Q26UD(E)H, Q50UDEH, Q100UDEH, Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDVCPU or Q12DCCPU-V.

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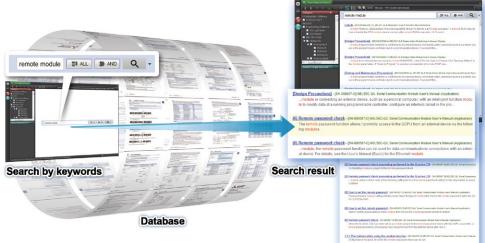
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- Automatic update of manual versions
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OS	OS version	Model		
iOS	iOS 8.1 or later	Apple iPad 2, iPad (3rd generation), iPad (4th generation), iPad Air, iPad Air 2,		
103	103 8.1 01 later	iPad mini, iPad mini 2, iPad mini 3, iPad mini 4		
Android™	Android™ 4.3/4.4/5.0	ASUS Nexus7™ (2013)*1		

\*1: When using a tablet not listed above, 7-inch (resolution of 1920×1200 dots (WUXGA)) or better is recommended.

\*Please check the compatibility and restrictions of the product in the related manual before purchasing.

[Legend] DB : Double brand product (Note) NEW : Recently released product SOON : Product available soon

# **CPU** module

Тур	e	Model	Outline
		Q03UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 30K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 120 KB, peripheral connection ports: USB, Ethernet (Predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
		Q04UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 160 KB, peripheral connection ports: USB, Ethernet (Predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
High-speed Univ QCPU	versal model	Q06UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 240 KB, peripheral connection ports: USB, Ethernet (Predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
		Q13UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 520 KB, peripheral connection ports: USB, Ethernet (Predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
		Q26UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 1040 KB, peripheral connection ports: USB, Ethernet (Predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
		Q00UJCPU	No. of I/O points: 256 points, no. of I/O device points: 8192 points, program capacity: 10K steps, basic operation processing speed (LD instruction): 120 ns, program memory capacity: 40 KB, peripheral connection ports: USB and RS-232, no memory card I/F, 5-slot base, with 100240 V AC input/5 V DC/3 A output power supply
		Q00UCPU	No. of I/O points: 1024 points, no. of I/O device points: 8192 points, program capacity: 10K steps, basic operation processing speed (LD instruction): 80 ns, program memory capacity: 40 KB, peripheral connection ports: USB and RS-232, no memory card I/F
		Q01UCPU	No. of I/O points: 1024 points, no. of I/O device points: 8192 points, program capacity: 15K steps, basic operation processing speed (LD instruction): 60 ns, program memory capacity: 60 KB, peripheral connection ports: USB and RS-232, no memory card I/F
		Q02UCPU	No. of I/O points: 2048 points, no. of I/O device points: 8192 points, program capacity: 20K steps, basic operation processing speed (LD instruction): 40 ns, program memory capacity: 80 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q03UDCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 30K steps, basic operation processing speed (LD instruction): 20 ns, program memory capacity: 120 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
Universal model QCPU	I	Q04UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 160 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
40.0		Q06UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 240 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q10UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 100K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 400 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q13UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 520 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q20UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 200K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 800 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q26UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 1040 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q03UDECPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 30K steps, basic operation processing speed (LD instruction): 20 ns, program memory capacity: 120 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q04UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 160 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q06UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 240 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q10UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 100K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 400 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
	Built-in Ethernet type	Q13UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 520 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q20UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 200K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 800 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q26UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 1040 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q50UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 500K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 2000 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card
		Q100UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 1000K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 4000 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card

Note: General specifications and product guarantee conditions of jointly developed products are different from those of MELSEC products. For more information, please refer to the product manuals or contact your local Mitsubishi representative for details.

# CPU module

Ту	ре	Model	Outline
		Q00JCPU	No. of I/O points: 256 points, no. of I/O device points: 2048 points, program capacity: 8K steps, basic operation processing speed (LD instruction): 200 ns, program memory capacity: 58 KB, peripheral connection ports: RS-232, no memory card I/F, 5-slot base, with 100240 V AC input/5 V DC/3 A output power supply, to be discontinued (September 2018)
Basic model QCPU	odel	Q00CPU	No. of I/O points: 1024 points, no. of I/O device points: 2048 points, program capacity: 8K steps, basic operation processing speed (LD instruction): 160 ns, program memory capacity: 94 KB, peripheral connection ports: RS-232, no memory card I/F, to be discontinued (September 2018)
		Q01CPU	No. of I/O points: 1024 points, no. of I/O device points: 2048 points, program capacity: 14K steps, basic operation processing speed (LD instruction): 100 ns, program memory capacity: 94 KB, peripheral connection ports: RS-232, no memory card I/F, to be discontinued (September 2018)
		Q02CPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 28K steps, basic operation processing speed (LD instruction): 79 ns, program memory capacity: 112 KB, peripheral connection ports: RS-232, memory card IF: SRAM card, FLASH card, and ATA card, to be discontinued (September 2018)
		Q02HCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 28K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 112 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card, to be discontinued (September 2018)
High Performa QCPU	nce model	Q06HCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 240 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card, to be discontinued (September 2018)
		Q12HCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 124K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 496 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card, to be discontinued (September 2018)
		Q25HCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 252K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 1008 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card, to be discontinued (September 2018)
		Q02PHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 28K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 112 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q06PHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 240 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
Process CPU		Q12PHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 124K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 496 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q25PHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 252K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 1008 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		Q12PRHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 124K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 496 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
Redundant CP	U	Q25PRHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 252K steps, basic operation processing speed (LD instruction): 34 ns, program memory capacity: 1008 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card
		QC10TR	Tracking cable 1 m
	Tracking cable	QC30TR	Tracking cable 3 m
		Q24DHCCPU-V	No. of I/O points: 4096 points, endian format: little endian, removable storage: SD memory card, OS: VxWorks® Version 6.8.1
		Q26DHCCPU-LS	No. of I/O points: 4096 points, endian format: little endian, removable storage: SD memory card, OS: No pre-installed operating system (Operating system installed by user)
C Controller CI	20	Q24DHCCPU-LS	No. of I/O points: 4096 points, endian format: little endian, removable storage: SD memory card, OS: No pre-installed operating system (Operating system installed by user)
		Q12DCCPU-V	No. of I/O points: 4096 points, endian format: little endian, removable storage: CompactFlash card, OS: VxWorks® Version 6.4
		Q06CCPU-V	No. of I/O points: 4096 points, endian format: little endian, removable storage: CompactFlash card, OS: VxWorks® Version 5.4
		Q12DCCPU-V-BZ11	C Controller (Q12DCCPU-V) pre-installed with SECS/GEM COMMUNICATION SOFTWARE for NONGEM, supports SECS-I (SEMI E4), HSMS (SEMI E37)
		Q12DCCPU-V-BZ13	C Controller (Q12DCCPU-V) pre-installed with SECS/GEM COMMUNICATION SOFTWARE for GEM, middle kit version that supports GEM (SEMI E30). (does not support Trace data collection, Limit monitoring, Document file output)
		Q12DCCPU-V-BZ15	C Controller (Q12DCCPU-V) pre-installed with SECS/GEM COMMUNICATION SOFTWARE for GEM ADVANCED, full kit version that supports GEM (SEMI E30). (supports Trace data collection, Limit monitoring, Document file output)
		Q12DCCPU-V-BZ19	C Controller (Q12DCCPU-V) pre-installed with DATA COLLECTION SOFTWARE, equipped with Simple MES functionality.
	Applications pre-installed model	Q12DCCPU-V-BZ1B	C Controller (012DCCPU-V) pre-installed with DATA COLLECTION SOFTWARE Light, not equipped with Simple MES functionality.
	moder	Q24DHCCPU-VG-B000	C Controller (Q24DHCCPU-VG) pre-installed with GENWARE®3-VG Runtime License Version, runtime library and font data are pre-installed.
		Q24DHCCPU-VG-B002	C Controller (024DHCCPU-VG) pre-installed with GENWARE <sup>®</sup> 3-VG Tool License Version, GUI development environment (CI SKETCH-E) is pre-installed into the Runtime License version
		Q26DHCCPU-LS-B031	C Controller (Q26DHCCPU-LS) pre-installed with Lineo uLinux Station +, Web pages application that can be configured in basic Linux system.
		Q24DHCCPU-LS-B030	C Controller (Q24DHCCPU-LS) pre-installed with Lineo uLinux and uLinux Station, Web pages application that can be configured in basic Linux system.
4 5	Cable	Q12DCCPU-CBL*1*2*3	RS-232 connection converter cable (custom mini-DIN to 9-pin D-sub connector)

\*1: For use with Q24DHCCPU-V, Q24DHCCPU-VG. \*2: For use with Q24DHCCPU-LS, Q26DHCCPU-LS. \*3: For use with Q12DCCPU-V.

# **CPU** module

Туре	Model	Outline
	Q6BAT	Replacement battery
	Q7BAT	Replacement large-capacity battery
Battery	Q7BAT-SET	Large-capacity battery with holder for installing CPU
	Q8BAT	Replacement large-capacity battery module
	Q8BAT-SET	Large-capacity battery module with CPU connection cable
	Q4MCA-1MBS*1	Extended SRAM cassette, capacity: 1 MB
Extended SRAM cassette	Q4MCA-2MBS*1	Extended SRAM cassette, capacity: 2 MB
Extended SRAM casselle	Q4MCA-4MBS*1	Extended SRAM cassette, capacity: 4 MB
	Q4MCA-8MBS*1	Extended SRAM cassette, capacity: 8 MB
	NZ1MEM-2GBSD*1*2*3*4	SD memory card, capacity: 2 GB
	NZ1MEM-4GBSD*1*2*3*4	SDHC memory card, capacity: 4 GB
SD memory card	NZ1MEM-8GBSD*1*2*3*4	SDHC memory card, capacity: 8 GB
	NZ1MEM-16GBSD*1*2*3*4	SDHC memory card, capacity: 16 GB
	Q2MEM-1MBS*5	SRAM memory card, capacity: 1 MB
	Q2MEM-2MBS*5	SRAM memory card, capacity: 2 MB
	Q3MEM-4MBS*5	SRAM memory card, capacity: 4 MB
	Q3MEM-4MBS-SET*5	SRAM memory card with cover, capacity: 4 MB
	Q3MEM-8MBS*6	SRAM memory card, capacity: 8 MB
Memory card	Q3MEM-8MBS-SET*6	SRAM memory card with cover, capacity: 8 MB
	Q3MEM-CV	Memory card protective cover for the Universal model QCPU (comes with Q3MEM-4MBS-SET/Q3MEM-8MBS-SET)
	Q3MEM-CV-H	Memory card protective cover for the High Performance model, Process, and Redundant CPUs (comes with Q3MEM-4MBS-SET)
	Q2MEM-32MBA*5	ATA card, capacity: 32 MB
	GT05-MEM-128MC*4*7	CompactFlash card, capacity: 128 MB
	GT05-MEM-256MC*4*7	CompactFlash card, capacity: 256 MB
	QD81MEM-512MBC*4*7*8	CompactFlash card, capacity: 512 MB
CompactFlash card	QD81MEM-1GBC*4*8	CompactFlash card, capacity: 1 GB
	QD81MEM-2GBC*4*8	CompactFlash card, capacity: 2 GB
	QD81MEM-4GBC*4*8	CompactFlash card, capacity: 4 GB
	QD81MEM-8GBC*4*8	CompactFlash card, capacity: 8 GB
Memory card adapter	Q2MEM-ADP	Adapter for Q2MEM memory card's standard PCMCIA slot
	Q2MEM-BAT	Replacement battery for Q2MEM-1MBS and Q2MEM-2MBS
SRAM card battery	Q3MEM-BAT	Replacement battery for Q3MEM-4MBS and Q3MEM-8MBS
Connection cable	QC30R2	RS-232 cable for connecting PC and CPU, 3 m (between mini-DIN6P and Dsub9P)
Cable disconnection prevention holder	Q6HLD-R2	Holder for preventing RS-232 cable (Programmable Controller CPU connection) disconnection

Prevention Flore
 Provention Flore
 \*1: For use with QuDVCPU.
 \*2: For use with QuDVCPU-VQ, QuDHCCPU-VG,
 \*3: For use with QuDHCCPU-S, QuDHCCPU-LS,
 \*4: Mitsubisini Electric shall not guarantee the operation of any non-Mitsubishi Electric products.
 \*4: Mitsubishi Electric shall not guarantee the operation of any non-Mitsubishi Electric products.
 \*5: For use with the Universal model QCPUs (except QnUDV), High Performance model QCPUs, process CPUs, and redundant CPUs that are equipped with the memory card interface.
 \*7: For use with QuECPU-V.
 \*8: For use with Q12DCCPU-V.



Туре	Model	Outline
	Q33B	3 slots, 1 power supply module required, for Q Series modules
Main base	Q35B	5 slots, 1 power supply module required, for Q Series modules
Main base	Q38B	8 slots, 1 power supply module required, for Q Series modules
	Q312B	12 slots, 1 power supply module required, for Q Series modules
	Q35DB	5 slots, power supply module required, for Q Series modules
Multiple CPU high speed main base	Q38DB	8 slots, 1 power supply module required, for Q Series modules
Indii Dase	Q312DB	12 slots, 1 power supply module required, for Q Series modules
	Q32SB	2 slots, 1 slim type power supply module required, for Q Series modules
Slim type main base	Q33SB	3 slots, 1 slim type power supply module required, for Q Series modules
	Q35SB	5 slots, 1 slim type power supply module required, for Q Series modules
Redundant power main base	Q38RB	8 slots, 2 redundant power supply modules required, for Q Series modules
	Q63B	3 slots, 1 power supply module required, for Q Series modules
	Q65B	5 slots, 1 power supply module required, for Q Series modules
	Q68B	8 slots, 1 power supply module required, for Q Series modules
Extension base	Q612B	12 slots, 1 power supply module required, for Q Series modules
	Q52B	2 slots, power supply module not required, for Q Series modules
	Q55B	5 slots, power supply module not required, for Q Series modules
Redundant power extension base	Q68RB	8 slots, 2 redundant power supply modules required, for Q Series modules
Redundant type extension base	Q65WRB <sup>*1</sup>	5 slots, 2 redundant power supply modules required, for Q Series modules
	QC05B	0.45 m cable for connecting extension base unit
	QC06B	0.6 m cable for connecting extension base unit
E deseries estate	QC12B	1.2 m cable for connecting extension base unit
Extension cable	QC30B	3 m cable for connecting extension base unit
	QC50B	5 m cable for connecting extension base unit
	QC100B	10 m cable for connecting extension base unit
	Q6DIN1	DIN rail mounting adapter for Q38B, Q312B, Q68B, Q612B, Q38RB, Q68RB, Q65WRB, Q38DB, and Q312DB
	Q6DIN2	DIN rail mounting adapter for Q35B, Q65B, Q00JCPU, and Q00UJCPU
DIN rail mounting adapter	Q6DIN3	DIN rail mounting adapter for Q32SB, Q33SB, Q35SB, Q33B, Q52B, Q55B, and Q63B
	Q6DIN1A	DIN rail mounting adapter (with vibration-proofing bracket set) for Q3DB, Q5B, Q6B, Q38RB, Q68RB, and Q65WRB
Blank cover	QG60	Blank cover for I/O slot

\*1: Only compatible with redundant CPU system.

# Power supply module

	Q61P	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 6 A
Davier everyte	Q62P	Input voltage: 100240 V AC, output voltage: 5/24 V DC, output current: 3/0.6 A
Power supply	Q63P	Input voltage: 24 V DC, output voltage: 5 V DC, output current: 6 A
	Q64PN	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 8.5 A
Power supply with life detection	Q61P-D	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 6 A
Slim type power supply	Q61SP	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 2 A
Redundent newer supply	Q63RP	Input voltage: 24 V DC, output voltage: 5 V DC, output current: 8.5 A
Redundant power supply	Q64RPN	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 8.5 A

# I/O module

Туре		Model	Outline
		QX10	16 points, 100120 V AC, response time: 20 ms, 16 points/common, 18-point terminal block
	AC	QX10-TS	16 points, 100120 V AC, response time: 20 ms, 16 points/common, 18-point spring clamp terminal block
		QX28	8 points, 100240 V AC, response time: 20 ms, 8 points/common, 18-point terminal block
		QX40	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, positive common, 18-point terminal block
		QX40-TS	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, positive common, 18-point spring clamp terminal bloc
		QX40-S1	16 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 16 points/common, positive common, 18-point terminal block
	DC	QX40H	16 points, 24 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, positive common, 18-point terminal bloc
	(Positive	QX41*2 *3	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, 40-pin connector
	common)*1	QX41-S1*2	32 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 32 points/common, positive common, 40-pin connector
		QX41-S2*2 *3	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, 40-pin connector
		QX42*2	64 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, 40-pin connector
		QX42-S1*2	64 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 32 points/common, positive common, 40-pin connector
Input	AC/DC	QX50	16 points, 48 V AC/DC, response time: 20 ms, 16 points/common, positive/negative common, 18-point terminal bloc
mput	110/20	QX70	16 points, 5/12 V DC, response time: 1/5/10/20/70 ms, 16 points/common, positive/negative common, 18-point terminal block
		QX70H	16 points, 5 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, positive common, 18-point terminal block
	DC sensor	QX71*2	32 points, 5/12 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive/negative common, 40-pin connector
		QX72*2	64 points, 5/12 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive/negative common, 40-pin connector
		QX80	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, negative common, 18-point terminal block
		QX80-TS	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, negative common, 18-point spring clamp terminal bloc
	DC	QX80H	16 points, 24 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, negative common, 18-point terminal block
	(Negative	QX81*3 *4	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, negative common, 37-pin D-sub connector
	common) *1	QX81-S2*3 *4	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, negative common, 37-pin D-sub connector
		QX82 *2	64 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, negative common, 40-pin connector
		QX82-S1*2	64 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 32 points/common, negative common, 40-pin connector
		QX90H	16 points, 5 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, negative common, 18-point terminal block
		QY10	16 points, 24 V DC/240 V AC, 2 A/point, 8 A/common, response time: 12 ms, 16 points/common, 18-point terminal block
	Relay	QY10-TS	16 points, 24 V DC/240 V AC, 2 A/point, 8 A/common, response time: 12 ms, 16 points/common, 18-point spring clamp terminal block
		QY18A	8 points, 24 V DC/240 V AC, 2 A/point, response time: 12 ms, 18-point terminal block, all points independent
	Triac	QY22	16 points, 100240 V AC, 0.6 A/point, 4.8 A/common, response time: 1 ms + 0.5 cycle, 16 points/common, 18-point terminal block, with surge suppression
		QY40P	16 points, 1224 V DC, 0.1 A/point, 1.6 A/common, response time: 1 ms, 16 points/common, sink type, 18-point terminal block, overload protection function, overheat protection function, surge suppression
		QY40P-TS	16 points, 1224 V DC, 0.1 A/point, 1.6 A/common, response time: 1 ms, 16 points/common, sink type, 18-point spring clamp terminal block, overload protection function, overheat protection function, surge suppression
	Transistor	QY41H	32 points, 524 V DC, 0.2 A/point, 2 A/common, response time: 2 us, 32 points/common, sink type, 40-pin connector, with surge suppression
	(Sink)	QY41P*2	32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
Output		QY42P*2	64 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
Output		QY50	16 points, 1224 V DC, 0.5 A/point, 4 A/common, response time: 1 ms, 16 points/common, sink type, 18-point terminal block, with surge suppression and fuse
	Transistor (Independent)	QY68A	8 points, 524 V DC, 2 A/point, 8 A/module, response time: 10 ms, sink/source type, 18-point terminal block, with surge suppression, all points independent
	TTL CMOS	QY70	16 points, 512 V DC, 16 mA/point, 256 mA/common, response time: 0.5 ms, 16 points/common, sink type, 18-point terminal block, with fuse
		QY71*2	32 points, 512 V DC, 16 mA/point, 512 mA/common, response time: 0.5 ms, 32 points/common, sink type, 40-pin connector, with fuse
		QY80	16 points, 1224 V DC, 0.5 A/point, 4 A/common, response time: 1 ms, 16 points/common, source type, 18-point terminal block, with surge suppression and fuse
	Transistor	QY80-TS	16 points, 1224 V DC, 0.5 A/point, 4 A/common, response time: 1 ms, 16 points/common, source type, 18-point spring clamp terminal block, with surge suppression and fuse
	(Source)	QY81P*4	32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, source type, 37-pin D-sub connector, overload protection function, overheat protection function, surge suppression
		QY82P*2	64 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, source type, 40-pin connector, overload protection function, overheat protection function, surge suppression
1/0		QH42P*2 *5	Input: 32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, output: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
	DC input/ transistor output	QX48Y57	Input: 8 points, 24 V DC, response time: 1/5/10/20/70 ms, 8 points/common, positive common, output: 7 points, 1224 V DC, 0.5 A/point, 2 A/common, response time: 1 ms, 7 points/common, sink type, 18-point terminal block, with surge suppression and fuse
		QX41Y41P*2 *5	Input: 32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, output: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression

\*1: "Positive common" indicates that the positive lead of a DC power supply must be connected to the common terminal. Accordingly, "Negative common" indicates that the negative lead must be connected to the common terminal.
\*2: Connector is not provided. Separately order one of the following: A6CON1/A6CON2/A6CON3/A6CON4.
\*3: The rated input currents are different. [QX41: approx. 4 mA, QX41-52: approx. 6 mA]
\*4: Connector is not provided. Separately order one of the following: A6CON1E/A6CON2E/A6CON3E.
\*5: The number of occupied input/output points is different. [QH42P: 32 points; QX41Y41P: 64 points (first 32 points: input/second 32 points: output)]

79



Туре		Model	Outline
		A6CON1	32-point connector soldering type (40-pin connector)
		A6CON2	32-point connector crimp-contact type (40-pin connector)
		A6CON3	32-point connector pressure-displacement (flat cable) type (40-pin connector)
Connector		A6CON4	32-point connector soldering type (40-pin connector, cable connectable in bidirection)
		A6CON1E	32-point connector soldering type (37-pin D-sub connector)
		A6CON2E	32-point connector crimp-contact type (37-pin D-sub connector)
		A6CON3E	32-point connector pressure-displacement (flat cable) type (37-pin D-sub connector)
Spring clamp termi	inal block	Q6TE-18SN	For 16-point I/O modules, 0.31.5 mm <sup>2</sup> (2216 AWG)
		Q6TA32	For 32-point I/O modules, 0.5 mm <sup>2</sup> (20 AWG)
Terminal block ada	apter	Q6TA32-TOL	Q6TA32 dedicated tool
		A6TBXY36	For positive common input modules and sink output modules (standard type)
		A6TBXY54	For positive common input modules and sink output modules (2-wire type)
		A6TBX70	For positive common input modules (3-wire type)
Connector/terminal	l block	A6TBX36-E	For negative common input modules (standard type)
conversion module	9	A6TBX54-E	For negative common input modules (2-wire type)
		A6TBX70-E	For negative common input modules (3-wire type)
		A6TBY36-E	For source output modules (standard type)
		A6TBY54-E	For source output modules (2-wire type)
		AC05TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 0.5 m
		AC10TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 1 m
		AC20TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 2 m
		AC30TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 3 m
		AC50TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 5 m
		AC80TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 8 m *Common current 0.5 A or lower
Ca	ble	AC100TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 10 m *Common current 0.5 A or lower
		AC05TB-E	For A6TBX36-E, A6TBY36-E, A6TBX54-E, A6TBY54-E, and A6TBX70-E (negative common/source type), 0.5 m
		AC10TB-E	For A6TBX36-E, A6TBY36-E, A6TBX54-E, A6TBY54-E, and A6TBX70-E (negative common/source type), 1 m
		AC20TB-E	For A6TBX36-E, A6TBY36-E, A6TBX54-E, A6TBY54-E, and A6TBX70-E (negative common/source type), 2 m
		AC30TB-E	For A6TBX36-E, A6TBY36-E, A6TBX54-E, A6TBY54-E, and A6TBX70-E (negative common/source type), 3 m
		AC50TB-E	For A6TBX36-E, A6TBY36-E, A6TBX54-E, A6TBY54-E, and A6TBX70-E (negative common/source type), 5 m
Relay terminal mod	dule	A6TE2-16SRN	For 40-pin connector 24 V DC transistor output modules (sink type)
		AC06TE	For A6TE2-16SRN, 0.6 m
		AC10TE	For A6TE2-16SRN, 1 m
Ca	ble	AC30TE	For A6TE2-16SRN, 3 m
		AC50TE	For A6TE2-16SRN, 5 m
		AC100TE	For A6TE2-16SRN, 10 m

# Analog I/O module

	Voltage input	Q68ADV	8 channels, input: -1010 V DC, output (resolution): 04000, -40004000, 012000, -1200012000, 016000, -1600016000, conversion speed: 80 μs/channel, 18-point terminal block
		Q62AD-DGH	2 channels; input, 420 mA DC, output (resolution): 032000, 064000, conversion speed: 10 ms/2 channels, 18-point terminal block, channel isolated, supplies power to 2-wire transmitter
	Current input	Q66AD-DG*1	6 channels, input: 420 mA DC (when 2-wire transmitter is connected), 020 mA DC, output (resolution): 04000, 012000, conversion speed: 10 ms/channel, 40-pin connector, channel isolated, supplies power to 2-wire transmitter
Analog		Q68ADI	8 channels, input: 020 mA DC, output (resolution): 04000, -40004000, 012000, -1200012000, 016000, -16000 conversion speed: 80 µs/channel, 18-point terminal block
input	Voltage/current	Q64AD	4 channels; input -1010 V DC, 020 mA DC, output (resolution): 04000, -40004000, 012000, -1200012000, 016000, -1600016000, conversion speed: 80 μs/channel, 18-point terminal block
		Q64ADH	4 channels; input -1010 V DC, 020 mA DC, output (resolution): 020000, -2000020000, -500022500, conversion speed: 20 µs/channel, 18-point terminal block
	input	Q64AD-GH	4 channels, input: -1010 V DC, 020 mA DC, output (resolution): 032000, -3200032000, 064000, -6400064000, conversion speed: 10 ms/4 channels, 18-point terminal block, channel isolated
		Q68AD-G*1	8 channels, input: -1010 V DC, 020 mA DC, output (resolution): 04000, -40004000, 012000, -1200012000, 016000, -1600016000, conversion speed: 10 ms/channel, 40-pin connector, channel isolated

\*1: A connector is not provided. The A6CON4 connector must be ordered separately.

# Analog I/O module

Туре		Model	Outline
	Voltage output	Q68DAVN	8 channels, input (resolution): 04000, -40004000, 012000, -1200012000, -1600016000, output: -1010 V DC, conversion speed: 80 μs/channel, 18-point terminal block
	Current output	Q68DAIN	8 channels, input (resolution): 04000, -40004000, 012000, -1200012000; output: 020 mA DC, conversion speed: 80 μs/channel, 18-point terminal block
		Q64DAH	4 channels, input (resolution): 020000, -2000020000 output: -1010 V DC, 020 mA DC, conversion speed: 20 µs/channel, 18-point terminal block
Analog output		Q62DAN	2 channels, input (resolution): 04000, -40004000, 012000, -1200012000, -1600016000, output: -1010 V DC, 020 mA DC, conversion speed: 80 μs/channel, 18-point terminal block
	Voltage/current output	Q62DA-FG	2 channels, input (resolution): 012000, -1200012000, -1600016000, output: -1212 V DC, 022 mA DC, conversion speed: 10 ms/2 channels, 18-point terminal block, channel isolated
		Q64DAN	4 channels, input (resolution): 04000, -40004000, 012000, -1200012000, -1600016000, output: -1010 V DC, 020 mA DC, conversion speed: 80 μs/channel, 18-point terminal block
		Q66DA-G*1	6 channels, input (resolution): 04000, -40004000, 012000, -1200012000, -1600016000, output: -1212 V DC, 022 mA DC, conversion speed: 6 ms/channel, 40-pin connector, channel isolated
Analog input/ output	Voltage and current input/ output	Q64AD2DA	Input: 4 channels, input: -1010 V DC, 020 mA DC > output (resolution): 04000, -40004000, 012000, 016000, -1600016000 > conversion speed: 500 µs/channel output: 2 channels input (resolution): 04000, -40004000, 012000, -1600016000 > output: -1010 V DC, 020 mA DC > conversion speed: 500 µs/channel 18-point terminal block
Load cell input		Q61LD	1 channel, input (load cell output): 0.03.3 mV/V, output (resolution): 010000, conversion speed: 10 ms, 18-point terminal block
CT input modu	le	Q68CT	8 channels, input: CT 05 A AC, 050 A AC, 0100 A AC, 0200 A AC, 0400 A AC, 0600 A AC, output: 010000, 18-point terminal block
		Q64TD	4 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: 40 ms/channel, channel isolated, 18-point terminal block
		Q64TDV-GH	4 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: sampling cycle x 3, sampling cycle: 20 ms/channel, channel isolated, 18-point terminal block
	Thermocouple	Q68TD-G-H01*1*2	8 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: 320 ms/8 channels, channel isolated, 40-pin connector
Temperature input		Q68TD-G-H02*1	8 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: 640 ms/8 channels, channel isolated, 40-pin connector
		Q64RD	4 channels, platinum RTD (Pt100, JPt100), disconnection detection function, conversion speed: 40 ms/channel, 18-point terminal block
	RTD	Q64RD-G	4 channels, platinum RTD (Pt100, JPt100), nickel RTD (Ni100), disconnection detection function, conversion speed: 40 ms/channel, channel isolated, 18-point terminal block
		Q68RD3-G*1	8 channels, platinum RTD (Pl100, JPl100), nickel RTD (Ni100), disconnection detection function, conversion speed: 320 ms/8 channels, channel isolated, 40-pin connector
		Q64TCTTN	4 channels, thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), heating control/cooling control/heating-cooling control, sampling cycle: 500 ms/4 channels, channel isolated, 18-point terminal block
Temperature control	Thermocouple	Q64TCTTBWN	4 channels, thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), heating control/cooling control/heating-cooling control, heater disconnection detection function, sampling cycle: 500 ms/4 channels, channel isolated, two 18-point terminal blocks
Control	BTD	Q64TCRTN	4 channels, platinum RTD (Pt100, JPt100), heating control/cooling control/heating-cooling control, sampling cycle: 500 ms/4 channels, channel isolated, 18-point terminal block
		Q64TCRTBWN	4 channels, platinum RTD (Pt100, JPt100), heating control/cooling control/heating-cooling control, heater disconnection detection function, sampling cycle: 500 ms/4 channels, channel isolated, two 18-point terminal blocks
Loop control		Q62HLC	2 channels, input: thermocouple/micro voltage/voltage/current, conversion speed (input): 25 ms/2 channels, sampling cycle: 25 ms/2 channels, output: 420 mA DC, conversion speed (output): 25 ms/2 channels, 18-point terminal block, with 5 PID control modes

\*1: A connector is not provided. The A6CON4 connector must be ordered separately. \*2: Depending on the combination of power source module and base unit, the installable slot position may be limited.

# Positioning module, pulse I/O module

	ype	Model	Outline
	With	QD77GF4	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, advanced synchronous control, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 26-pin connector, with CC-Link IE Field Network connectivity
	CC-Link IE Field Network	QD77GF8	8-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, advanced synchronous control, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 26-pin connector, with CC-Link IE Field Network connectivity
Simple	connectivity	QD77GF16*1	16-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, advanced synchronous control, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 26-pin connector, with CC-Link IE Field Network connectivity
motion		QD77MS2*2	2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNET II/H connectivity
	With SSCNET II/H connectivity	QD77MS4*2	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNET II/H connectivity
	connectivity	QD77MS16*2	16-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNET II/H connectivity
		QD75P1N*2	1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector
		QD75P1*2	1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector
		QD75P2N*2	2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector
	Open collector output	QD75P2*2	2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector
	output	QD75P4N*2	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector
		QD75P4*2	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector
		QD70P4*2	4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector
		QD70P8*2	8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector
		QD75D1N*2	1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector
		QD75D1*2	40-pin connector
	Differential output	QD75D2N*2	2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector
Positioning		QD75D2*2	2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 1 Mpps, 40-pin connector
		QD75D4N*2	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector
		QD75D4*2	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 1 Mpps, 40-pin connector
		QD70D4*2	4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector
		QD70D8*2	8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector
		QD75MH1*3	1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNET II connectivity, to be discontinued (September 2018)
			2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse,
	With SSCNET II	QD75MH2*3	no. of positioning data: 600/axis, 40-pin connector, with SSCNET II connectivity, to be discontinued (September 2018)
	connectivity	QD75MH4*3	4-axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNET III connectivity, to be discontinued (September 2018)
		QD74MH8	8-axes, control unit: pulse, no. of positioning data: 32/axis, with SSCNET II connectivity
	-	QD74MH16	16-axes, control unit: pulse, no. of positioning data: 32/axis, with SSCNET II connectivity
	Open collector output with built-in counter function	QD72P3C3*2	Positioning: 3-axes, control unit: pulse, no. of positioning data: 1/axis, max. output pulse: 100 kpps, counter: 3 channels, 100 kpps, count input signal: 5/24 V DC, 40-pin connector
		QD62*3	2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector
		QD62E*3	2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, 0.1 A/point, 0.4 A/common, 40-pin connector
		QD62D*3	2 channels, 500/200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 5/12/24 V DC; coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector
		QD63P6*2	6 channels, 200/100/10 kpps, count input signal: 5 V DC, 40-pin connector
High-speed co	ounter	QD64D2*2	2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector
		QD65PD2*2	2 Channels Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/200 kpps/100 kpps/10 kpps » Count input signal level: EIA Standards RS-422-A, differential line driver level DC Input: 200 kpps/100 kpps/10 kpps » Count input signal level: 5/12/24 V DC, 710 mA external outputs: Transistor (sink type) output, 12/24 V DC 0.1 A/point, 0.8 A/common, 40-pin connector
Channel isola	ted pulse input	QD60P8-G	8 channels, 30 kpps/10 kpps/1 kpps/100 pps/50 pps/10 pps/0.1 pps/0.1 pps, count input signal: 5/1224 V DC
		7MHIOCON connector must b	

\*1: A connector is not provided. The LD77/MHIOCON connector must be ordered separately. \*2: A connector is not provided. The A6CON1/A6CON2/A6CON4 connector must be ordered separately. \*3: A connector is not provided. The A6CON1/A6CON2/A6CON3/A6CON4 connector must be ordered separately.

# Energy measuring module, insulation monitoring module

	Ту	ре	Model	Outline
			QE81WH*1	Three-phase 3-wire type, Number of measurement circuits: 1 circuit, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
	Energy measuring	ring	QE84WH*1*2	Three-phase 3-wire type, Number of measurement circuits: 4 circuits, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
		ning	QE81WH4W*1*3	Three-phase 4-wire type, Number of measurement circuits: 1 circuit, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
		QE83WH4W*1*2*3	Three-phase 4-wire type, Number of measurement circuits: 3 circuits, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.	
		QE8WH4VT	QE81WH4W, QE83WH4W dedicated voltage transformer (63.5/110 V AC227/480 V AC)	
	Isolation monitoring		QE82LG*4	Measured items: leakage current (lo), resistive component leakage current (lor), number of measured circuits: 2 circuits

\*1: Dedicated current sensors are required for operation. \*2: Current measurement mode is provided. Up to eight circuits can be measured when measuring only the current value. \*3: The separate voltage transformer (DEBWH4VT) is required for the three-phase 4-wire compatible products. \*4: Dedicated residual current transformers are required for operation.

# Advanced information module

MES interface		QJ71MES96N NEW	MES interface module (MX MESInterface and CompactFlash card are required)
		QJ71MES96	MES interface module (MX MESInterface and CompactFlash card are required), to be discontinued (May 2018)
		GT05-MEM-128MC	CompactFlash card, capacity: 128 MB
		GT05-MEM-256MC	CompactFlash card, capacity: 256 MB
Op	ption	QD81MEM-512MBC	CompactFlash card, capacity: 512 MB
		QD81MEM-1GBC	CompactFlash card, capacity: 1 GB
High-speed data lo	ogger	QD81DL96	High-speed data logger module 10BASE-T/100BASE-TX (CompactFlash card is required)
		QD81MEM-512MBC	CompactFlash card, capacity: 512 MB
		QD81MEM-1GBC	CompactFlash card, capacity: 1 GB
Op	ption	QD81MEM-2GBC	CompactFlash card, capacity: 2 GB
		QD81MEM-4GBC	CompactFlash card, capacity: 4 GB
		QD81MEM-8GBC	CompactFlash card, capacity: 8 GB
High-speed data co	ommunication	QJ71DC96	High-speed data communication module 10BASE-T/100BASE-TX (CompactFlash card is required)
		QD81MEM-512MBC	CompactFlash card, capacity: 512 MB
Option		QD81MEM-1GBC	CompactFlash card, capacity: 1 GB
	ption	QD81MEM-2GBC	CompactFlash card, capacity: 2 GB
		QD81MEM-4GBC	CompactFlash card, capacity: 4 GB
		QD81MEM-8GBC	CompactFlash card, capacity: 8 GB



Ту	pe	Model	Outline
Ethernet		QJ71E71-100	10BASE-T/100BASE-TX BACnet® client function, MODBUS® TCP master function (using predefined protocol support function)
	atual Naturauli	QJ71GP21-SX	Multi-mode fiber optic cable, dual loop, control network (control/normal station)
CC-LINK IE CO	CC-Link IE Control Network QJ71GP21S-SX		Multi-mode fiber optic cable, dual loop, control network (control/normal station), with external power supply function
CC-Link IE Fie	ld Network	QJ71GF11-T2	Master/local station, CC-Link IE Field Network compatible
CC-Link		QJ61BT11N	Master/local station, CC-Link Ver. 2 compatible
CC-Link/LT		QJ61CL12	Master station, CC-Link/LT system compatible
AnyWireASLIN	к	QJ51AW12AL DB	Master station, AnyWireASLINK system compatible
		QJ71LP21-25	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote mater station)
	Optical loop (SI)	QJ71LP21S-25	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote mater station), with external power supply function
		QJ72LP25-25	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, remote I/O network (remote I/O station)
MELSECNET/H	Optical loop (GI)	QJ71LP21G	GI-50/125 fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote master station)
		QJ72LP25G	GI-50/125 fiber optic cable, dual loop, remote I/O network (remote I/O station)
	Coaxial	QJ71BR11	3C-2V/5C-2V coaxial cable, single bus, control network (control/normal station) or remote I/O network (remote master station)
	bus	QJ72BR15	3C-2V/5C-2V coaxial cable, single bus, remote I/O network (remote I/O station)
	Twist bus	QJ71NT11B	Twisted pair cable, single bus, control network (control/normal station)
FL-net	Ver. 2.00	QJ71FL71-T-F01	10BASE-T, 100BASE-TX
(OPCN-2)	Ver. 1.00	QJ71FL71-T	10BASE-T
MODDUIOS		QJ71MB91	MODBUS® RTU/ASCII, RS-232, RS-422/485 configurable as master or slave
MODBUS®		QJ71MT91	MODBUS®/TCP 10BASE-T/100BASE-TX configurable as master or slave
AS-i		QJ71AS92	Master station, AS-Interface Specification Version 2.11 compatible
Serial communication		QJ71C24N	RS-232: 1 channel, RS-422/485: 1 channel, total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function)
		QJ71C24N-R2	RS-232: 2 channels, total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function)
		QJ71C24N-R4	RS-422/485: 2 channels, total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function)

# Compatible module for each protocol

Compatible protocol	Compatible modules	Model	Outline
CC-Link IE Field Network Basic	High-speed Universal model QCPU (Built-in Ethernet)	QnUDVCPU	CC-Link IE Eield Network Basic master station function
CC-LINK TE FIEld Network Basic	Universal model process CPU (Built-in Ethernet)	QnUDPVCPU	
	High-speed Universal model (Built-in Ethernet)	QnUDVCPU	SLMP server function (only MC protocol QnA compatible 3E frame)
SLMP (MC protocol)	Universal model QCPU (Built-in Ethernet)	QnUDE(H)CPU	SLMP client function (using predefined protocol support function)
	Ethernet interface module	QJ71E71-100	SLMP server function (including MC protocol) SLMP client function (using predefined protocol support function)
	High-speed Universal model (Built-in Ethernet)	QnUDVCPU	Compatible BACnet <sup>®</sup> object: Analog Input (AI), Binary Input (BI), Binary Output (BO), Accumulator (AC)
	Ethernet interface module	QJ71E71-100	(using predefined protocol support function)
BACnet <sup>®</sup>	BACnet <sup>®</sup> interface module (3rd party products)	BAQ08V	Compatible BACnet <sup>®</sup> object: Analog Input (AI), Analog Output (AO), Analog Value (AV), Binary Input (BI), Binary Output (BO), Binary Value (BV), Multi-state Input (MI), Multi-state Output (MO), Multi-state Value (MV), Accumulator (AC), Calendar (CA), EventEnrolIment (EE), Group Object (GR), Notification Class (NC), Schedule (SC), TrendLog (TL), Device (DV), Measurement object (measure) <sup>*1</sup> , Power demand monitoring (monitor power) <sup>*2</sup> , Power demand control (control power) <sup>*2</sup> , Generator load control (generator) <sup>*2</sup>
MODDUO®EDD	High-speed Universal model (Built-in Ethernet)	QnUDVCPU	MODBUS®/TCP communication master function
MODBUS®/TCP	Ethernet interface module	QJ71E71-100	(using predefined protocol support function)
	MODBUS®/TCP interface module	QJ71MT91	MODBUS®/TCP communication master function/slave function
MODBUS®	Serial communication module	QJ71C24N (-R2/R4)	MODBUS®RTU communication master function (using predefined protocol support function)
	MODBUS <sup>®</sup> interface module	QJ71MB91	MODBUS® RTU/ASCII communication master function/slave function

\*1: ANSI/ASHRAE 2004 and IEIEJ 2006 standards are not supported. \*2: ANSI/ASHRAE 2004 standard is not supported.

84 -

# Replacement support MELSEC-A/AnS/QnA/QnAS transition products

Туре		Model	Outline
	Main base	Q35BL*1	5 slots. Power supply module installation required. For Q Series large input/output module installation
	Main base	Q38BL*1	8 slots. Power supply module installation required. For Q Series large input/output module installation
	<b>-</b>	Q65BL*1	5 slots. Power supply module installation required. For Q Series large input/output module installation
Q Large base	Extension base	Q68BL*1	8 slots. Power supply module installation required. For Q Series large input/output module installation
		Q55BL*1	5 slots. Power supply module installation not required. For Q Series large input/output module installation
	Large blank cover	QG69L*1	For gap adjustment when a previous Q Series module is installed on the Q large base
		Q35BLS	5 slots. Q Series module installation Attaches to board surface
	Main base	Q38BLS	8 slots. Q Series module installation Attaches to board surface
	Wall Dase	Q35BLS-D	5 slots. Q Series module installation Attaches to DIN rail
		Q38BLS-D	8 slots. Q Series module installation Attaches to DIN rail
		Q65BLS	5 slots. Q Series module installation Attaches to board surface
AnS-sized version		Q68BLS	8 slots. Q Series module installation Attaches to board surface
Q Large base	Extension	Q65BLS-D	5 slots. Q Series module installation Attaches to DIN rail
g	base	Q68BLS-D	8 slots. Q Series module installation Attaches to DIN rail
		Q55BLS	5 slots. Q Series module installation Attaches to board surface, power supply module not required
		Q55BLS-D	5 slots. Q Series module installation Attaches to DIN rail, power supply module not required
-	Large blank cover		
		QX11L*1	For replacement of A-Series large type module "AX11". 32 points, 100120 V AC, response time: 25 ms, 32 points/common, 38-point terminal block
	Input	QX21L*1	For replacement of A-Series large type module "AX21". 32 points, 200240 V AC, response time: 25 ms, 32 points/common, 38-point terminal block
	Output	QY11AL*1	For replacement of A-Series large type module "AY10A, AY11A". 16 points, contact, 24 V DC/240 V AC, 2 A/point; 16 A/all points, all-point independent contacts, response time: 12 ms, 38-point terminal block
Q Large I/O		QY13L*1	For replacement of A-Series large type module "AY13". 32 points, contact, 24 V DC/240 V AC, 2 A/point; 5 A/common, 8 points/common, response time: 12 ms, 38-point terminal block
		QY23L*1	For replacement of A-Series large type module "AY23". 32 points, triac, 100240 V AC; 0.6 A/point, 2.4 A/common, 8 points/common, response time: 1 ms + 0.5 cycle, 38-point terminal block
		QY51PL	For replacement of A-Series large type module "AY41, AY41P, AY51, AY51-S1". 32 points, transistor (sink), 12/24 V DC; 0.5 A/point; 4 A/common, 16 points/common, response time: 1 ms, 38-point terminal block
High-speed cou	inter	QD62-H01*2	For replacement of A-Series large type module "AD61". 2 channels, 50 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sync), 12/24 V DC, 0.5 A/point; 2 A/common
ngn-speed cot	antei	QD62-H02*2	For replacement of A-Series large type module "AD61-S1". 2 channels, 10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sync), 12/24 V DC, 0.5 A/point; 2 A/common
Positioning		QD73A1	For replacement of "A1SD70". 1 axis. Number of positioning data items: 1 data/axis, analog output
		QA1S51B*3	1 slot. Does not require installation of AnS Series power supply module. For AnS Series module installation
	AnS Series	QA1S65B*3	5 slots. Requires AnS Series power supply module installation. For AnS Series module installation
Extension ase		QA1S68B*3	8 slots. Requires AnS Series power supply module installation. For AnS Series module installation
		QA65B*3	5 slots. Requires A Series power supply module installation. For A Series module installation
	A Series	QA68B*3	8 slots. Requires A Series power supply module installation. For A Series module installation
		QA1S6ADP	Conversion adapter to connect an AnS/QnAS Series extension base unit to the Q Series system
Q-AnS base un adapter	it conversion	QA1S6ADP-S1	Conversion adapter to connect an AnS/QnAS Series extension base unit to the Q Series system (for up to 3 extension base units)
	onversion		

\*1: Only supported only by High Performance QCPU and Universal QCPU (Excluding Q00UJCPU). \*2: A connector is not provided. Please order one of the following separately: A6CON1/A6CON2/A6CON3/A6CON4 \*3: Only supported only by High Performance model QCPU.



Ту	pe	Model	Outline
		Q80BD-J71GP21-SX	PCI bus/PCI-X bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station)
CC Link IE Co		Q81BD-J71GP21-SX	PCI Express bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station)
		Q80BD-J71GP21S-SX	PCI bus/PCI-X bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station), with external power supply function
		Q81BD-J71GP21S-SX	PCI Express bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station), with external power supply function
CC-Link IE Fie	CC-Link IE Field Network Q81BD-J71GF11-T2*1		PCI Express compatible, Ethernet connections in line, star, or line and star mixed, configurable as master or local station.
		Q81BD-J71LP21-25	PCI Express bus, Japanese/English OS compatible, SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station)
	Optical loop (SI)	Q80BD-J71LP21-25	PCI bus, Japanese/English OS compatible, SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station)
MELSECNET/H(10)		Q80BD-J71LP21S-25	PCI bus, Japanese/English OS compatible, SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station), with external power supply function
	Optical loop (GI)	Q80BD-J71LP21G	PCI bus, Japanese/English OS compatible, GI-50/125 fiber optic cable, dual loop, control network (control/normal station)
	Coaxial bus	Q80BD-J71BR11	PCI bus, Japanese/English OS compatible, 3C-2V/5C-2V coaxial cable, single bus, control network (control/normal station)
CC-Link		Q81BD-J61BT11	PCI Express bus, Japanese/English OS compatible, master/local interface board, CC-Link Ver. 2 compatible
CO-LINK		Q80BD-J61BT11N	PCI bus, Japanese/English OS compatible, master/local interface board, CC-Link Ver. 2 compatible

\*1: Does not support being used as the master station in a ring network.

# Ethernet related products

Wireless LAN Adapter	U.S.A.	NZ2WL-US*2*3 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards, to be discontinued (September 2018)
	China	NZ2WL-CN*2*3 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards, to be discontinued (September 2018)
	Korea	NZ2WL-KR*2*3 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards, to be discontinued (September 2018)
	Taiwan	NZ2WL-TW*2*3 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards, to be discontinued (September 2018)
Industrial switching HUB		NZ2EHG-T8N DB	10 Mbps/100 Mbps/1 Gbps AUTO MDI/MDI-X, DIN rail supported, 8 ports
industrial switc	ліпд нов	NZ2EHF-T8 DB	10 Mbps/100 Mbps AUTO MDI/MDI-X, DIN rail supported, 8 ports, to be discontinued (October 2018)
Intelligent HUB		NZ2MHG-T8F2	10 Mbps/100 Mbps/1 Gbps DIN rail mountable, 8 ports (2 ports support optical fiber cable), CC-Link IE and Ethernet devices are connectable, ERP- and LA- style topologies, VLAN and SNMP are supported
CC-Link IE Field Network Ethernet Adapter		NZ2GF-ETB	100 Mbps/1 Gbps compatible station for expanding CC-Link IE Field Networks

\*2: Each product is usable only in the respective country.\*3: Both access points and stations are supported, and can be switched with the settings.

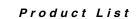
»For details on the software versions compatible with each module, refer to the manual for each product. Please contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

#### Software MELSOFT GX Series

\* Refer to the "Compatible CPUs" table for individual model names Compatible CPU\* Universal model High Basic Model QnUDV QnU QnUD(E) Performance Controller Programming Software: MELSOFT GX Works3\* MELSOFT Supported by GX Works2 or GX Developer or SW1DND-GXW3-F MITSUBISHI ELECTRIC FA Library Comes with GX Works2, GX Developer and PX Developer\*2 GX Works3 PX Developer (both come with GX Works3) Controller Programming Software Comes with GX Developer MELSOFT SW1DNC-GXW2-E • • • • • • • GX Works2 SW8D5C-GPPW-E MELSEC programmable controller programming software • ٠ • • . • MELSOFT GX Developer SW8D5C-GPPW-EV MELSEC programmable controller programming software (upgrade) • •\*3 . . . • SW7D5C-LLT-E MELSEC programmable controller simulation software • ●\*<sup>3</sup> • • • • MELSOFT GX Simulator\*4 SW7D5C-LLT-EV MELSEC programmable controller simulation software (upgrade) • •\*3 • • • • MELSOFT GX Converter\*4 SW0D5C-CNVW-E Excel®/text data converter . • . . MELSOFT SW2D5C-QADU-E Analog to digital conversion module setting/monitoring tool • •\*3 • • • \_ . GX Configurator-AD\*4 MELSOFT SW2D5C-QDAU-E • Digital to analog conversion module setting/monitoring tool •\*3 • \_ • • • GX Configurator-DA\*4 MELSOFT MELSEC-Q dedicated serial communication module setting/monitoring SW2D5C-OSCU-F \_ • •\*3 • • • • GX Configurator-SC\*4 tool MELSOFT SW0D5C-QCTU-E MELSEC-Q dedicated high-speed counter module setting/monitoring tool ●\*<sup>3</sup> • • \_\_\_\_\_ . • • GX Configurator-CT\*4 MELSOFT SW0D5C-QTCU-E MELSEC-Q dedicated temperature control module setting/monitoring tool • •\*3 • • • • GX Configurator-TC\*4 MELSOFT SW1D5C-QTIU-E ●\*<sup>3</sup> MELSEC-Q dedicated temperature input module setting/monitoring tool . . • • . GX Configurator-TI\*4 MELSOFT SW0D5C-QFLU-E MELSEC-Q dedicated FL-net module setting/monitoring tool •\*3 • ٠ \_ • • • GX Configurator-FL\*4 MELSOFT SW1D5C-QPTU-E MELSEC-Q dedicated positioning module QD70 setting/monitoring tool \_ . •\*3 . • . • GX Configurator-PT\*4 MELSOFT SW1D5C-OMBU-F MODBUS master module setting/monitoring tool \_ . •\*3 . . • • GX Configurator-MB\*4 MELSOFT SW1D5C-QASU-E AS-i master module setting/monitoring tool \_ • •\*3 • • • • GX Configurator-AS\*4 MELSOFT SW2D5C-QD75P-E Positioning module QD75P/D/M setting/monitoring tool \_ • ●\*<sup>3</sup> • • • • GX Configurator-QP MELSOFT SW2D5C-EXP-E Maintenance tool \_ • • •\*5 GX Explorer MELSOFT SW2D5C-RAS-E Remote access tool •\*5 • • \_\_\_\_ GX RemoteService- I Set type products (7 in total): GX Developer, GX Simulator, GX Explorer, SW4D5C-QSET-E \*6 MELSOFT GX Configurator-AD, DA, SC, CT GX Works \*6 SW8D5C-GPPLLT-E GX Developer, GX Simulator, GX Explorer

11: The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese. 22: Includes both programming tool and monitor tool for process control. 33: Not compatible with Q50UDEHCPU, Q100UDEHCPU, and QJ71GF11-T2. 44: This operates as add-in software for GX Developer. GX Developer is required separately. 45: Not compatible with Q02PHCPU and Q06PHCPU.

\*6: To determine which CPUs are supported, refer to the individual products above.



# Software MELSOFT PX Series

#### \* Refer to the "Compatible CPUs" table for individual model names.

			Compatible CPU*						
Туре	Model	Outline	Uni	versal m	odel	High		Process	Redundant
			QnUDV	QnU	QnUD(E)	model	model	CPU	CPU
MELSOFT PX Developer	SW1D5C-FBDQ-E	Process control FBD software package	—	—	-	_	—	•	•
	SW1DNC-FBDQMON-E	Process control FBD software package monitoring tool	—	—	-	_	—	•	•
MELSOFT PX Works		Set type products (6 in total): PX Developer, GX Developer, GX Configurator-AD, DA, CT, TI				*1			

\*1: To determine which CPUs are supported, refer to the individual products.

# Software MELSOFT MX Series

MELSOFT MX Component	SW4DNC-ACT-E	ActiveX® library for communication	٠	•	•	•	•	•	•
MELSOFT MX Sheet	SW2DNC-SHEET-E*2	Excel® communication support tool	•	•	•	•	•	•	•
MELSOFT MX Works	SW2DNC-SHEETSET-E	A set of two products: MX Component, MX Sheet				*3			
MELSOFT MX Component for iOS/Android™	SW1DNC-ACTAND-B	Library for communication (for Android application development) (Japanese/English version)	•	•	•	•	•	•	•
	SW1MIC-ACTIOS-B	Library for communication (for iOS application development) (Japanese/English version)	٠	•	•	•	٠	•	•
MELSOFT MX MESInterface	SW1DNC-MESIF-E	MES interface module QJ71MES96(N) dedicated information linkage tool				*4			

\*2: To use MX Sheet, MX Component is required.
\*3: To determine which CPUs are supported, refer to the individual products.
\*4: Required when using the MES interface module.

# Software MELSOFT iQ Works

MELSOFT iQ Works S	SW2DND-IQWK-E	FA engineering software <sup>+5</sup> • System Management Software: MELSOFT Navigator • Controller Programming Software: MELSOFT GX Works3 <sup>+6</sup> , GX Works2, GX Developer • Motion Programming Software: MELSOFT MT Works2 • HMI Programming Software: MELSOFT GT Works3 • Robot Programming Software: MELSOFT RT ToolBox3 <sup>+7</sup> • Inverter Setup Software: MELSOFT FR Configurator2 • Servo setup software: MELSOFT MR Configurator2 • C Controller setting and monitoring tool: MELSOFT CW Configurator • MITSUBISHI ELECTRIC FA Library
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\*5: For detailed information about supported modules, refer to the manuals of the relevant software package.
 \*6: The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese.
 \*7: RT ToolBox3 mini (simplified version) will be installed if iQ Works product ID is used. When RT ToolBox3 (with simulation function) is required, please purchase RT ToolBox3 product ID.

# **Compatible CPUs**

Item		Modei		
	QnUDV	Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV		
QCPU	QnU	Q00UJ, Q00U, Q01U, Q02U		
	QnUD(E)	Q03UD(E), Q04UD(E)H, Q06UD(E)H, Q10UD(E)H, Q13UD(E)H, Q20UD(E)H, Q26UD(E)H, Q50UDEH, Q100UDEH		
High Performance m	odel QCPU	Q02, Q02H, Q06H, Q12H, Q25H		
Basic model QCPU		Q00J, Q00, Q01		
Process CPU		Q02PH, Q06PH, Q12PH, Q25PH		
Redundant CPU		Q12PRH, Q25PRH		

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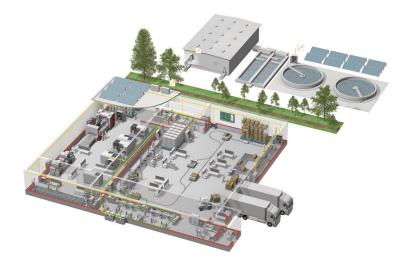
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Mitsubishi Electric Corporation Nagoya Works is a factory certified for ISO 14001 (standards for environmental management systems) and ISO 9001 (standards for quality assurance management systems).

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